

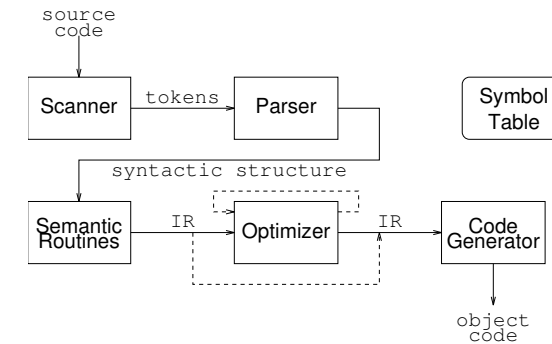
# CS6013 - Modern Compilers: Theory and Practise

## Control flow analysis

V. Krishna Nandivada

IIT Madras

# Control flow analysis



- Code optimization requires that the compiler has a global “understanding” of how programs use the available resources.
- It has to understand how the control flows (control-flow analysis) in the program and how the data is manipulated (data-flow analysis)
- Control-flow analysis: flow of control within each procedure.
- Data-flow analysis: how the data is manipulated in the program.



## Example

```

unsigned int fib(m)
{
  unsigned int m;
  unsigned int f0 = 0, f1 = 1, f2, i;
  if (m <= 1) {
    return m;
  }
  else {
    for (i = 2; i <= m; i++) {
      f2 = f0 + f1;
      f0 = f1;
      f1 = f2;
    }
    return f2;
  }
}
  
```

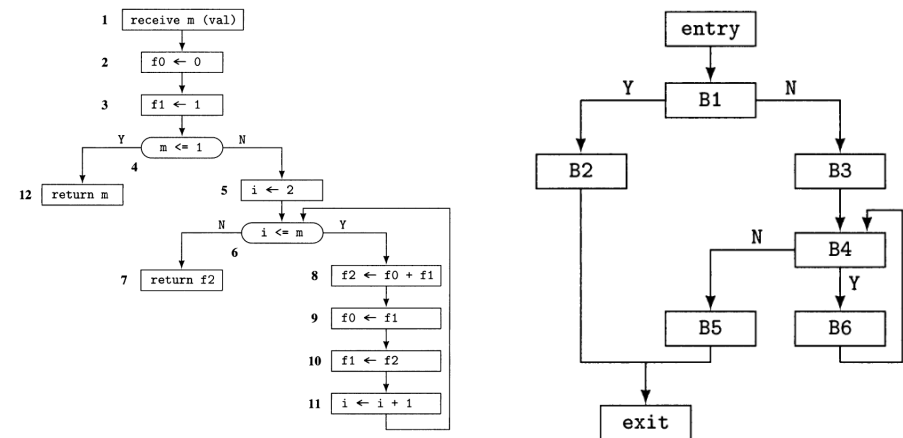
```

1  receive m (val)
2  f0 ← 0
3  f1 ← 1
4  if m <= 1 goto L3
5  i ← 2
6  L1: if i <= m goto L2
7  return f2
8  L2: f2 ← f0 + f1
9  f0 ← f1
10 f1 ← f2
11 i ← i + 1
12 goto L1
13 L3: return m
  
```

- IR for the C code (in a format described in Muchnick book)
- `receive` specifies the reception of a parameter and the parameter-passing discipline (by-value, by-result, value-result, reference). Why do we want to have an explicit receive instruction?— Gives a point of definition for the args.
- What is the control structure? Obvious?



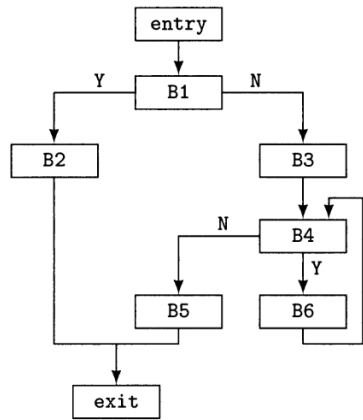
## Example - flow chart and control-flow



- The high-level abstractions might be lost in the IR.
- Control-flow analysis can expose control structures not obvious in the high level code. Possible? Loops constructed from `if` and `goto`
- A basic block is informally a straight-line sequence of code that can be entered only at the beginning and exited only at the end.



