Recap

CS6848 - Principles of Programming Languages Principles of Programming Languages

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- Type rules.
- Simply typed lambda calculus.
- Type soundness proof.

Recursive types

- A data type for values that may contain other values of the same type.
- Also called inductive data types.
- Compared to simple types that are finite, recursive types are not.

```
interface I {
   void s1(boolean a);
   int m1(J a);
}
interface J {
   boolean m2(I b);
}
```

• Infinite graph.



Recursive types

- Can be viewed as directed graphs.
- Useful for defining dynamic data structures such as Lists, Trees.

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• Size can grow in response to runtime requirements (user input); compare that to static arrays.



Equality and subtyping

- In Java two types are considered equal iff they have the same name. Tricky example?
- Same with subtyping.
- Contrast the name based subtyping to structural subtyping.
- Why is structural subtyping interesting?

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Type derivation example

- Type of the lambda term $\lambda x.xx$.
- Use a type $u = \mu \alpha . (\alpha \rightarrow \text{Int})$.

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Grammar for recursive types

- We will extend the grammar of our simple types.
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 $t ::= t_1 \to t_2 | \text{Int} | \alpha | \mu \alpha. (t_1 \to t_2)$

where

- α is a variable that ranges over types.
- $\mu \alpha . t$ is a recursive type that allows unfolding.

 $\mu\alpha.t = t[\alpha := (\mu\alpha.t)]$

• Example: Say $u = \mu \alpha . (\alpha \rightarrow \text{Int})$. Now unfold

• Once:
$$u = u \rightarrow Int$$

• Twice:
$$u = (u \rightarrow Int) \rightarrow Int$$

- ...
- Infinitely: Infinite tree the type of *u*.
- A type derived from this grammar will have finite number of *distinct* subtrees *regular* trees.
- Any regular tree can be written as a finite expression using μ s.

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Type derivation, example II

- $Y = \lambda f.(\lambda x.f(xx))(\lambda x.f(xx))$
- Y-combinator is also called fixed point combinator or paradoxical combinator.
- When applied to any function g, it produces a fixed point of g.
- That is Y(E) = E(Y(E))
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 $Y(E) =_{\beta} (\lambda x.E(xx))(\lambda x.E(xx))$ $=_{\beta} E((\lambda x.E(xx))(\lambda x.E(xx)))$ $=_{\beta} E(Y(E))$

Useless assignment: For the factorial function $F = \lambda f . \lambda n. if (zero? n) 1 (mult n (f pred n)), show that<math>(Y F) n$ computes factorial n.Use the definition of factorial function:Fact n = if (zero? n) 1 (mult n (Fact (pred n))) Ueless assignment II:Write the Y combinator in Scheme.VKrishna Nandivada (IIT Madras)CS6848 (IIT Madras)

Type derivation of Y-combinator

- Y combinator cannot be typed with simple types.
- Use a type $u = \mu \alpha . (\alpha \rightarrow \text{Int})$.
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$$\phi[f:Int \to \text{Int}] \vdash (\lambda x.f(xx))(\lambda x.f(xx)):\text{Int}$$

$$\phi \vdash \lambda f.(\lambda x.f(xx))(\lambda x.f(xx)):(\text{Int} \to \text{Int}) \to \text{Int})$$

- If we can get the type of $\lambda x f(xx)$ to be type u then using $u = u \rightarrow \text{Int}$ like above, we can get the premise.
- Goal $\phi[f: \text{Int} \rightarrow \text{Int}] \vdash \lambda x.f(xx): u$
- $$\begin{split} \phi[f: \mathsf{Int} \to int][x:u] \vdash f: \mathsf{Int} \to \mathsf{Int} \quad \phi[x:u] \vdash xx: \mathsf{Int} \\ \hline \phi[f: \mathsf{Int} \to \mathsf{Int}][x:u] \vdash f(xx): \mathsf{Int} \\ \hline \phi[f: \mathsf{Int} \to \mathsf{Int}] \vdash \lambda x: u.f(xx): u \end{split}$$
- Not all terms can be typed with recursive types either: $\lambda x.x(\operatorname{succ} x)$
- Type soundness theorem can be proved for recursive types as well.

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Representation of types - as functions

- Denote an alphabet Σ that contains all the labels and paths of the type tree.
- We can represent such a tree by a function that maps paths to labels — called a term.
- Say we denote *left* by 0 and *right* by 1, for the types discussed before: path $\in \{0,1\}^*$.
- And the labels are from the set $\Sigma = \{ \text{Int}, \rightarrow \}$.
- A term t over Σ is a partial function

$$t: \{0,1\}^* \to \Sigma$$

- The domain D(t) must satisfy:
 - D(t) is non-empty and is prefix-closed.

