# CS6013 - Modern Compilers: Theory and Practise Semantic Analysis

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# Semantic Processing

The compilation process is driven by the syntactic structure of the program as discovered by the parser

#### Semantic routines:

- interpret meaning of the program based on its syntactic structure
- two purposes:
  - finish analysis by deriving context-sensitive information (e.g. type checking)
  - begin synthesis by generating the IR or target code
- associated with individual productions of a context free grammar or subtrees of a syntax tree



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# Alternatives for semantic processing

- one-pass analysis and synthesis
- one-pass compiler plus peephole
- one-pass analysis & IR synthesis + code generation pass
- multipass analysis

(e.g. gcc)

multipass synthesis

(e.g. gcc)

• language-independent and retargetable (e.g. gcc) compilers

Our focus in the assignment: One-pass analysis & IR synthesis + multipass analysis + multipass synthesis.





# Type checking

- We need generate type information.
  - For fields, variables, expressions, functions.
- Need to enforce types:
  - Assignments, function calls, expressions.
- We need to remember the type information and recall them as/where required – symbol table.



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# Symbol table information

What kind of information might the compiler need?

- textual name
- data type
- dimension information

(for aggregates)

- declaring procedure
- lexical level of declaration
- storage class

(base address)

- offset in storage
- if record, pointer to structure table
- if parameter, by-reference or by-value?
- can it be aliased? to what other names?
- number and type of arguments to functions



# Symbol tables

For compile-time efficiency, compilers use a symbol table:

associates lexical names (symbols) with their attributes

What items should be entered?

- variable names
- defined constants
- procedure and function names
- literal constants and strings
- source text labels
- compiler-generated temporaries

(we'll get there)

A symbol table is a compile-time structure

Separate table for structure layouts (types) (includes field offsets and lengths)

May need to preserve list of locals for the debugger

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# Storage classes of variables

During code generation, each variable is assigned an address (addressing method), approrpriate to its storage class.

- A local variable is not assigned a fixed machine address (or relative to the base of a module) - rather a stack location that is accessed by an offest from a register whose value does not point to the same location, each time the procedure is invoked. Why is it interesting?
- Four major storage classes: global, stack, stack static, registers



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# Symbol table organization

How should the table be organized?

- Linear List
  - **O**(n) probes per lookup
  - easy to expand no fixed size
  - one allocation per insertion
- Ordered Linear List
  - $O(\log_2 n)$  probes per lookup using binary search
  - insertion is expensive (to reorganize list)
- Binary Tree
  - O(n) probes per lookup unbalanced
  - O(log₂ n) probes per lookup balanced
  - easy to expand no fixed size
  - one allocation per insertion
- Hash Table
  - O(1) probes per lookup on average
  - expansion costs vary with specific scheme



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# Nested scopes: complications

Fields and records:

give each record type its own symbol table

or assign record numbers to qualify field names in table

#### with R do \( stmt \):

- all IDs in \( stmt \) are treated first as R.id
- separate record tables: chain R's scope ahead of outer scopes
- record numbers:

open new scope, copy entries with R's record number or chain record numbers: search using these first



# Nested scopes: block-structured symbol tables

What information is needed?

- when asking about a name, want most recent declaration
- declaration may be from current scope or outer scope
- innermost scope overrides outer scope declarations

Key point: new declarations occur only in current scope What operations do we need?

- void put (Symbol key, Object value) bind key to value
- Object get(Symbol key) return value bound to key
- void beginScope() remember current state of table
- void endScope()
   close current scope and restore table to state at most recent open beginScope

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# Nested scopes: complications (cont.)

