#### Complexity of Matrix Rank and Rigidity

Jayalal Sarma M.N.

Joint work with Meena Mahajan

IMSc

Institute Seminar Week

Mar 5, 2007

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

#### Matrix Rank

Rank of a matrix  $M \in \mathbb{F}^{n \times n}$  has the following equivalent definitions.

- ► The size of the largest submatrix with non-zero determinant.
- ► The number of linearly independent rows/columns of a matrix.
- ▶ The smallest *r* such that M = AB where  $A \in \mathbb{F}^{n \times r}$  is an  $B \in \mathbb{F}^{r \times n}$  matrix.
- The smallest k such that M is the sum of k rank-1 matrices.

SINGULAR: Given a matrix M, is rank(M) < n?

RANK BOUND: Given a matrix M and a value r, is rank(M) < r?

### Computing the Rank

Some motivation ...

- From Linear Algebra : Computation of the dimension of the solution space of a system of linear equations.
- From Control Theory : Rank of a matrix can be used to determine whether a linear system is controllable, or observable.
- From Algorithmics : Some natural algorithmic problems can be expressed in terms of rank computation and determinant computation.
- From Complexity Theory : In the context of seperating complexity classes, it might facilitate application of the well developed algebraic techniques.

<ロト (個) (目) (目) (目) (0) (0)</p>

Classes based on Turing machine (TM) models

 L : Problems that can be solved by TMs which uses only O(log n)-space.

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

Classes based on Turing machine (TM) models

- L : Problems that can be solved by TMs which uses only O(log n)-space.
- NL : Problems that can be solved by O(log n)-space TMs which are allowed to guess and verify but they should get it right atleast once for a positive answer and none otherwise.

Classes based on Turing machine (TM) models

- L : Problems that can be solved by TMs which uses only O(log n)-space.
- NL : Problems that can be solved by O(log n)-space TMs which are allowed to guess and verify but they should get it right atleast once for a positive answer and none otherwise.
- C<sub>=</sub>L : Problems that can be solved by O(log n)-space TMs which are allowed to guess and verify but they should get it right exactly half the time for a postive answer, and non-half otherwise.

Classes based on Turing machine (TM) models

- L : Problems that can be solved by TMs which uses only O(log n)-space.
- NL : Problems that can be solved by O(log n)-space TMs which are allowed to guess and verify but they should get it right atleast once for a positive answer and none otherwise.
- ► C<sub>=</sub>L : Problems that can be solved by O(log n)-space TMs which are allowed to guess and verify but they should get it right exactly half the time for a postive answer, and non-half otherwise.

Circuits are directed acyclic graphs with  $\wedge,\,\vee$  and  $\neg$  gates at the vertices.

- ► AC<sup>0</sup> : poly size constant depth and unbounded fanin circuits.
- ▶ TC<sup>0</sup> : AC<sup>0</sup> with "majority" gates

# Why are they interesting ?

Class	Resource Bound	Complete Problem
L	log space	Reachability in
	ТМ	undirected graphs
NL	log space TMs with	Reachability in
	guess & verify power	directed graphs
$C_{=}L$	log space TMs with	Singularity of
	"balanced" guess & verify	0-1 matrices
AC <sup>0</sup>	poly size, constant	Reachability in
	depth circuits	constant width maze-graphs
TC <sup>0</sup>	$AC^0 +$ "majority"	Testing Majority

# The Zoo below P



・ロト・西ト・西ト・日・ うらの

Turing/Circuit Model : Combinatorial ! Seperation of small classes : Unknown



Rank Computation : Algebraic ! Characterising computation using this might help.

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

# Computing the Rank

- The natural approach takes exponential time.
- Can be computed in Polynomial time : Gaussian elimination (1800s)
  But it is inherently sequential.
- Elegant parallel algorithm ([Mul87]) by relating the problem to testing if some coefficients of the characteristic polynomial are zeros. Rank can be computed in NC.
- Refined complexity bounds by [ABO96]. Upperbound testing exactly characterises C<sub>=</sub>L.

## Computing the rank of special matrices

- Complexity theoretic characterisations.
- Several applications have inherent structure for the matrices.

Restrictions we are interested in :

•  $M = [a_{i,j}]$  is diagonally dominant if

$$|a_{ii}| \ge \sum_{j \ne i} |a_{ij}|$$

Fun fact : If dominance is strict for all i, M is non-singular.

 Diagonal matrices : Non-zero entries only on the main diagonal.

# Characterising Log space

#### Theorem

Computing the rank of symmetric non-negative diagonally dominant matrices is complete for the complexity class L.

- Membership: The proof uses a nice combinatorial characterisation of the dimension of the null-space of the matrix due to [Dah99]. We can reduce the problem to counting the number of bipartite components in a graph.
- Hardness :The problem of testing reachability in undirected forests where there are exactly two components is L-complete. We reduce this problem to rank computation on symmetric non-negative diagonally dominant matrices.