## Basic blocks - what do we get?



- `entry` and `exit` are added for reasons to be explained later.
- We can identify loops by using dominators
  - a node  $A$  in the flowgraph dominates a node  $B$  if every path from `entry` node to  $B$  includes  $A$ .
  - This relations is antisymmetric, reflexive, and transitive.
- back edge: An edge in the flow graph, whose head dominates its tail (example - edge from  $B6$  to  $B4$ ).
- A loop consists of subset of nodes dominated by its entry node (head of the back edge) and having exactly one back edge in it.



## Deep dive - Basic block

### Basic block definition

- A **basic block** is a maximal sequence of instructions that can be entered only at the first of them
- The basic block can be exited only from the last of the instructions of the basic block.
- Implication: First instruction can be a) entry point of a routine, b) item target of a branch, c) item instruction following a branch or a return.
- First instruction is called the leader of the BB.

### How to construct the basic block?

- Identify all the leaders in the program.
- For each leader: include in its basic block all the instructions from the leader to the next leader (next leader not included) or the end of the routine, in sequence.

### What about function calls?

- In most cases it is not considered as a branch+return. Why?
- Problem with `setjmp()` and `longjmp()`? [ self-study ]



## CFG - Control flow graph

### Definition:

- A rooted directed graph  $G = (N, E)$ , where  $N$  is given by the set of basic blocks + two special BBs: `entry` and `exit`.
- And edge connects two basic blocks  $b_1$  and  $b_2$  if control can pass from  $b_1$  to  $b_2$ .
- An edge(s) from `entry` node to the initial basic block(s)
- From each final basic blocks (with no successors) to `exit` BB.



## CFG continued

- **successor** and **predecessor** – defined in a natural way.
- A basic block is called **branch node** - if it has more than one successor.
- **join node** – has more than one predecessor.
- For each basic block  $b$ :

$$Succ(b) = \{n \in N \mid \exists e \in E \text{ such that } e = b \rightarrow n\}$$

$$Pred(b) = \{n \in N \mid \exists e \in E \text{ such that } e = n \rightarrow b\}$$

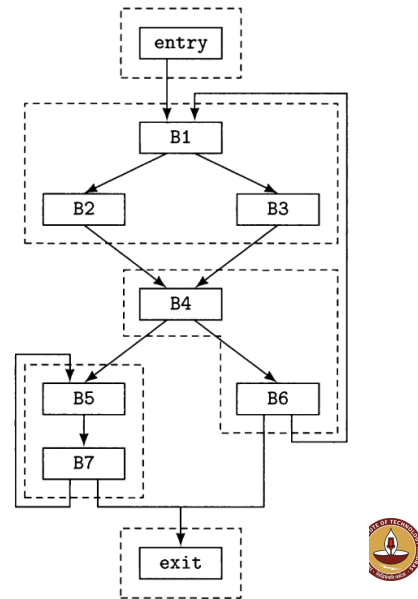
- A region is a strongly connected subgraph of a flow-graph.



## Extended basic block

### Extended basic block

- a maximal sequence of instructions beginning with a leader that contains no join nodes other than its first node.
- Has a single entry, but possible multiple exit points.
- Some optimizations are more effective on extended basic blocks.
- Why EBBs? Extending “local” optimizations to EBBs is straightforward.
- How to build an EBB, for a given basic block?



## Dominators and Postdominators

- Goal: To determine loops in the flowgraph.

### Dominance relation:

- Node  $d$  dominates node  $i$  (written  $d \text{ dom } i$ ), if every possible execution path from  $\text{entry}$  to  $i$  includes  $d$ .
- This relation is antisymmetric ( $a \text{ dom } b, b \text{ dom } a \Rightarrow a = b$ ), reflexive ( $a \text{ dom } a$ ), and transitive (if  $a \text{ dom } b$  and  $b \text{ dom } c$ , then  $a \text{ dom } c$ ).
- We write  $\text{dom}(a)$  to denote the dominators of  $a$ .

### Immediate dominance:

- A subrelation of dominance.
- For  $a \neq b$ , we say  $a \text{ idom } b$  iff  $a \text{ dom } b$  and there does not exist a node  $c$  such that  $c \neq a$  and  $c \neq b$ , for which  $a \text{ dom } c$  and  $c \text{ dom } b$ .
- We write  $\text{idom}(a)$  to denote the immediate dominator of  $a$  – note it is unique.

### Strict dominance:

- $d \text{ sdom } i$ , if  $d$  dominates  $i$  and  $d \neq i$ .