Implicit declarations:

- labels: declare and define name (in Pascal accessible only within enclosing scope)
- Ada/Modula-3/Tiger FOR loop: loop index has type of range specifier

Overloading:

• link alternatives (check no clashes), choose based on context

Forward references:

ullet bind symbol only after all possible definitions  $\Rightarrow$  multiple passes Other complications:

packages, modules, interfaces - IMPORT, EXPORT



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### Attribute information

Attributes are internal representation of declarations Symbol table associates names with attributes Names may have different attributes depending on their meaning:

- variables: type, procedure level, frame offset
- types: type descriptor, data size/alignment
- constants: type, value
- procedures: formals (names/types), result type, block information (local decls.), frame size



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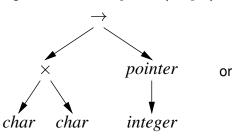
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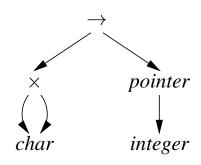
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# Type descriptors

Type descriptors are compile-time structures representing type expressions

e.g.,  $char \times char \rightarrow pointer(integer)$ 



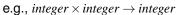




### Type expressions

Type expressions are a textual representation for types:

- basic types: boolean, char, integer, real, etc.
- 2 type names
- onstructed types (constructors applied to type expressions):
  - array(I,T) denotes an array of T indexed over I e.g., array(1...10, integer)
  - 2 products:  $T_1 \times T_2$  denotes Cartesian product of type expressions  $T_1$  and  $T_2$
  - records: fields have names e.g.,  $record((a \times integer), (b \times real))$
  - **4** pointers: pointer(T) denotes the type "pointer to an object of type T"





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# Type compatibility

Type checking needs to determine type equivalence Two approaches:

Name equivalence: each type name is a distinct type Structural equivalence: two types are equivalent iff. they have the same structure (after substituting type expressions for type names)

- $s \equiv t$  iff. s and t are the same basic types
- $array(s_1, s_2) \equiv array(t_1, t_2)$  iff.  $s_1 \equiv t_1$  and  $s_2 \equiv t_2$
- $s_1 \times s_2 \equiv t_1 \times t_2$  iff.  $s_1 \equiv t_1$  and  $s_2 \equiv t_2$
- $pointer(s) \equiv pointer(t)$  iff.  $s \equiv t$
- $s_1 \rightarrow s_2 \equiv t_1 \rightarrow t_2$  iff.  $s_1 \equiv t_1$  and  $s_2 \equiv t_2$



# Type compatibility: example

Consider:

```
type link = \footnotell;
var next : link;
    last : link;
    p : \footnotell;
    q, r : \footnotell;
```

Under name equivalence:

- next and last have the same type
- p, q and r have the same type
- p and next have different type

Under structural equivalence all variables have the same type Ada/Pascal/Modula-2/Tiger are somewhat confusing: they treat distinct type definitions as distinct types, so p has different type from q and r



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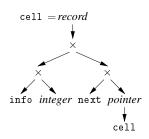
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# Type compatibility: recursive types

Consider:

We may want to eliminate the names from the type graph Eliminating name link from type graph for record:

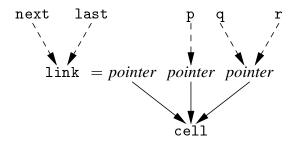




# Type compatibility: Pascal name equivalence

Build compile-time structure called a type graph:

- each constructor or basic type creates a node
- each name creates a leaf (associated with the type's descriptor)



Type expressions are equivalent if they are represented by the same node in the graph

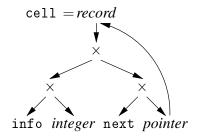
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# Type compatibility: recursive types

Allowing cycles in the type graph eliminates cell:





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# Food for thought - fun assignment

Write a Type Checker for MiniJava expressions.

#### Considerations:

- Overloaded addition operation.
- Assignment op.
- Function calls.
- Inheritance.



