

# CS6013 - Modern Compilers: Theory and Practise

## Register Allocation

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## Register allocation

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## Opening remarks

What have we done so far?

- Compiler overview.
- Scanning and parsing.
- JavaCC, visitors and JTB
- Semantic Analysis - specification, execution, attribute grammars.
- Type checking, Intermediate Representation, Intermediate code generation.
- Control flow analysis, interval analysis, structural analysis
- Data flow analysis, intra-procedural and inter-procedural constant propagation.
- Points-to analysis

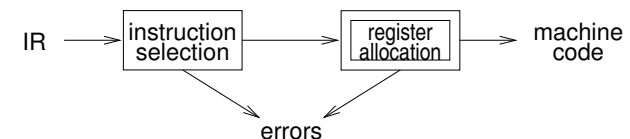
Announcement:

- Assignment 5 is out. Due in three weeks.

Today: Liveness analysis and register allocation.



## Register allocation



Register allocation:

- have value in a register when used
- limited resources
- can effect the instruction choices
- can move loads and stores
- optimal allocation is difficult  
⇒ NP-complete for  $k \geq 1$  registers



# Liveness analysis

Problem:

- IR contains an unbounded number of temporaries
- machine has bounded number of registers

Approach:

- temporaries with disjoint live ranges can map to same register
- if not enough registers then spill some temporaries (i.e., keep them in memory)

The compiler must perform liveness analysis for each temporary:

*It is live if it holds a value that may be needed in future*



# Example

```

a ← 0
L1: b ← a + 1
      c ← c + b
      a ← b × 2
      if a < N goto L1
      return c

```



# Liveness analysis

Gathering liveness information is a form of data flow analysis operating over the CFG:

- We will treat each statement as a different basic block.
- liveness of variables “flows” around the edges of the graph
- assignments define a variable,  $v$ :
  - $def(v)$  = set of graph nodes that define  $v$
  - $def[n]$  = set of variables defined by  $n$
- occurrences of  $v$  in expressions use it:
  - $use(v)$  = set of nodes that use  $v$
  - $use[n]$  = set of variables used in  $n$



# Definitions

- $v$  is live on edge  $e$  if there is a directed path from  $SRC(e)$  to a use of  $v$  that does not pass through any  $def(v)$
- $v$  is live-in at node  $n$  if live on all of  $n$ 's in-edges
- $v$  is live-out at  $n$  if live on any of  $n$ 's out-edges
- $v \in use[n] \Rightarrow v$  live-in at  $n$
- $v$  live-in at  $n \Rightarrow v$  live-out at all  $m \in pred[n]$
- $v$  live-out at  $n, v \notin def[n] \Rightarrow v$  live-in at  $n$



## Liveness analysis

Define:

$in[n]$  = variables live-in at  $n$   
 $out[n]$  = variables live-out at  $n$

Then:

$out[n] = \bigcup_{s \in succ(n)} in[s]$   
 $succ[n] = \phi \Rightarrow out[n] = \phi$

Note:

$in[n] \supseteq use[n]$   
 $in[n] \supseteq out[n] - def[n]$

$use[n]$  and  $def[n]$  are constant (independent of control flow)

Now,  $v \in in[n]$  iff.  $v \in use[n]$  or  $v \in out[n] - def[n]$

Thus,  $in[n] = use[n] \cup (out[n] - def[n])$



## Iterative solution for liveness

$N$  : Set of nodes of CFG;

**foreach**  $n \in N$  **do**

$in[n] \leftarrow \phi$ ;

$out[n] \leftarrow \phi$ ;

**end**

**repeat**

**foreach**  $n \in Nodes$  **do**

$in'[n] \leftarrow in[n]$ ;

$out'[n] \leftarrow out[n]$ ;

$in[n] \leftarrow use[n] \cup (out[n] - def[n])$ ;

$out[n] \leftarrow \bigcup_{s \in succ[n]} in[s]$  ;

**end**

**until**  $\forall n, in'[n] = in[n] \vee out'[n] = out[n]$  ;



## Notes

- should order computation of inner loop to follow the “flow”
- liveness flows backward along control-flow arcs, from out to in
- nodes can just as easily be basic blocks to reduce CFG size
- could do one variable at a time, from uses back to defs, noting liveness along the way