### Post dominance:

- $p \text{ pdom } i$ , if every possible execution path from  $i$  to  $\text{exit}$  includes  $p$ .
- Opposite of dominance ( $i \text{ dom } p$ ), in the reversed CFG (edges reversed,  $\text{entry}$  and  $\text{exit}$  exchanged).



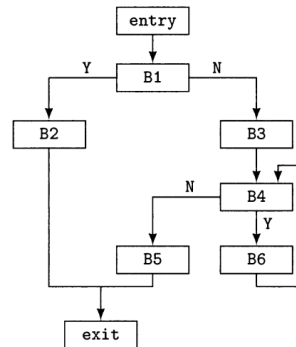
## Computing all the dominators

```

procedure Dom_Comp(N,Pred,r) returns Node → set of Node
N: in set of Node
Pred: in Node → set of Node
r: in Node
begin
  D, T: set of Node
  n, p: Node
  change := true: boolean
  Domin: Node → set of Node
  Domin(r) := {r}
  for each n ∈ N - {r} do
    Domin(n) := N
  od
  repeat
    change := false
  * for each n ∈ N - {r} do
    T := N
    for each p ∈ Pred(n) do
      T := Domin(p)
    od
    D := {n} ∪ T
    if D ≠ Domin(n) then
      change := true
      Domin(n) := D
    fi
  od
until !change
return Domin
end || Dom_Comp

```

\* Order makes the difference.



Compute the dominators.

| i     | Domin(i)                |
|-------|-------------------------|
| entry | {entry}                 |
| B1    | {entry, B1}             |
| B2    | {entry, B1, B2}         |
| B3    | {entry, B1, B3}         |
| B4    | {entry, B1, B3, B4}     |
| B5    | {entry, B1, B3, B4, B5} |
| B6    | {entry, B1, B3, B4, B6} |
| exit  | {entry, B1, exit}       |



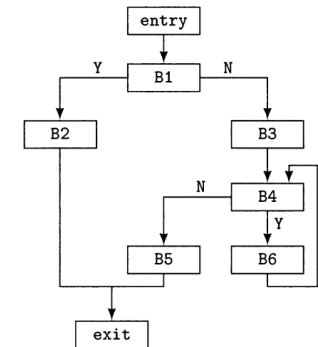
## Computing all the immediate dominators

```

procedure Idom_Comp(N,Domin,r) returns Node → Node
N: in set of Node
Domin: in Node → set of Node
r: in Node
begin
  n, s, t: Node
  Tmp: Node → set of Node
  Idom: Node → Node
  for each n ∈ N do
    Tmp(n) := Domin(n) - {n}
  od
  * for each n ∈ N - {r} do
    for each s ∈ Tmp(n) do
      for each t ∈ Tmp(n) - {s} do
        if t ∈ Tmp(s) then
          Tmp(n) -= {t}
        fi
      od
    od
  od
  for each n ∈ N - {r} do
    Idom(n) := ♦Tmp(n)
  od
return Idom
end || Idom_Comp

```

\* Order makes the difference.



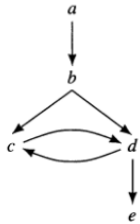
immediate dominators.

| i     | Idom(i) |
|-------|---------|
| entry | ∅       |
| B1    | {entry} |
| B2    | {B1}    |
| B3    | {B1}    |
| B4    | {B3}    |
| B5    | {B4}    |
| B6    | {B4}    |
| exit  | {B1}    |



## Identifying loops

- Back edge: an edge in the flowgraph, whose head dominates its tail. (Counter example)



Has a loop, but no back edge – hence not a natural loop.

- Given a back edge  $m \rightarrow n$ , the natural loop of  $m \rightarrow n$  is
  - the subgraph consisting of the set of nodes containing  $n$  and all the nodes from which  $m$  can be reached in the flowgraph without passing through  $n$ , and
  - the edge set connecting all the nodes in its node set.
  - Node  $n$  is called the loop header.