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# Intermediate representations

#### Why use an intermediate representation?

- break the compiler into manageable pieces
  - good software engineering technique
- simplifies retargeting to new host
  - isolates back end from front end
- 3 simplifies handling of "poly-architecture" problem
  - -m lang's, n targets  $\Rightarrow m+n$  components

enables machine-independent optimization

- general techniques, multiple passes

An intermediate representation is a compile-time data structure



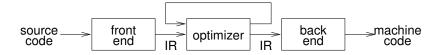
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# Intermediate representations



### Generally speaking:

- front end produces IR
- optimizer transforms that representation into an equivalent program that may run more efficiently
- back end transforms IR into native code for the target machine

# Intermediate representations

### Representations talked about in the literature include:

- abstract syntax trees (AST)
- linear (operator) form of tree
- directed acyclic graphs (DAG)
- control flow graphs
- program dependence graphs
- static single assignment form
- 3-address code
- hybrid combinations





### Intermediate representations - properties

#### Important IR Properties

- ease of generation
- ease of manipulation
- cost of manipulation
- level of abstraction
- freedom of expression
- size of typical procedure

Subtle design decisions in the IR have far reaching effects on the speed and effectiveness of the compiler.

Level of exposed detail is a crucial consideration.



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# Intermediate representations

Broadly speaking, IRs fall into three categories:

- Structural
  - structural IRs are graphically oriented
  - examples include trees, DAGs
  - heavily used in source to source translators
  - nodes, edges tend to be large
- Linear
  - pseudo-code for some abstract machine
  - large variation in level of abstraction
  - simple, compact data structures
  - easier to rearrange
- Hybrids
  - combination of graphs and linear code
  - attempt to take best of each
  - e.g., control-flow graphs
  - Example: GCC Tree IR.



# IR design issues

- Is the chosen IR appropriate for the (analysis/ optimization/ transformation) passes under consideration?
- What is the IR level: close to language/machine.
- Multiple IRs in a compiler: for example, High, Medium and Low

```
t1 \leftarrow a[i,j+2]
                                     t1 \leftarrow j + 2
                                                                        r1 \leftarrow [fp-4]
                                     t2 \leftarrow i * 20
                                                                        r2 \leftarrow r1 + 2
                                     t3 \leftarrow t1 + t2
                                                                        r3 \leftarrow [fp-8]
                                     t4 \leftarrow 4 * t3
                                                                        r4 \leftarrow r3 * 20
                                     t5 ← addr a
                                                                         r5 \leftarrow r4 + r2
                                     t6 \leftarrow t5 + t4
                                                                        r6 \leftarrow 4 * r5
                                                                         r7 \leftarrow fp - 216
                                                                        f1 \leftarrow [r7+r6]
(a)
```

- (a) High-, (b) medium-, and (c) low-level representations of a C array reference.
- In reality, the variables etc are also only pointers to other data structures.



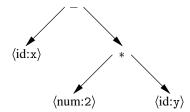
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### Abstract syntax tree

An abstract syntax tree (AST) is the procedure's parse tree with the nodes for most non-terminal symbols removed.



This represents "x - 2 \* y".

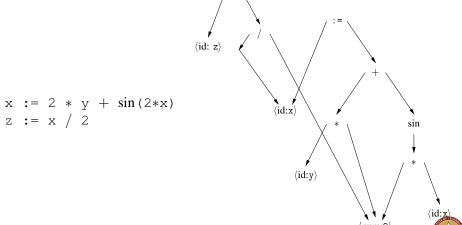
For ease of manipulation, can use a linearized (operator) form of the tree.

e.g., in postfix form: x = 2 y \* -



# Directed acyclic graph

A directed acyclic graph (DAG) is an AST with a unique node for each value.



Q: What to do for matching names present across different function

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z := x / 2

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# 3-address code

- At most one operator on the right side of an instruction.
- 3-address code can mean a variety of representations.
- In general, it allow statements of the form:

$$x \leftarrow y \underline{op} z$$

with a single operator and, at most, three names. Simpler form of expression:

becomes

$$t1 \leftarrow 2 * y$$

$$t2 \leftarrow x - t1$$

#### Advantages

- compact form (direct naming)
- names for intermediate values

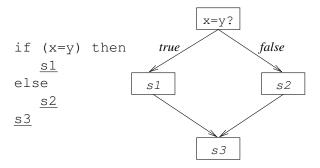
Can include forms of prefix or postfix code



# Control flow graph

The control flow graph (CFG) models the transfers of control in the procedure

- nodes in the graph are basic blocks straight-line blocks of code
- edges in the graph represent control flow loops, if-then-else, case, goto





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# 3-address code: Addresses

Three-address code is built from two concepts: addresses and instructions.

