

## CS3300 - Language Translators

### Liveness analysis and Register allocation

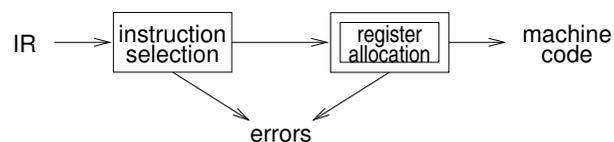
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# Register allocation



Register allocation:

- have value in a register when used
- limited resources
- can effect the instruction choices
- can move loads and stores
- optimal allocation is difficult  
⇒ NP-complete for  $k \geq 1$  registers



# Liveness analysis

Problem:

- IR contains an unbounded number of temporaries
- machine has bounded number of registers

Approach:

- temporaries with disjoint live ranges can map to same register
- if not enough registers then spill some temporaries (i.e., keep them in memory)

The compiler must perform liveness analysis for each temporary:

*It is live if it holds a value that may be needed in future*



## Example

```
a ← 0
L1: b ← a + 1
      c ← c + b
      a ← b × 2
      if a < N goto L1
      return c
```



## Liveness analysis

Gathering liveness information is a form of data flow analysis operating over the CFG:

- We will treat each statement as a different basic block.
- liveness of variables “flows” around the edges of the graph
- assignments define a variable,  $v$ :
  - $def(v)$  = set of graph nodes that define  $v$
  - $def[n]$  = set of variables defined by  $n$
- occurrences of  $v$  in expressions use it:
  - $use(v)$  = set of nodes that use  $v$
  - $use[n]$  = set of variables used in  $n$



## Definitions

- $v$  is live on edge  $e$  if there is a directed path from  $e$  to a use of  $v$  that does not pass through any  $def(v)$
- $v$  is live-in at node  $n$  if live on any of  $n$ 's in-edges
- $v$  is live-out at  $n$  if live on any of  $n$ 's out-edges
- $v \in use[n] \Rightarrow v$  live-in at  $n$
- $v$  live-in at  $n \Rightarrow v$  live-out at all  $m \in pred[n]$
- $v$  live-out at  $n, v \notin def[n] \Rightarrow v$  live-in at  $n$



## Liveness analysis

Define:

$$\begin{aligned} in[n] &= \text{variables live-in at } n \\ out[n] &= \text{variables live-out at } n \end{aligned}$$

Then:

$$\begin{aligned} out[n] &= \bigcup_{s \in succ(n)} in[s] \\ succ[n] = \emptyset &\Rightarrow out[n] = \emptyset \end{aligned}$$

Note:

$$\begin{aligned} in[n] &\supseteq use[n] \\ in[n] &\supseteq out[n] - def[n] \end{aligned}$$

$use[n]$  and  $def[n]$  are constant (independent of control flow)

Now,  $v \in in[n]$  iff.  $v \in use[n]$  or  $v \in out[n] - def[n]$

Thus,  $in[n] = use[n] \cup (out[n] - def[n])$



## Iterative solution for liveness

$N$  : Set of nodes of CFG;

**foreach**  $n \in N$  **do**

$in[n] \leftarrow \phi$ ;  
     $out[n] \leftarrow \phi$ ;

**end**

**repeat**

**foreach**  $n \in \text{Nodes}$  **do**

$in'[n] \leftarrow in[n]$ ;  
         $out'[n] \leftarrow out[n]$ ;  
         $in[n] \leftarrow use[n] \cup (out[n] - def[n])$ ;  
         $out[n] \leftarrow \bigcup_{s \in succ[n]} in[s]$ ;

**end**

**until**  $\forall n, in'[n] = in[n] \vee out'[n] = out[n]$ ;



## Notes

- should order computation of inner loop to follow the “flow”
- liveness flows backward along control-flow arcs, from out to in
- nodes can just as easily be basic blocks to reduce CFG size
- could do one variable at a time, from uses back to defs, noting liveness along the way