• if
$$t(\alpha) = \rightarrow$$
 then $\alpha 0, \ \alpha 1 \in D(t)$.



Equality of types

- Isorecursive types: $\mu \alpha t$ and $t[\alpha/\mu \alpha t]$ are distinct (disjoint) types.
- Equirecursive types: Type type expessions are same if their infinite trees match.
 - Direct comparison is not enough.
 - Convert a given type into a canonical (normal/standard) form and then compare.



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Types as functions (contd)

Example.





- A term over Σ is a partial function: $t: w^* \to \Sigma$
- Define a new partial function $t \downarrow \alpha$:

• $t \downarrow \alpha(\beta) = t(\alpha\beta)$.

- A term t is finite if its domain D(t) is a finite set - finite types
- If $t \downarrow \alpha$ has non empty domain \Rightarrow it is a term and is called the subterm of t at position α .
- t is regular if it has only finitely many distinct subterms. That is, $\{t \downarrow \alpha | \alpha \in w^*\}$ is a finite set.
- A term t is regular \equiv it represents a recursive type.



Types as automata

If *t* is a term then following are equivalent:

- t is regular.
- t is representable by a term automata
- t is describable by a type expression involving μ .



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(reflexive) $t \leq t$

transitive $\frac{t_1 \le t_2 \quad t_2 \le t_3}{t_1 \le t_3}$

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Arrow
$$\frac{t_1 \le s_1 \quad s_2 \le t_2}{s_1 \to s_2 \le t_1 \to t_2}$$

- The subtype relation is reversed (contravariant) for the argument types.
- The subtype relation in the result types covariant.

Subtyping

- We want to denote that some types are more informative than other.
- We say $t_1 \le t_2$ to indicate that every value described by t_1 is also describled by t_2 .
- That is, if you have a function that needs a value of type *t*₂, you can give safely pass a value of type t_1 .
- t_1 is a subtype of t_2 or t_2 is a super type of t_1 .
- Example: C++ and Java.
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subsumption
$$A \vdash e: t \quad t \leq t'$$

 $A \vdash e: t'$

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Special types

- $(Top)t \leq \top$ • T = Java Object class.
- \perp = Subtype of all the classes undefined type.
 - (lambda (x) (zero? x) 4 (error # mesg))

•
$$t = \text{Int} |\perp| \top |t \to t| v |\mu v.(t \to t)$$



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Subtyping algorithm for recursive types

- Roberto M Amadio. and Luca Cardelli. Subtyping recursive types. In ACM Symposium on Principles of Programming Languages, 1990. - self reading.
- Dexter Kozen, Jens Palsberg, and Michael I. Schwartzbach. Efficient recursive sub-typing. In ACM Symposium on Principles of Programming Languages, 1993.

Parity

- The partiy of $\alpha \in \{0,1\}^*$ is even if α has even number of zeros.
- The partiy of $\alpha \in \{0,1\}^*$ is odd if α has odd number of zeros.
- Denote parity of α by $\pi \alpha = 0$ if even, 1 if odd.
- We will definte two orders.
 - co-variant: $\bot \leq_0 \top$
 - contra-variant: $\top \leq_1 \bot$



- Two trees are ordered if no common path detects a counter example.
- For finite types, we can compare all the paths (*cost?*) in the tree For recursive types?

Recap product autoamta

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• A prduct automata represents interaction between two finite state machines.

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If we start from A,C and after the word w we are in the state A,D we know that w contains an even number of $p_0{\rm s}$ and odd number of $p_1{\rm s}$

Slide from Thierry Coquand @ University of Gothenburg

Modified product automata

- Given two term automata *M* and *N*, we will construct a product automata (non-deterministic?)
 - $A = (Q^{A}, \Sigma, q_{0}^{A}, \delta^{A}, F^{A})$ where $Q^{A} = Q^{M} \times Q^{N} \times \{0, 1\}$ $\Sigma = \{0, 1\}$ $q_{0}^{A} = (q_{0}^{M}, q_{0}^{N}, 0) \text{start state of } A.$ $\delta^{A} : Q^{A} \times \Sigma \to Q^{A}.$ For $b, i \in \Sigma, p \in Q^{M}$, and $q \in Q^{N}$,
 we have $\delta^{A}((p, q, b), i) = (\delta^{M}(p, i), \delta^{N}(q, i), b \oplus \pi i)$ $(\oplus = \text{xor})$ Final states
 Recall: $s \not\leq t$ iff $\{\alpha \in D(s) \cap D(t) | s(\alpha) \not\leq_{\pi\alpha} t(\alpha)\}$ Goal: create an automata, where final states are denoted by states that will lead to \leq .