## Algorithm to compute natural loops

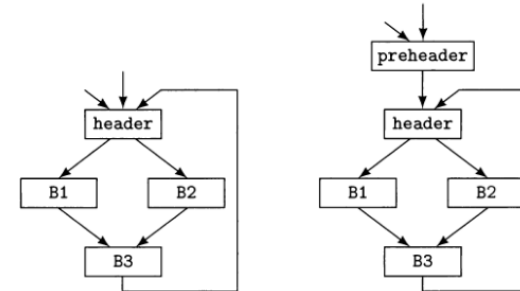
```

procedure Nat_Loop(m,n,Pred) returns set of Node
  m, n: in Node
  Pred: in Node → set of Node
begin
  Loop: set of Node
  Stack: sequence of Node
  p, q: Node
  Stack := []
  Loop := {m,n}
  if m ≠ n then
    Stack += [m]
  fi
  while Stack ≠ [] do
    || add predecessors of m that are not predecessors of n
    || to the set of nodes in the loop; since n dominates m,
    || this only adds nodes in the loop
    p := Stack[-1]
    Stack += -1
    for each q ∈ Pred(p) do
      if q ∉ Loop then
        Loop U= {q}
        Stack += [q]
      fi
    od
  od
  return Loop
end || Nat_Loop
  
```



## Loops (contd.)

- preheader: a new (initially empty) block is placed just before the header of a loop
- all the edges that previously went to the header from outside the loop now go to the preheader, and there is a single new edge from the preheader to the header.

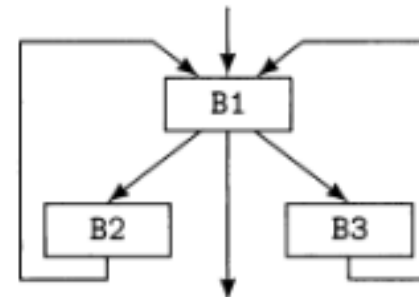


- Adv: helps optimizations that move code from inside a loop to just before its header – preheader guarantees that such a place is available – the code will be put in the pre-header



## Loops (contd.)

- Unless two natural loops have the same header – they are either disjoint or one is nested inside other.
- What about the other way? Given two loops with the same header – can we guarantee that either a) one is nested inside other, or b) they constitute the same loop?



## Two natural Loops with same header (contd.)

```

i = 1;
B1: if (i >= 100)
    goto b4;
    else if ((i % 10) == 0)
        goto B3;
    else
B2:     ...
        i++;
        goto B1;
B3:     ...
        i--;
        goto B1;
B4:     ...

```

- Can be fixed – disallow if-then-else?
- What about loops with multiple entry points?
- A loop can be most generally described by a strongly connected component of a flowgraph.
- Self reading – Algorithm to compute SCCs.



## Reducibility

- “Reducibility” – a property of the flowgraphs.
- A reducible transformation is one that collapses subgraphs into single nodes (and hence “reduces” the graph).
- A flow graph is reducible if applying a sequence of such transformations ultimately reduces it to a single node.
- A flow graph  $G = (N, E)$  is reducible (or well structured) iff
  - $E$  can be partitioned into disjoint sets  $E_F$  – set of forward edges; and  $E_B$  – set of backward edges; such that
  - $(N, E_F)$  forms a DAG in which every node can be reached from the entry node.
  - $E_B$  has all the back edges.
- A flowgraph is reducible if all the loops in it are natural loops (characterized by their back edges) and vice versa.
- Implication: A reducible flowgraph has no jumps into the middle of the loops – makes the analysis easy.
- Read yourself – irreducible flow graphs.

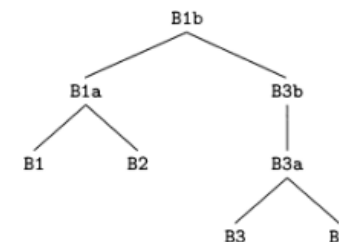
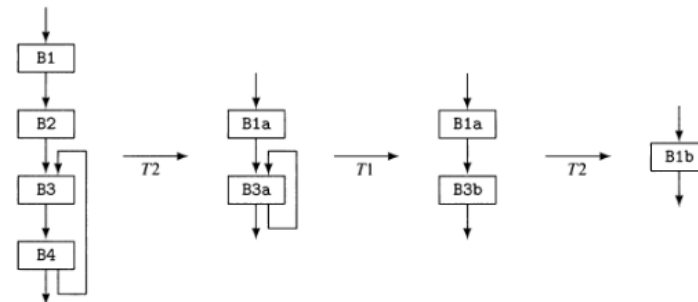


## Interval analysis

- An alternative approach to do control flow analysis.
- Overall three steps:
  - Divide the flowgraph into “regions” of various sorts (depending on the particular approach),
  - consolidating each region into a new node (called an abstract node – as it abstracts away what’s inside the node), and
  - replace “entering” and “leaving” edges.
- Resulting graph is called a abstract flowgraph.
- The above transformations can be applied in sequence or in parallel.
- Each abstract node corresponds to a subgraph.
- The result of applying such transformations on a abstract flowgraph is also called control tree.