## Iterative solution for liveness

Complexity: for input program of size  $N$

- $\leq N$  nodes in CFG  
     $\Rightarrow \leq N$  variables  
     $\Rightarrow N$  elements per *in/out*  
     $\Rightarrow O(N)$  time per set-union
- **for** loop performs constant number of set operations per node  
     $\Rightarrow O(N^2)$  time for **for** loop
- each iteration of **repeat** loop can only add to each set  
    sets can contain at most every variable  
     $\Rightarrow$  sizes of all in and out sets sum to  $2N^2$ ,  
    bounding the number of iterations of the **repeat** loop  
 $\Rightarrow$  worst-case complexity of  $O(N^4)$
- ordering can cut **repeat** loop down to 2-3 iterations  
     $\Rightarrow O(N)$  or  $O(N^2)$  in practice



## Least fixed points

There is often more than one solution for a given dataflow problem (see example).

Any solution to dataflow equations is a conservative approximation:

- $v$  has some later use downstream from  $n$   
     $\Rightarrow v \in out(n)$
- but not the converse

Conservatively assuming a variable is live does not break the program; just means more registers may be needed.

Assuming a variable is dead when really live will break things.

Many possible solutions but we want the “smallest”: the least fixpoint.

The iterative algorithm computes this least fixpoint.

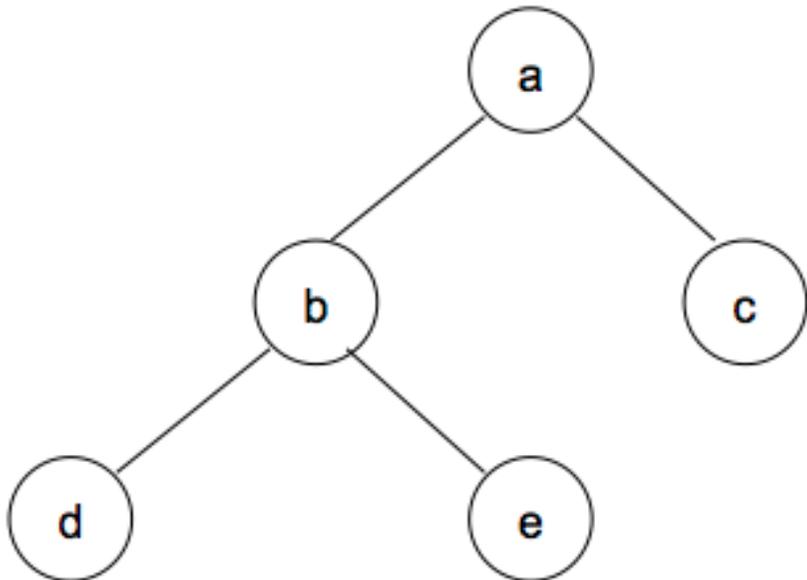


# Register allocation - by Graph coloring

- Step 1:
  - Select target machine instructions assuming infinite registers (temps).
  - If an instruction requires a special register – replace that temp with that register.
- Step 2:
  - Construct an interference graph.
  - Solve the register allocation problem by coloring the graph.
  - A graph is said to be colored if each pair of neighboring nodes have different colors.



## Example 1, available colors = 2



# Graph coloring - a simplistic approach

**Input:**  $G$  - the interference graph,  $K$  - number of colors

**repeat**

**repeat**

    Remove a node  $n$  and all its edges from  $G$ , such that degree of  $n$  is less than  $K$ ;

    Push  $n$  onto a stack;

**until**  $G$  has no node with degree less than  $K$ ;

  //  $G$  is either empty or all of its nodes have degree  $\geq K$

**if**  $G$  is not empty **then**

    Take one node  $m$  out of  $G$ , and mark it for spilling;

    Remove all the edges of  $m$  from  $G$ ;