## Iterative solution for liveness

Complexity: for input program of size  $N$

- $\leq N$  nodes in CFG  
 $\Rightarrow \leq N$  variables  
 $\Rightarrow N$  elements per  $in/out$   
 $\Rightarrow O(N)$  time per set-union
- **for** loop performs constant number of set operations per node  
 $\Rightarrow O(N^2)$  time for **for** loop
- each iteration of **repeat** loop can only add to each set  
sets can contain at most every variable  
 $\Rightarrow$  sizes of all in and out sets sum to  $2N^2$ ,  
bounding the number of iterations of the **repeat** loop
- $\Rightarrow$  worst-case complexity of  $O(N^4)$
- ordering can cut **repeat** loop down to 2-3 iterations  
 $\Rightarrow O(N)$  or  $O(N^2)$  in practice



## Least fixed points

There is often more than one solution for a given dataflow problem (see example).

Any solution to dataflow equations is a conservative approximation:

- $v$  has some later use downstream from  $n$   
 $\Rightarrow v \in out(n)$
- but not the converse

Conservatively assuming a variable is live does not break the program; just means more registers may be needed.

Assuming a variable is dead when really live will break things.

Many possible solutions but we want the “smallest”: the least fixpoint.

The iterative algorithm computes this least fixpoint.



## Register allocation - by Graph coloring

- Step 1:
  - Select target machine instructions assuming infinite registers (temps).
  - If an instruction requires a special register – replace that temp with that register.
- Step 2:
  - Construct an interference graph.
  - Solve the register allocation problem by coloring the graph.
  - A graph is said to be colored if each each pair of neighboring nodes have different colors.

Parts of slides: sources - Andrew Myers



## Graph coloring - a simplistic approach

**Input:**  $G$  - the interference graph,  $K$  - number of colors

**repeat**

// Simplify

**repeat**

Remove a node  $n$  and all its edges from  $G$ , such that degree of  $n$  is less than  $K$ ;

Push  $n$  onto a stack;

**until**  $G$  has no node with degree less than  $K$  ;

//  $G$  is either empty or all of its nodes have degree  $\geq K$

// Spill

**if**  $G$  is not empty **then**

Take one node  $m$  out of  $G$ , and mark it for spilling;

Remove all the edges of  $m$  from  $G$ ;