- An address can be
  - A name: source variable program name or pointer to the Symbol Table name.
  - A constant: Constants in the program.
  - Compiler generated temporary:



# 3-address code

Typical instructions types include:

lacktriangledown assignments x  $\leftarrow$  y op z

② assignments x ← op y

assignments x ← y[i]

 $\bullet$  assignments  $x \leftarrow y$ 

**6** branches goto L

• conditional branches if x goto L

procedure calls

param  $x_1$ , param  $x_2$ , ... param  $x_n$  and call p, n

address and pointer assignments



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How to translate:

S2

?

if (x < y) S1 else

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# 3-address code - implementation

### Quadruples

- Has four fields: op, arg1, arg2 and result.
- Some instructions (e.g. unary minus) do not use arg2.
- ullet For copy statement : the operator itself is  $\underline{=}$ ; for others it is implied.
- Instructions like param don't use neither arg2 nor result.
- Jumps put the target label in result.

x - 2 * y						
ор	arg1	arg2	result			
load	t1	у				
loadi	t2	2				
mult	t3	t2	t1			
load	t4	х				
sub	t5	t4	t3			
	op load loadi mult load	op arg1 load t1 loadi t2 mult t3 load t4	op         arg1         arg2           load         t1         y           loadi         t2         2           mult         t3         t2			

- simple record structure with four fields
- easy to reorder
- explicit names
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# 3-address code - implementation

### Triples

	x - 2	* У	
(1)	load	у	
(2)	loadi	2	
(3)	mult	(1)	(2)
(4)	load	Х	
(5)	sub	(4)	(3)

- use table index as implicit name
- require only three fields in record
- harder to reorder

# 3-address code - implementation

### **Indirect Triples**

	exec-order	stmt	ор	arg1	arg2
(1)	(100)	(100)	load	у	
(2)	(101)	(101)	loadi	2	
(3)	(102)	(102)	mult	(100)	(101)
(4)	(103)	(103)	load	x	
(5)	(104)	(104)	sub	(103)	(102)

- simplifies moving statements (change the execution order)
- more space than triples
- implicit name space management





### Indirect triples advantage

for i:=1	to	10	do
begin			
a=b*c			
d=i*3			
end			
(a)			

#### Optimized version

```
(1) := 1 i

(2) * b c

(3) := (2) a

(4) * 3 i

(5) := (4) d

(6) + 1 i

(7) LE I 10

(8) IFT go (2)
```

Execution Order (a): 12345678 Execution Order (b): 23145678 Note: No need to change the operands. Labels still need changing.



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# Other hybrids

An attempt to get the best of both worlds.

- graphs where they work
- linear codes where it pays off

Unfortunately, there appears to be little agreement about where to use each kind of IR to best advantage.

#### For example:

- PCC and FORTRAN 77 directly emit assembly code for control flow, but build and pass around expression trees for expressions.
- Many people have tried using a control flow graph with low-level, three address code for each basic block.



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# Intermediate representations

# But, this isn't the whole story

### Symbol table:

- identifiers, procedures
- size, type, location
- lexical nesting depth

#### Constant table:

- representation, type
- storage class, offset(s)

#### Storage map:

- storage layout
- overlap information
- (virtual) register assignments

# **Advice**

- Many kinds of IR are used in practice.
- There is no widespread agreement on this subject.
- A compiler may need several different IRs
- Choose IR with right level of detail
- Keep manipulation costs in mind





# Opening remarks

What have we done so far?

- Compiler overview.
- Scanning and parsing.
- JavaCC, visitors and JTB
- Semantic Analysis specification, execution, attribute grammars.
- Type checking, Intermediate Representation.

Announcement:

Assignment 2. Seven days to go.

Today:

• Intermediate code generation.