## Example T1-T2 analysis



## Control tree:

- Root of the control tree is an abstract graph representing the original graph.
- The leaves are individual basic blocks.
- The nodes between the root and the leaves are the abstract nodes representing regions of the flowgraph.
- The edges represent the relationship between each abstract node and the node regions.

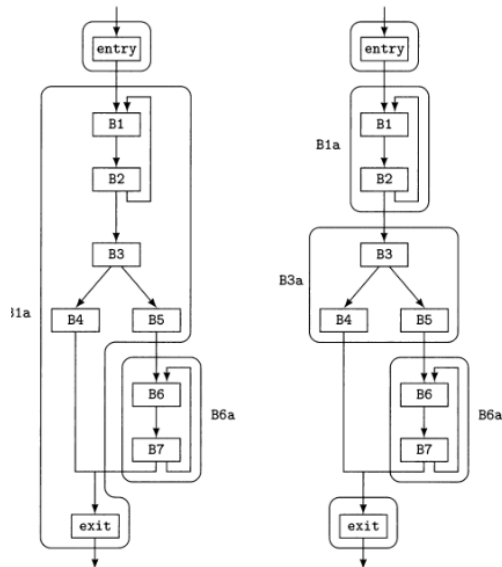


## Interval analysis

- Ignores irreducible regions.
- Uses maximal intervals: A maximal interval, with a leader  $h$  is the single entry subgraph with entry  $h$ , may contain a natural loop and some acyclic structure dangling from its exits.
- minimal interval: A minimal interval is defined to be
  - ① a natural loop.
  - ② a maximal acyclic subgraph.
  - ③ a minimal irreducible region.
- It is used to identify loops in the flowgraph.



## Example: Maximal and minimal intervals

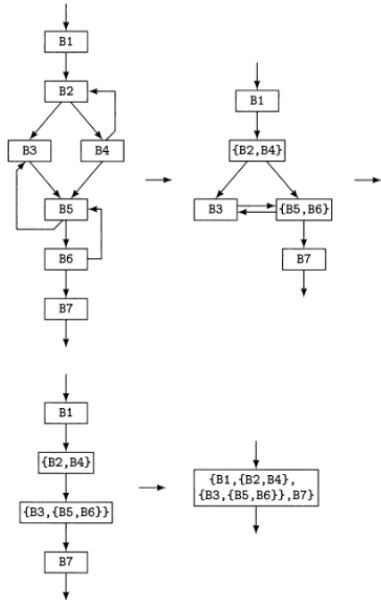


## Steps to perform interval analysis

- Perform a postorder traversal of the flowgraph – look for loop headers, and headers of improper regions.
- For each loop header found, construct its natural loop; and then reduce it (T1).
- For each improper region – construct a minimal SCC and reduce.
- For the `entry` node and the immediate descendent of a node in a natural loop, construct a maximal acyclic graph with that node as its root; may reduce it (T2) if it has more than one node in it.
- Iterate till it terminates.



## Example: Interval analysis



## Approaches to Control flow Analysis

Two main approaches to control-flow analysis of single routines.

- Both start by determining the basic blocks that make up the routine.
- Construct the control-flowgraph.

First approach:

- Use dominators to discover loops; to be used in later optimizations.
- Sufficient for many optimizations (ones that do iterative data-flow analysis, or ones that work on individual loops only).

Second approach (interval analysis):

- Analyzes the overall structure of the routine.
- Decomposes the routine into nested regions - called intervals.
- The resulting nesting structure is called a control tree.
- A sophisticated variety of interval analysis is called structural analysis.