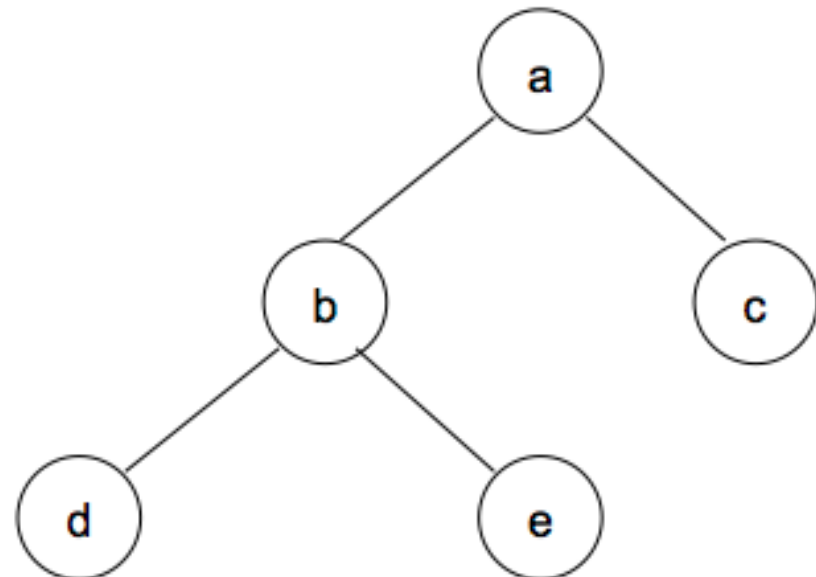
**end**

**until**  $G$  is empty ;

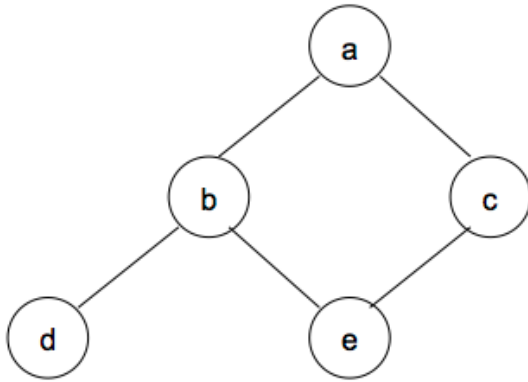
Take one node at a time from the stack and assign a non conflicting color.



## Example 1, available colors = 2



## Example 2



We have to spill.



## Graph coloring - Kempe's heuristic

- Algorithm dating back to 1879.

**Input:**  $G$  - the interference graph,  $K$  - number of colors

**repeat**

**repeat**

    Remove a node  $n$  and all its edges from  $G$ , such that degree of  $n$  is less than  $K$ ;

    Push  $n$  onto a stack;

**until**  $G$  has no node with degree less than  $K$  ;

  //  $G$  is either empty or all of its nodes have degree  $\geq K$

**if**  $G$  is not empty **then**

    Take one node  $m$  out of  $G$ .;

    push  $m$  onto the stack;

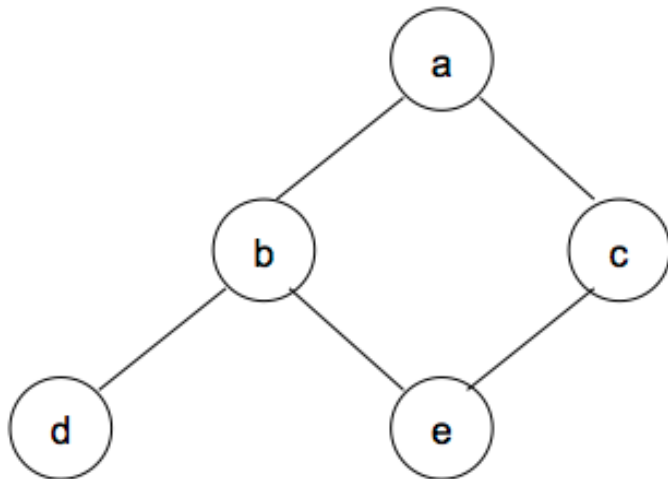
**end**

**until**  $G$  is empty ;

Take one node at a time from the stack and assign a non conflicting color (if possible, else spill).



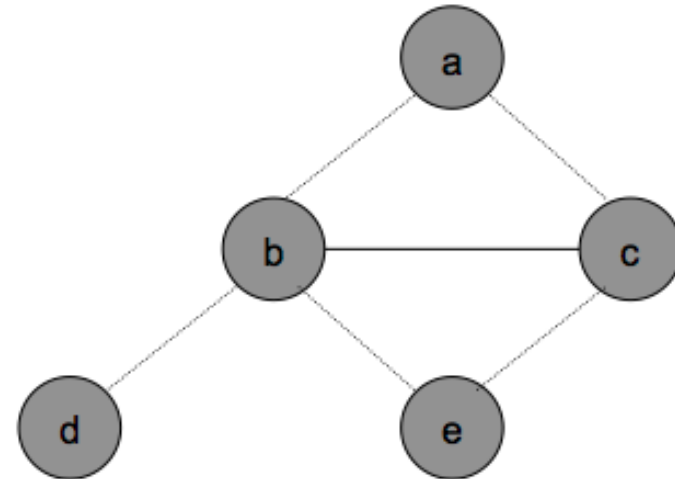
## Example 2 (revisited)



We don't have to spill.



## Example 3



Don't have a choice. Have to spill.



- We need to generate extra instructions to load variables from the stack and store them back.
- The load and store may require registers again:
  - Naive approach: Keep a separate register (wasteful).
  - Rewrite the code - by introducing a temporary; rerun the liveness + ra.  
(Note: the new temp has much smaller live range).