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 $F^A = \{(p,q,b) | l^M(p) \leq_b l^N(q)\} - l$ gives the label of that node.

Example 0

• $(\bot \to \top)$ and $(\top \to \bot) \not\leq$ • $((\bot \to \top) \to (\bot)$ and $((\top \to \bot) \to (\bot) \leq$



Input: Two types *s*, *t*.

Output: If $s \le t$.

- Construct the term automata for s and t.
- 2 Construct the product automaton $s \times t$. Size = ?
- Obcide, using depth first search, if the product automaton accepts the nonempty set.
 - Does there exist a path from the start state to some final state?
- If yes, then $s \not\leq t$. Else $s \leq t$.

Compute the time complexity - $O(n^2)$



Example 1

• $\mu v.(v \rightarrow \bot)$ and $\mu u.(u \rightarrow \top)$

Term automata







- Unreachable states $((\rightarrow_V, \top, 1)), (\rightarrow_V, \top, 0), (\perp, \rightarrow u, 1), ((\perp, \rightarrow u, 0)),$
- μν.(v→⊥) ≤ μu.(u→⊤)
 Note: Some of the unreachable states are ((final))

Example 2

• $\mu u.((u \rightarrow u) \rightarrow \bot)$ and $\mu v.((v \rightarrow \bot) \rightarrow \top)$

Term automata



First order unification

- Goal: To do type inference
- Given: A set of variables and literals and their possible types.
 - Remember: type = constraint.
- Target: Does the given set of constraints have a solution? And if so, what is the most general solution?
- Unification can be done in linear time: M. S. Paterson and M. N. Wegman, Linear Unification, Journal of Computer and System Sciences, 16:158167, 1978.
- We will instead present a simpler to understand, complex to run algorithm.

Type inference

- Goal: Given a program with some types.
- Infer "consistent" types of all the expressions in the program.

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Definitions

• We will stick to simple type experssions generated from the grammar:

$$t ::= t \rightarrow t | \text{Int} | \alpha$$

where α ranges over type variables.

• Type substitution, example:

$$((\mathsf{Int} \ o lpha) \, o eta)[lpha:=\mathsf{Int} \ ,eta:=(\mathsf{Int} \ o \mathsf{Int} \)]=(\mathsf{Int} \ o \mathsf{Int} \) o (\mathsf{Int} \ o \mathsf{Int} \)$$

$$((\mathsf{Int} \ \to \alpha) \to \gamma)[\alpha := \mathsf{Int} \ , \beta := (\mathsf{Int} \ \to \alpha)] = (\mathsf{Int} \ \to \mathsf{Int} \) \to \gamma$$

- We say given a set of type equations, we say a substitution σ is an *unifier or* solution if for each of the equation of the form s = t, $s\sigma = t\sigma$.
- Substituions can be composed:

 $t(\sigma \circ \theta) = (t\sigma)\theta$

A substitution σ is called a most general solution of an equation set provided for any other solution θ, there exists a substituon τ such that θ = σ ο τ

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Unification algorithm

Input: G: set of type equations (derived from a given program). **Output**: Unification σ

- failure = false; $\sigma = \{\}$.
- 2 while $G \neq \phi$ and \neg failure do
 - Choose and remove an equation *e* from G. Say $e\sigma$ is (s = t).
 - 2 If s and t are variables, or s and t are both Int then continue.
 - **3** If $s = s_1 \rightarrow s_2$ and $t = t_1 \rightarrow t_2$, then $G = G \cup \{s_1 = t_1, s_2 = t_2\}$.
 - If (s = Int and t is an arrow type) or vice versa then failure = true.
 - **6** If *s* is a variable that does not occur in *t*, then $\sigma = \sigma o [s := t]$.
 - **6** If *t* is a variable that does not occur in *s*, then $\sigma = \sigma o[t := s]$.
 - If s ≠ t and either s is a variable that occurs in t or vice versa then failure = true.

end-while.

• if (failure = true) then output "Does not type check". Else o/p σ .

Q:	Cor	mposability helps?
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Q: Cost?
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Recap

Examples

 $egin{array}{lll} lpha = eta
ightarrow {
m Int} \ eta = {
m Int}
ightarrow {
m Int} \ lpha = {
m Int}
ightarrow {
m Int} \ lpha = {
m Int}
ightarrow eta \end{array}$

 $\beta = \alpha \rightarrow \text{Int}$

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- Structural subtyping
- Unification algorithm



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