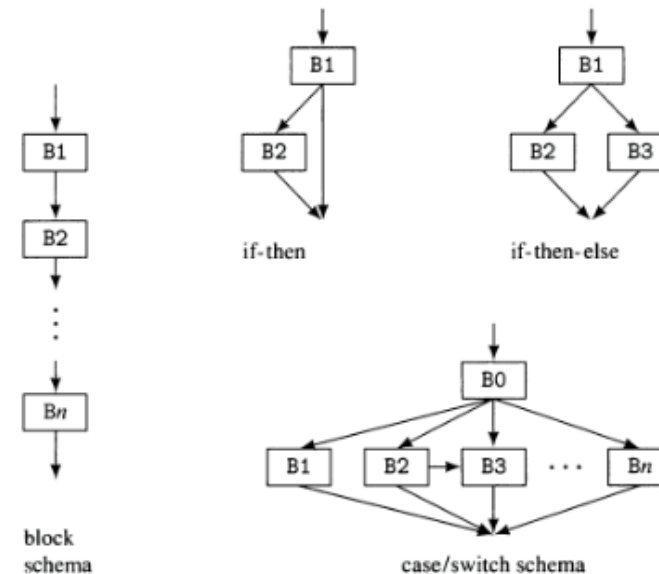


## Structural analysis

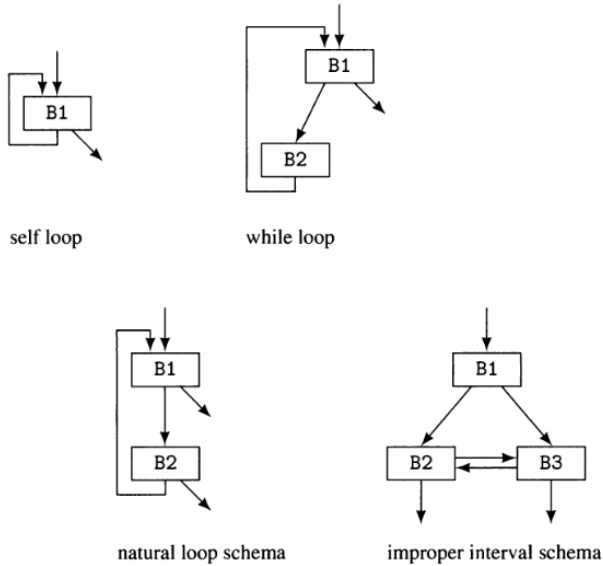
- A more refined form of interval analysis.
- Differs from basic interval analysis in that it identifies many types of control structures than just loops.
- Each such structure is turned into a region and provides a basis for doing efficient data-flow analysis on each of the different regions.
- Output - a control tree. Typically larger than that we find for interval analysis. But the individual regions are simpler and simpler.
- Region – has exactly one entry point – How to include an irreducible or improper region? (coming soon).



## Examples of (Acyclic) regions

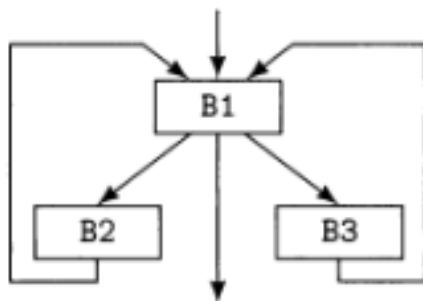


## Examples of (Cyclic) regions



## Structural analysis - computation

- Process is similar to that of interval analysis – except that there are more patterns.

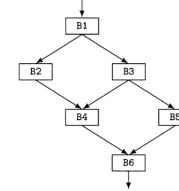


Example:



## Beyond the discussed regions

- The patterns for the control-flow constructs are determined by the syntax and semantics of the language.
- The presented patterns are schematic in nature.
  - For example - switch case may or not have a free fall to the next branch.
  - “natural loop” talks about loops that neither a self or a while loop.
- Will the presented patterns cover all types of intervals seen in practise?
- Another type of pattern is called a proper interval – an arbitrary acyclic structure; contains no cycles and cannot be reduced to any of the simple acyclic cases.



Example:



## Structural analysis - algorithm

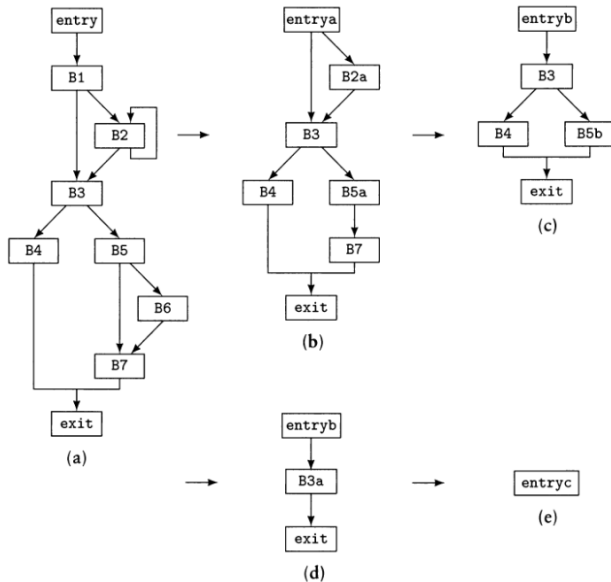
- Construct a depth-first spanning tree for the flowgraph.
- Examine the flowgraph's nodes in postorder, for instances of the various regions.
  - Form abstract nodes for each region.
  - Collapse the connecting edges.
- Build the control tree in the process.

Self reading: how to identify these intervals?





## Example - structural analysis

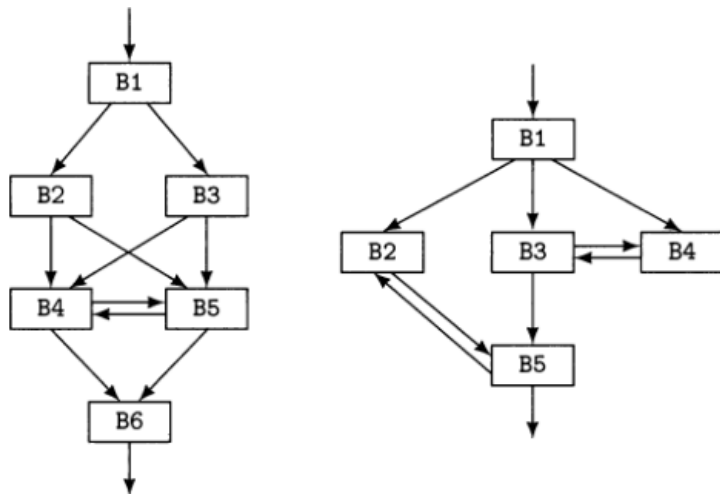


## How to detect Improper regions

- Add the lowest common dominator ( $n_{gcd}$ ) of the set of entry points ( $I$ ) for the multiple-entry cycle.
- Find a node that is reachable from  $n_{gcd}$ . Say  $n$ .
- If there exists a path from  $n$  to any element of  $I$  – add  $n$ .



## Improper regions and Importance of order



- 1 interval = (improper)  $\{B1, B2, B3, B4, B5\} \{B6\}$
- 2 Say, we choose B3 before B2: a)  $\{B1, B3, B4\}, \{B2, B5\}$ ;  
Otherwise b)  $\{B1, B2, B3, B4, B5\}$



## Who uses what?

We studied two techniques: dominators based and interval analysis based. Which is used in practise?

- Most optimizing compilers dominators and iterative data flow analysis – its easy/quick to write.

But

- The interval-based approaches are faster.
- The interval-based approaches help easy update of computed data (don't need to recompute from scratch).



## Uses of Structural analysis

- Structural control flow analysis to the aid of Constant propagation.
- Control flow optimizations



## Control flow optimization

- Goal: produce longer basic blocks. What is it good for?
  - Can help increase instruction-level parallelism.
- Reduce code size.



## Unreachable code elimination



## Straightening

- Fuses basic blocks if the predecessor has only one successor and the successor has only one predecessor.



## If simplification

- Simplify if conditions:
  - Say the `then` part is empty – reverse the condition.
  - If both `then` and `else` are empty – remove both and keep the condition. Why?
  - 'Predicate' evaluates to a constant – throw away `then` or `else` part. What about the predicate evaluation?
  - Nested if-then-else statements where the outer predicate  $\Rightarrow$  inner predicate.



## Examples - loop inversion

- Where the loop condition is known to hold for the first iteration.
- Where the loop condition is not guaranteed to hold for the first iteration.



## Loop Inversion

- Transforming a `while` loop to a `do-while` or `repeat-until` loop.
- Adv:
  - Only one jump to end the loop.
  - Gives a guarantee that the loop will be executed for sure.

```
x = 3;
while (cond) {
    S1;
    x = 4;
}
// Q: Is x a constant here?
```



## Closing remarks

What have we done?

- Control flow analysis (identifying loops and interval analysis).
- Control flow optimizations.

To read

- Muchnick - Ch 7, (parts of) Ch 18.

Next:

- Data flow analysis