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# Translating expressions

$$S \rightarrow \mathbf{id} = E$$
; {  $gen(top.get(\mathbf{id}.lexeme) '=' E.addr)$ ; }   
  $E \rightarrow E_1 + E_2$  {  $E.addr = \mathbf{new} \ Temp()$ ;  $gen(E.addr '=' E_1.addr '+' E_2.addr)$ ; }   
  $| -E_1$  {  $E.addr = \mathbf{new} \ Temp()$ ;  $gen(E.addr '=' '\mathbf{minus'} \ E_1.addr)$ ; }   
  $| (E_1)$  {  $E.addr = E_1.addr$ ; }   
  $| \mathbf{id}$  {  $E.addr = top.get(\mathbf{id}.lexeme)$ ; }

- Builds the three-address code for an assignment statement.
- addr is an synthetic-attribute of *E*.
  - denotes the address that will hold the value of E.
- Constructs a three-address instruction and appends the instruction to the sequence of instructions.
- top is the top-most (current) symbol table.

Gap between HLL and IR

- High level languages may allow complexities that are not allowed in IR (such as expressions with multiple operators).
- High level languages have many syntactic constructs, not present in the IR (such as if-then-else or loops)

Challenges in translation:

- Deep nesting of constructs.
- Recursive grammars.
- We need a systematic approach to IR generation.

Goal:

- A HLL to IR translator.
- Input: A program in HLL.
- Output: A program in IR (may be an AST or program text)



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# Array elements dereference (Recall)

- Elements are typically stored in a block of consecutive locations.
- If the width of each array element is w, then the  $i^{th}$  element of array A (say, starting at the address base), begins at the location:  $base + i \times w$ .
- For multi-dimensions, beginning address of  $A[i_1][i_2]$  is calculated by the formula:

 $base + i_1 \times w_1 + i_2 \times w_2$ 

where,  $w_1$  is the width of the row, and  $w_2$  is the width of one element.

• We declare arrays by the number of elements ( $n_j$  is the size of the  $j^{th}$  dimension) and the width of each element in an array is fixed (say w).

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The location for  $A[i_1][i_2]$  is given by  $base + (i_1 \times n_2 + i_2) \times w$ 

- Q: If the array index does not start at '0', then ?
- Q: What if the data is stored in column-major form?



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# Translation of Array references

• Extending the expression grammar with arrays:

$$S 
ightarrow \mathbf{id} = E$$
;  
 $\mid L = E$ ;  
 $E 
ightarrow E_1 + E_2$   
 $\mid \mathbf{id}$   
 $\mid L_1 \ [E]$ 

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 $\boldsymbol{L}$ 

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### Translation of Array references (contd)

```
L \rightarrow \mathbf{id} \ [ \ E \ ] \quad \{ \ L.array = top.get(\mathbf{id}.lexeme); \\ L.type = L.array.type.elem; \\ L.addr = \mathbf{new} \ Temp \, (); \\ gen(L.addr'=' E.addr'*' L.type.width); \, \}
\mid \ L_1 \ [ \ E \ ] \quad \{ \ L.array = L_1.array; \\ L.type = L_1.type.elem; \\ t = \mathbf{new} \ Temp \, (); \\ L.addr = \mathbf{new} \ Temp \, (); \\ gen(t'=' E.addr'*' L.type.width); \, \}
gen(L.addr'=' L_1.addr'+' t); \, \}
```

- 3 L.type is the type of the subarray generated by L.
  - For any type t: t.width gives get the width of the type.
  - For any type *t*: *t.elem* gives the element type.



# Translation of Array references (contd)

```
\begin{array}{lll} S \ \rightarrow \ \mathbf{id} = E \ ; & \left\{ \ gen(\ top.get(\mathbf{id}.lexeme) \ '=' \ E.addr); \ \right\} \\ & \mid \ L = E \ ; & \left\{ \ gen(L.addr.base'['\ L.addr']' \ '=' \ E.addr); \ \right\} \\ E \ \rightarrow \ E_1 + E_2 & \left\{ \ E.addr = \ \mathbf{new} \ Temp\left(\right); \\ gen(E.addr'=' \ E_1.addr'+' \ E_2.addr); \ \right\} \\ & \mid \ \mathbf{id} & \left\{ \ E.addr = \ \mathbf{new} \ Temp\left(\right); \\ gen(E.addr'=' \ L.array.base'['\ L.addr']'); \ \right\} \end{array}
```

Nonterminal *L* has three synthesized attributes

- 1 *L.addr* denotes a temporary that is used while computing the offset for the array reference.
- 2 *L.array* is a pointer to the ST entry for the array name. The field *barray* gives the actual I-value of the array reference.