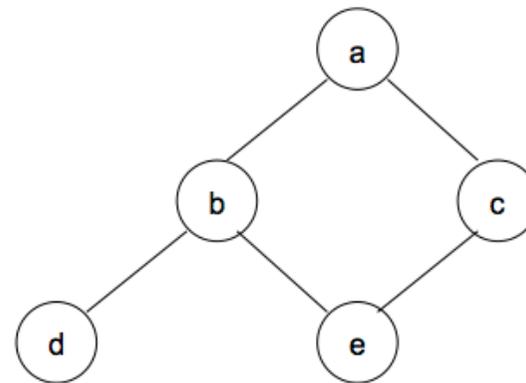
**end**

**until**  $G$  is empty;

Take one node at a time from the stack and assign a non conflicting color.



## Example 2



We have to spill.



## Graph coloring - Kempe's heuristic

- Algorithm dating back to 1879.

**Input:**  $G$  - the interference graph,  $K$  - number of colors

**repeat**

**repeat**

    Remove a node  $n$  and all its edges from  $G$ , such that degree of  $n$  is less than  $K$ ;

    Push  $n$  onto a stack;

**until**  $G$  has no node with degree less than  $K$ ;

  //  $G$  is either empty or all of its nodes have degree  $\geq K$

**if**  $G$  is not empty **then**

    Take one node  $m$  out of  $G$ .;

    push  $m$  onto the stack;

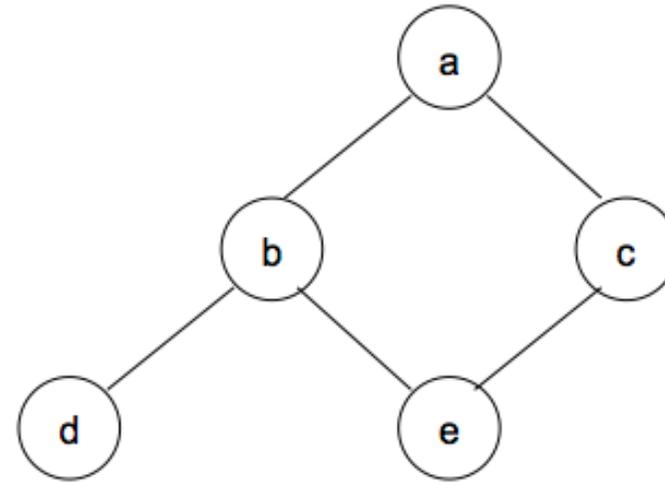
**end**

**until**  $G$  is empty;

Take one node at a time from the stack and assign a non conflicting color possible, else spill).



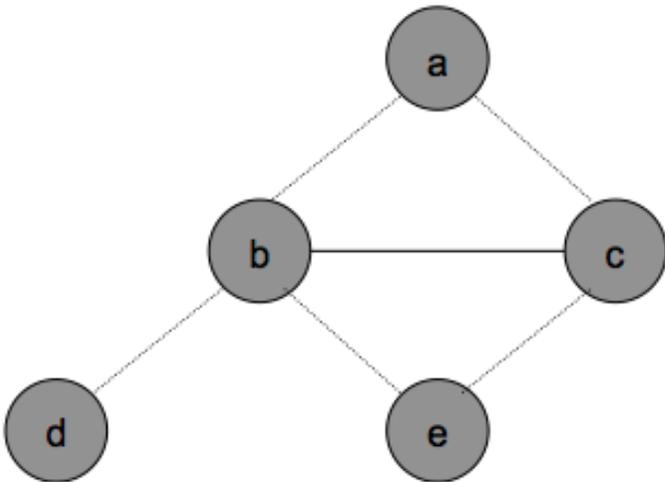
## Example 2 (revisited)



We don't have to spill.



## Example 3



Don't have a choice. Have to spill.



## Register allocation - Linear scan

Register allocation is **expensive**.