#### For Special Matrices...

Matrix type	RANK BOUND	SINGULAR
General	C <sub>=</sub> L-complete	$C_{=}L$ -complete
	[ABO96]	[ABO96]
Sym.Non-neg.	C <sub>=</sub> L-complete	$C_{=}L$ -complete
	[ABO96]	[ABO96]

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

#### For Special Matrices...

Matrix type	RANK BOUND	SINGULAR
General	$C_{=}L$ -complete	$C_{=}L$ -complete
	[ABO96]	[ABO96]
Sym.Non-neg.	$C_{=}L$ -complete	$C_{=}L$ -complete
	[ABO96]	[ABO96]
Sym.Non-neg.		
Diag. Dom.	L-complete	L-complete
Diag	TC <sup>0</sup> -complete	in AC <sup>0</sup>

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

#### How close is M to a rank r matrix?

## Definition (Rigidity)

Given a matrix M and r < n, rigidity of the matrix  $M(R_M(r))$  is the number of entries of the matrix that we need to change to bring the rank below r.

- A natural linear algebraic optimisation problem; and it arises in control theory.
- Interesting in a circuit complexity theory setting. Highly rigid linear transformations(matrices) have some "nice" size lowerbounds for log-depth circuits computing them [Val77].

It is related to the "power" of Valiant's proof technique.

# Computing Rigidity

RIGID(M, r, k): Given a matrix M, values r and k, is  $R_M(r) \le k$ .

- ► Over any finite field F, RIGID is in NP. The algorithm will simply guess the positions and the changed values and simply verify if the rank has gone down.
- ► Over F<sub>2</sub>, RIGID is NP-complete [Des]. The hardness comes from a reduction from a problem in the coding theory setting : the nearest neighbour decoding problem.

- Over infinite fields the only upperbound we know is *r.e.*
- ► If k is constant, restriced to boolean matrices, RIGID is C=L-complete.

#### Bounded Rigidity

Too much change involves too much "cost".

- Given a matrix M and r < n, bounded rigidity of the matrix M (R<sub>M</sub>(b, r)) is the number of entries of the matrix that we need to change to bring the rank below r, if the change allowed per entry is atmost b.
- ▶ B-RIGID(M, r, k, b): Given a matrix M, values b, r and k, is  $R_M(b, r) \le k$ ?
- Another formulation : Define an interval of matrices [A] where

$$m_{ij} - b \leq a_{ij} \leq m_{ij} + b$$

Question : Is there a rank r matrix  $B \in [A]$  such that M - B has atmost k non-zero entries?

#### Why should there be?

Consider the matrix

$$\left[\begin{array}{cccccc} 2^k & 0 & 0 & 0 & 0 \\ 0 & 2^k & 0 & 0 & 0 \\ 0 & 0 & 2^k & 0 & 0 \\ 0 & 0 & 0 & 2^k & 0 \\ 0 & 0 & 0 & 0 & 2^k \end{array}\right]$$

- $R_M(b, n-1)$  is undefined unless  $b \ge \frac{2^k}{n}$ .
- Question : For a given matrix M, bound b, target rank r, can we efficiently test, whether R<sub>M</sub>(b, r) is defined ?

#### Why should there be?

Consider the matrix

$$\left[\begin{array}{cccccc} 2^k & 0 & 0 & 0 & 0 \\ 0 & 2^k & 0 & 0 & 0 \\ 0 & 0 & 2^k & 0 & 0 \\ 0 & 0 & 0 & 2^k & 0 \\ 0 & 0 & 0 & 0 & 2^k \end{array}\right]$$

- $R_M(b, n-1)$  is undefined unless  $b \ge \frac{2^k}{n}$ .
- Question : For a given matrix M, bound b, target rank r, can we efficiently test, whether R<sub>M</sub>(b, r) is defined ?

It is NP-hard.

#### A restricted case

For a given matrix M, bound b, testing whether  $R_M(b, n-1)$  is defined, is NP-complete.

Membership: The bound b defines an interval for each entry of the matrix.

Determinant is a multilinear polynomial on the entries of the matrix.

Now use the following lemma:

#### Lemma (Zero-on-an-edge)

For a multilinear polynomial  $p(x_1, x_2 \dots x_t)$ , consider the hypercube defined by the interval of each of the  $x_i$ s. If there is a zero of the polynomial in the hypercube then there is a zero on an edge of the hypercube.

- ▶ NP algorithm : Guess the "nice" singular matrix and verify.
- ► Hardness: A reduction from MAX-CUT problem.

# Thank You

<□ > < @ > < E > < E > E のQ @

Eric Allender, Robert Beals, and Mitsunori Ogihara.

The complexity of matrix rank and feasible systems of linear equations.

In STOC 96, pages 161-167, 1996.

G. Dahl.

A note on nonnegative diagonally dominant matrices. *Linear Algebra and Applications*, 317:217–224, April 1999.

- Amit Jayant Deshpande. Private Communication (Sep 2006).
- K. Mulmuley.

A fast parallel algorithm to compute the rank of a matrix over an arbitrary field.

Combinatorica, 7:101-104, 1987.

#### L. G. Valiant.

Graph theoretic arguments in low-level complexity. In *MFCS 1977*, pages 162–176, 1977.