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### Translation of Array references (contd)

#### Example:

- Let a denotes a  $2 \times 3$  integer array.
- Type of a is given by array(2, array(3, integer))
- Width of a = 24 (size of *integer* = 4).
- Type of a[i] is array(3, integer), width = 12.
- Type of a[i][j] = integer

#### Exercise:

• Write three adddress code for c + a[i][j]

$$t_1 = i * 12$$
 $t_2 = j * 4$ 
 $t_3 = t_1 + t_2$ 
 $t_4 = a [t_3]$ 
 $t_5 = c + t_4$ 

Q: What if we did not know the size of integer (machine dependent)

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# IR generation for flow-of-control statements

```
P \rightarrow S
                                S.next = newlabel()
                                P.code = S.code \mid\mid label(S.next)
S \rightarrow \mathbf{assign}
                                S.code = assign.code
S \rightarrow \mathbf{if} (B) S_1
                                B.true = newlabel()
                                B.false = S_1.next = S.next
                                S.code = B.code || label(B.true) || S_1.code
S \rightarrow \mathbf{if} (B) S_1 \mathbf{else} S_2
                                B.true = newlabel()
                                B.false = newlabel()
                                S_1.next = S_2.next = S.next
                                S.code = B.code
                                              || label(B.true) || S_1.code
                                              || gen('goto' S.next)
                                             || label(B.false) || S_2.code
```

- code is an synthetic attribute: giving the code for that node.
- Assume: *gen* only creates an instruction.
- || concatenates the code.



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# IR generation for boolean expressions

```
B \rightarrow B_1 \mid \mid B_2
                        B_1.true = B.true
                         B_1.false = newlabel()
                         B_2.true = B.true
                         B_2.false = B.false
                         B.code = B_1.code \mid\mid label(B_1.false) \mid\mid B_2.code
B \rightarrow B_1 \&\& B_2
                        B_1.true = newlabel()
                         B_1.false = B.false
                         B_2.true = B.true
                         B_2.false = B.false
                        B.code = B_1.code \mid | label(B_1.true) \mid | B_2.code
B \rightarrow ! B_1
                         B_1.true = B.false
                         B_1.false = B.true
                        B.code = B_1.code
B \rightarrow E_1 \operatorname{rel} E_2
                        B.code = E_1.code \mid\mid E_2.code
                              || gen('if' E<sub>1</sub>.addr rel.op E<sub>2</sub>.addr 'goto' B.true)
                              || gen('goto' B.false)
B \rightarrow \mathbf{true}
                        B.code = gen('goto' B.true)
                        B.code = gen('goto' B.false)
B \rightarrow false
```



### IR generation for flow-of-control statements

```
S 	o 	ext{while } (B) S_1
\begin{array}{c} begin = newlabel() \\ B.true = newlabel() \\ B.false = S.next \\ S_1.next = begin \\ S.code = label(begin) || B.code \\ || label(B.true) || S_1.code \\ || gen('goto' begin) \\ S 	o S_1 S_2 \\ S_2.next = newlabel() \\ S_2.next = S.next \\ S.code = S_1.code || label(S_1.next) || S_2.code \\ \end{array}
```

- *code* is an synthetic attribute: giving the code for that node.
- Assume: *gen* only creates an instruction.
- || concatenates the code.



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# Some challenges/questions

- Avoiding redundant gotos. ??
- Multiple passes. ??
- How to translate implicit branches: break and continue?
- How to translate switch statements efficiently?
- How to translate procedure code?



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# Closing remarks

What have we done today?

• Intermediate Code Generation.

To read

• Dragon Book. Sections 6.4, 6.5, 6.6, 6.7, 6.8, 6.9 and 2.8



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