**Consider:** `add t1 t2`

- Suppose `t2` has to be spilled, say to `[sp-4]`.
- Invent a new temp `t35`, and rewrite:  
`mov t35 [sp-4] add t1 t35`
- `t35` has a very short live range and less likely to interfere.
- Now rerun the algo.



Register allocation is **expensive**.

- Many algorithms use heuristics for graph coloring.
- Allocation may take time quadratic in the number of live intervals.

### Not suitable

- Online compilers – need to generate code quickly. e.g. JIT compilers.
- Sacrifice efficient register allocation for compilation speed.

Linear scan register allocation - Massimiliano Poletto and Vivek Sarkar, ACM TOPLAS 1999

- Complexity linear in the number of variables (assuming the number of register is not too large).



- 1 Simplify
- 2 Spill
- 3 Select: assign colors to nodes
  - 1 start with empty graph and keep adding nodes:
  - 2 if adding a non-spill node – will have a color (basis for removal)
  - 3 if adding spill node and no color available (neighbors already K-colored) then mark as an actual spill; break;
  - 4 continue to select nodes.
- 4 Start over: if select has no actual spills then finished, otherwise
  - 1 rewrite code: fetch spills at use, store at definition
  - 2 recalculate liveness and repeat

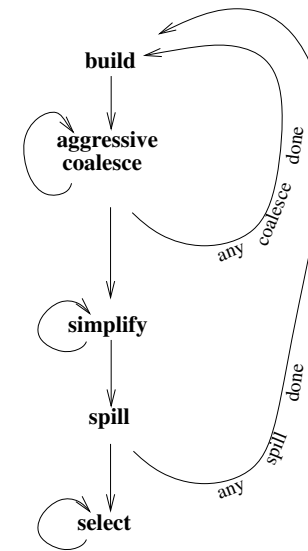


## Coalescing

- Can delete a move instruction when source  $s$  and destination  $d$  do not interfere:
  - coalesce them into a new node whose edges are the union of those of  $s$  and  $d$
- In principle, any pair of non-interfering nodes can be coalesced
  - unfortunately, the union is more constrained and new graph may no longer be  $K$ -colorable
  - overly aggressive



## Simplification with aggressive coalescing



## Conservative coalescing

Apply tests for coalescing that preserve colorability.

Suppose  $a$  and  $b$  are candidates for coalescing into node  $ab$ .

Briggs: coalesce only if  $ab$  has  $< K$  neighbors of significant degree  $\geq K$

- simplify first removes all insignificant-degree neighbors
- $ab$  will then be adjacent to  $< K$  neighbors
- simplify can then remove  $ab$

George: coalesce only if all significant-degree neighbors of  $a$  already interfere with  $b$

- simplify removes all insignificant-degree neighbors of  $a$
- remaining significant-degree neighbors of  $a$  already interfere with  $b$ ; coalescing does not increase degree of any node



## Iterated register coalescing

Interleave simplification with coalescing to eliminate most moves while guaranteeing not to introduce spills:

- 1 Build interference graph  $G$  and distinguish move-related from non-move-related nodes. A move-related node is one that is either the source or destination of a move instruction.
- 2 Simplify: remove non-move-related nodes of low degree one at a time
- 3 Coalesce: conservatively coalesce move-related nodes
  - remove associated move instruction
  - if resulting node is non-move-related it can now be simplified
  - repeat simplify and coalesce until only significant-degree or uncoalesced moves

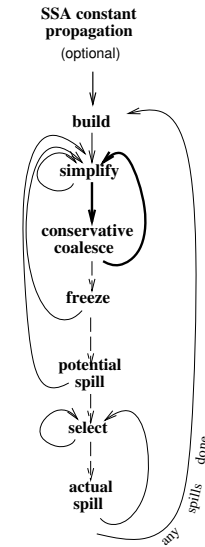


## Iterated register coalescing (cont.)

4. Freeze: if unable to simplify or coalesce
  - 1 look for move-related node of low-degree
  - 2 freeze its associated moves (give up on coalescing)
  - 3 now treat as non-move-related; resume iteration of simplify and coalesce
5. Spill: if no low-degree nodes
  - 1 select candidate for spilling
  - 2 remove to stack and continue simplifying
6. Select: pop stack assigning colors (with actual spills)
7. Start over: if select has no actual spills then finished, otherwise
  - 1 rewrite code: fetch spills before use, store after def
  - 2 recalculate liveness and repeat