- Many algorithms use heuristics for graph coloring.
- Allocation may take time quadratic in the number of live intervals.

**Not suitable**

- Online compilers – need to generate code quickly. e.g. JIT compilers.
- Sacrifice efficient register allocation for compilation speed.

Linear scan register allocation - Massimiliano Poletto and Vivek Sarkar, ACM TOPLAS 1999



## Linear Scan algorithm

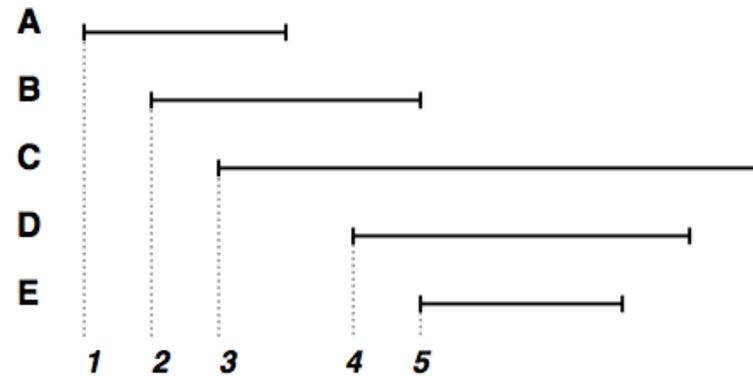
```
LINEARSCANREGISTERALLOCATION
  active ← {}
  foreach live interval i, in order of increasing start point
    EXPIREOLDINTERVALS(i)
    if length(active) = R then
      SPILLATINTERVAL(i)
    else
      register[i] ← a register removed from pool of free registers
      add i to active, sorted by increasing end point

EXPIREOLDINTERVALS(i)
  foreach interval j in active, in order of increasing end point
    if endpoint[j] ≥ startpoint[i] then
      return
  remove j from active
  add register[j] to pool of free registers

SPILLATINTERVAL(i)
  spill ← last interval in active
  if endpoint[spill] > endpoint[i] then
    register[i] ← register[spill]
    location[spill] ← new stack location
    remove spill from active
    add i to active, sorted by increasing end point
  else
    location[i] ← new stack location
```



## Example



- Say, available registers = 2



## Linear Scan algorithm - analysis

- Each live range gets either a register or a spill location.
- Note: The number of overlapping intervals changes only at the start and end points of an interval.
- Live intervals are stored in a list that is sorted in order of increasing start point.
- The active list is kept sorted in order of increasing end point. Adv: need to scan only those intervals (+1 at most) that have to be removed.
- Complexity:  $O(V)$  – if number of registers is assumed to be a constant. Else?  $O(V \times \log R)$



## Spilling

- We need to generate extra instructions to load variables from the stack and store them back.
- The load and store may require registers again:
  - Naive approach: Keep a separate register (wasteful).
  - Rewrite the code - by introducing a temporary; rerun the liveness + ra.  
(Note: the new temp has much smaller live range).



## Example: rewrite code

**Consider:** `add t1 t2`

- Suppose `t2` has to be spilled, say to `[sp-4]`.
- Invent a new temp `t35`, and rewrite:  
`mov t35 [sp-4]` `add t1 t35`
- `t35` has a very short live range and less likely to interfere.
- Now rerun the algo.



## Criteria for spilling

During register allocation, we identify that one of the live ranges from a given set, has to be spilled. Criteria?

- Random! Adv? Disadv?
- One with maximum degree
- One that has the longest life
- One with the shortest life (take advantage of the cache).
- One with least cost.
  - Cost = Dynamic (load cost + store cost)
  - How to handle loops, conditionals?
  - Cost of load, store



## Caller and Callee save registers

- The set of registers are divided into caller save and callee save registers.
- Caller has three choices: Save callee save registers, caller save registers or all.
- Callee has three choices: Save caller save registers, callee save registers or all.

Adv and Disadv?