## Iterated register coalescing



## Precolored nodes

Precolored nodes correspond to machine registers (e.g., stack pointer, arguments, return address, return value)

- select and coalesce can give an ordinary temporary the same color as a precolored register, if they don't interfere
- e.g., argument registers can be reused inside procedures for a temporary
- simplify, freeze and spill cannot be performed on them
- also, precolored nodes interfere with other precolored nodes

So, treat precolored nodes as having infinite degree

This also avoids needing to store large adjacency lists for precolored nodes; coalescing can use the George criterion



## Temporary copies of machine registers

Since precolored nodes don't spill, their live ranges must be kept short:

- 1 use move instructions
- 2 move callee-save registers to fresh temporaries on procedure entry, and back on exit, spilling between as necessary
- 3 register pressure will spill the fresh temporaries as necessary, otherwise they can be coalesced with their precolored counterpart and the moves deleted





# Criteria for spilling

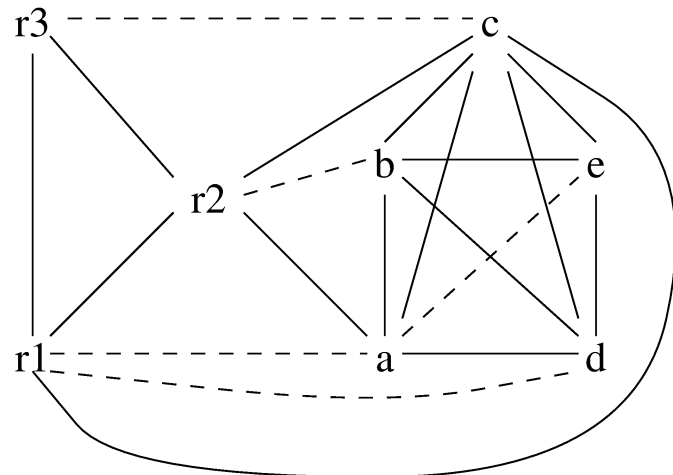
During register allocation, we identify that one of the live ranges from a given set, has to be spilled. Criteria?

- Random! Adv? Disadv?
- One with maximum degree
- One that has the longest life
- One with the shortest life (take advantage of the cache).
- One with least cost.
  - Cost = Dynamic (load cost + store cost)
  - How to handle loops, conditionals?
  - Cost of load, store



# Example (cont.)

Interference graph:



# Example

```

enter:
  c := r3
  a := r1
  b := r2
  d := 0
  e := a
loop:
  d := d + b
  e := e - 1
  if e > 0 goto loop
  r1 := d
  r3 := c
return [ r1, r3 live out ]
    
```

- Temporaries are a, b, c, d, e
- Assume target machine with  $K = 3$  registers: r1, r2 (caller-save/argument/result), r3 (callee-save)



explicitly by copying into temporary a and back

# Example (cont.)

- No opportunity for simplify or freeze (all non-precolored nodes have significant degree  $\geq K$ )
- Any coalesce will produce a new node adjacent to  $\geq K$  significant-degree nodes

- Must spill based on priorities:

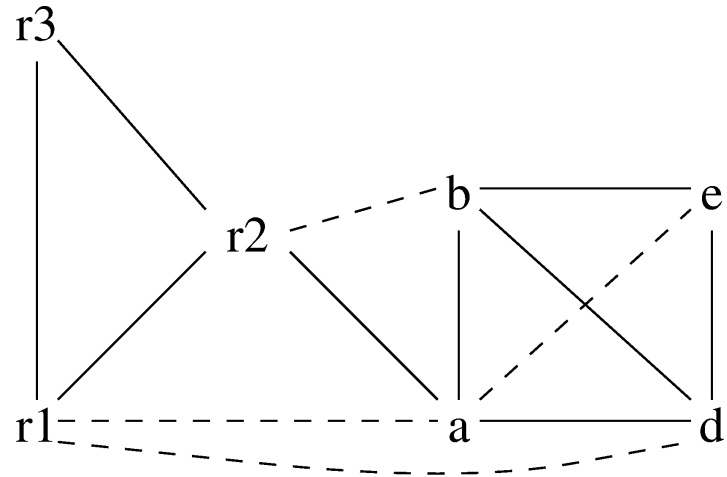
Node	uses + defs outside loop	uses + defs inside loop	degree	priority
a	( 2 +10x )	( 0 )	4	= 0.50
b	( 1 +10x )	( 1 )	4	= 2.75
c	( 2 +10x )	( 0 )	6	= 0.33
d	( 2 +10x )	( 2 )	4	= 5.50
e	( 1 +10x )	( 3 )	3	= 10.30

- Node c has lowest priority so spill it



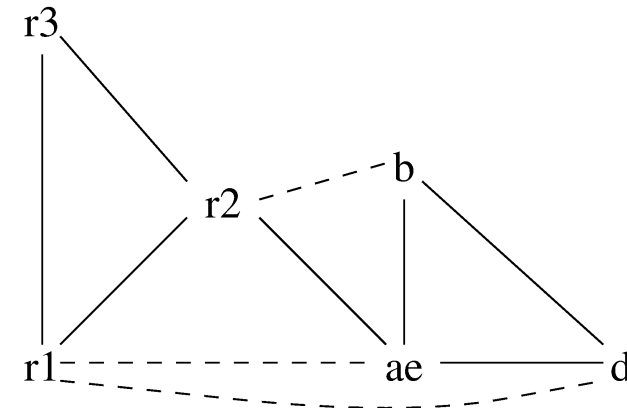
## Example (cont.)

Interference graph with  $c$  removed:



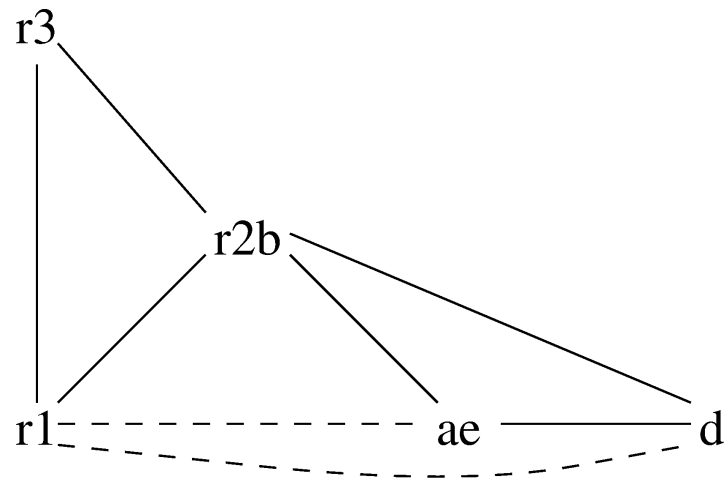
## Example (cont.)

Only possibility is to coalesce  $a$  and  $e$ :  $ae$  will have  $< K$  significant-degree neighbors (after coalescing  $d$  will be low-degree, though high-degree before)



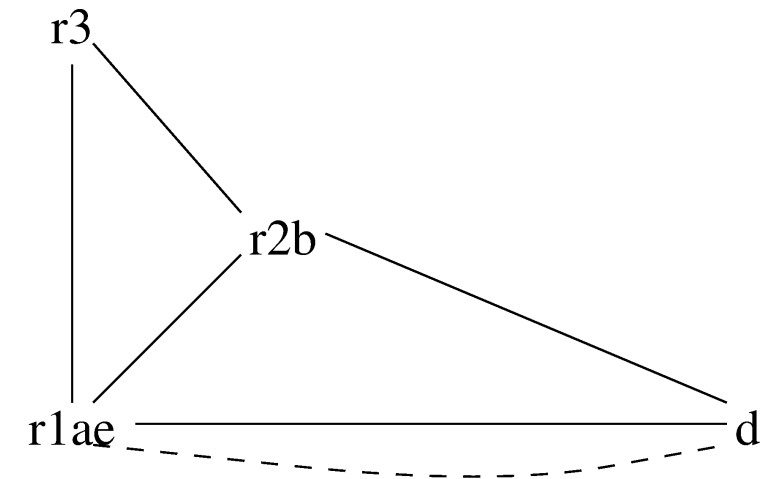
## Example (cont.)

Can now coalesce  $b$  with  $r2$  (or coalesce  $ae$  and  $r1$ ):



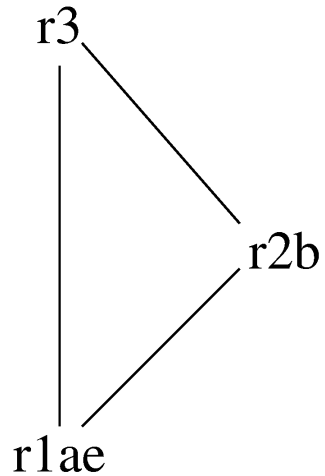
## Example (cont.)

Coalescing  $ae$  and  $r1$  (could also coalesce  $d$  with  $r1$ ):



## Example (cont.)

Cannot coalesce  $r1ae$  with  $d$  because the move is constrained: the nodes interfere. Must simplify  $d$ :



## Example (cont.)

- Graph now has only precolored nodes, so pop nodes from stack coloring along the way
  - $d \equiv r3$
  - $a, b, e$  have colors by coalescing
  - $c$  must spill since no color can be found for it
- Introduce new temporaries  $c1$  and  $c2$  for each use/def, add loads before each use and stores after each def



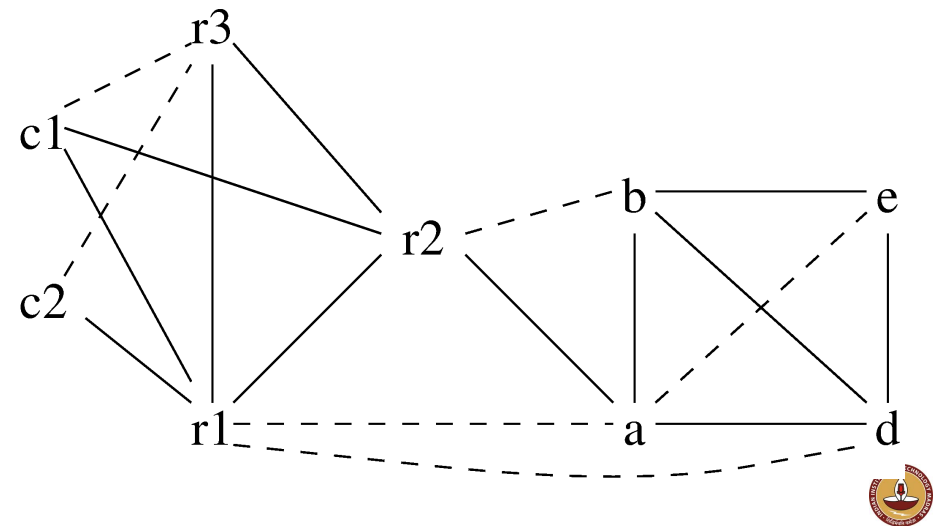
## Example (cont.)

```
enter:
  c1 := r3
  M[c_loc] := c1
  a := r1
  b := r2
  d := 0
  e := a
loop:
  d := d + b
  e := e - 1
  if e > 0 goto loop
  r1 := d
  c2 := M[c_loc]
  r3 := c2
return [ r1, r3 live out ]
```



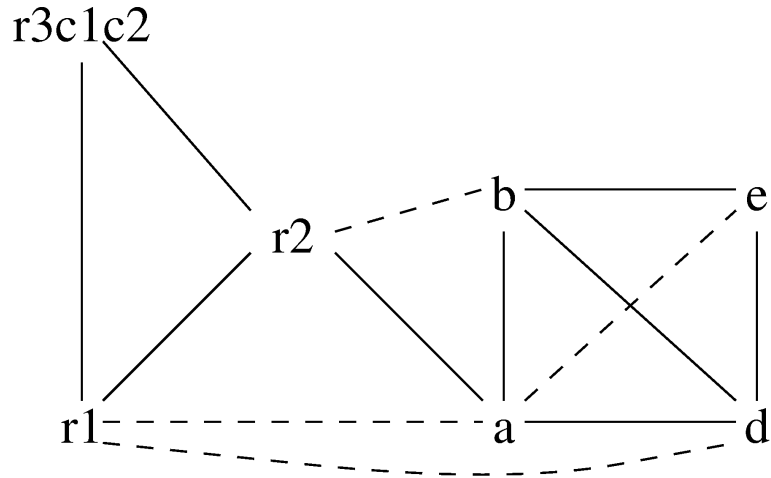
## Example (cont.)

New interference graph:



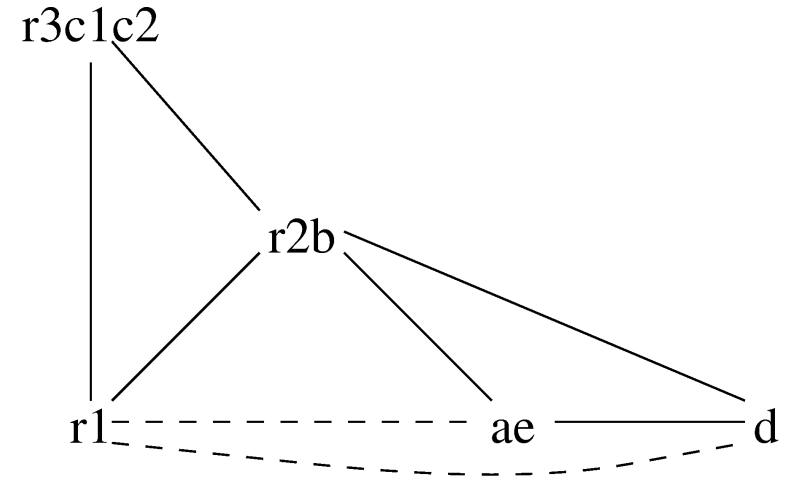
## Example (cont.)

Coalesce  $c_1$  with  $r_3$ , then  $c_2$  with  $r_3$ :



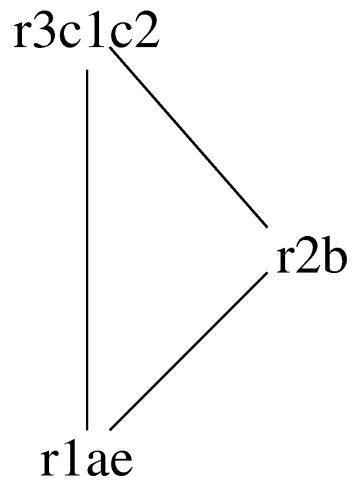
## Example (cont.)

As before, coalesce  $a$  with  $e$ , then  $b$  with  $r_2$ :



## Example (cont.)

As before, coalesce  $ae$  with  $r_1$  and simplify  $d$ :



## Example (cont.)

Pop  $d$  from stack: select  $r_3$ . All other nodes were coalesced or precolored. So, the coloring is:

- $a \equiv r_1$
- $b \equiv r_2$
- $c \equiv r_3$
- $d \equiv r_3$
- $e \equiv r_1$



## Example (cont.)

Rewrite the program with this assignment:

```
enter:
  r3 := r3
  M[c_loc] := r3
  r1 := r1
  r2 := r2
  r3 := 0
  r1 := r1
loop:
  r3 := r3 + r2
  r1 := r1 - 1
  if r1 > 0 goto loop
  r1 := r3
  r3 := M[c_loc]
  r3 := r3
return [ r1, r3 live out ]
```



## Example (cont.)

- Delete moves with source and destination the same (coalesced):

```
enter:
  M[c_loc] := r3
  r3 := 0
loop:
  r2 := r3 + r2
  r1 := r1 - 1
  if r1 > 0 goto loop
  r1 := r3
  r3 := M[c_loc]
return [ r1, r3 live out ]
```

- One uncoalesced move remains

