

$$Aw = \begin{bmatrix} x_1^T w \\ \vdots \\ x_n^T w \end{bmatrix} \quad Y = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}$$

$$Aw - Y = \begin{bmatrix} x_1^T w - y_1 \\ \vdots \\ x_n^T w - y_n \end{bmatrix}$$

$$(Aw - Y)^T (Aw - Y) = \sum_{i=1}^n (x_i^T w - y_i)^2 = 2J(w)$$

$$\nabla_w J(w) = \frac{1}{2} \nabla_w (Aw - Y)^T (Aw - Y) = A^T (Aw - Y)$$

$$\text{So, } \nabla J(w) = 0 \Leftrightarrow (A^T A)w = A^T Y$$

$$\text{Can we write } w = (A^T A)^{-1} A^T Y ?$$

Yes, if A is full rank.

since full rank $A \Rightarrow A^T A$ is invertible

(Why? argue $\text{rank}(A) = \text{rank}(A^T A)$ by showing $N(A) = N(A^T A)$)

Augmented features: $\{(\tilde{x}_i, y_i), i=1, \dots, n\}$ $\tilde{x}_i \in \mathbb{R}^d$

$$\tilde{x}_i = (1, \overleftarrow{x_i} \rightarrow)$$

$$f(x) = \sum_{i=1}^d w_i x_i + w_0 = \underbrace{w^T}_{\substack{\uparrow \\ \text{d-dimensional objects}}} \underbrace{\tilde{x}}_{\substack{\uparrow \\ \text{d-dimensional objects}}} + w_0$$

Why w_0 ?

$$J(w) = \frac{1}{2} \sum_{i=1}^n (w^T \tilde{x}_i + w_0 - y_i)^2$$

Take partial derivative w.r.t w_0

$$\frac{\partial J}{\partial w_0} = 0$$

$$\sum_{i=1}^n (w^T \tilde{x}_i + w_0 - y_i) = 0$$

Simplify, $w_0 = \frac{1}{n} \sum_{i=1}^n y_i - w^T \left(\sum_{i=1}^n \tilde{x}_i \right)$

Polynomial regression:

$$d=1, \quad \{ (x_i, y_i), i=1 \dots n \} \quad x_i, y_i \in \mathbb{R}$$

Use transformed features, i.e.,

the following model

$$\hat{y}(x) = w_0 + w_1 x + w_2 x^2 + \dots + w_m x^m$$

mth degree polynomial

features \leftarrow polynomial basis.

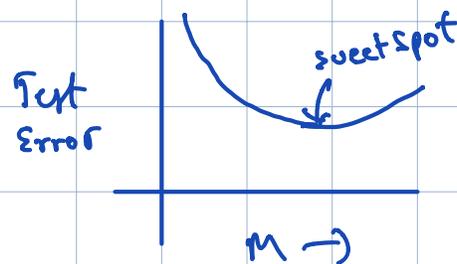
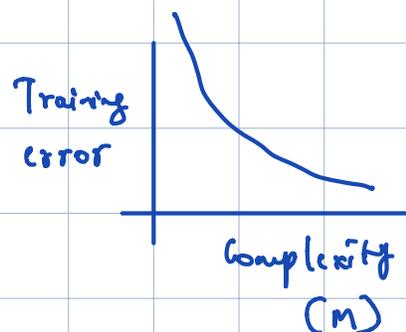
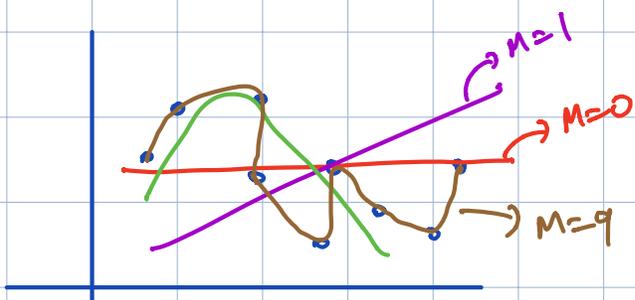
$$\hat{y}(x) = \sum_{j=0}^m w_j \phi_j(x), \quad \phi_j(x) = x^j$$

$$= \omega^T \phi(x)$$

$$\omega = (\omega_0, \dots, \omega_m)$$

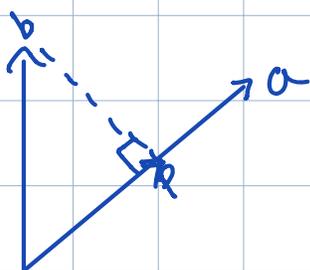
$$\begin{aligned} \phi(x) &= (\phi_0(x), \dots, \phi_m(x)) \\ &= (1, x, x^2, \dots, x^m) \end{aligned}$$

Alternatively, $\phi_j(x) = \exp\left(-\frac{(x-\mu_j)^2}{2\sigma^2}\right) \leftarrow$ Gaussian basis



Least-squares: Geometric viewpoint

Recap of projections:-



$$p = \hat{x} a$$

$$(b - \hat{x} a) \perp a$$

$$a^T (b - \hat{x}a) = 0$$

$$\hat{x} = \frac{a^T b}{a^T a}$$

$$p = \hat{x}a = \left(\frac{a^T b}{a^T a} \right) a$$

$$= a \frac{a^T b}{a^T a} = \left[\frac{1}{a^T a} (a a^T) \right] b$$

Projection matrix

$$P = \frac{1}{a^T a} a a^T$$

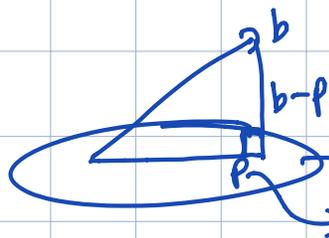
Projection matrix is (i) symmetric

(ii) $P^2 = P$

Project onto a subspace:

A is a $m \times n$ -matrix.

Want: Project b onto $\text{Col}(A)$



$\text{Col}(A) = \text{span}(\text{columns of } A)$

$$p = A \hat{x}$$

$$e = b - p = b - A \hat{x}$$

$e \perp$ every vector in $\text{Col}(A)$

$\Rightarrow c \in N(A^T)$ because $N(A^T) \perp C(A)$

$$A^T (b - A\hat{x}) = 0$$

$$A^T A \hat{x} = A^T b$$

observe $A = \begin{bmatrix} | & & | \\ a_1 & \dots & a_n \\ | & & | \end{bmatrix}$

$$a_1^T (b - A\hat{x}) = 0$$

\vdots

$$a_n^T (b - A\hat{x}) = 0$$

$$\begin{bmatrix} a_1^T \\ \vdots \\ a_n^T \end{bmatrix} [b - A\hat{x}] = 0$$

$$A^T (b - A\hat{x}) = 0$$

So, $A^T A \hat{x} = A^T b$ & this minimizes

$$E = \|Ax - b\|^2$$

If A is full col-rank, then

$$\hat{x} = (A^T A)^{-1} A^T b$$

Projection $p = A\hat{x} = A(A^T A)^{-1} A^T b$

Example:-

$$\begin{bmatrix} -1 & 1 \\ 1 & 1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} \theta' \\ \theta'' \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix}$$

Want to solve $A\theta = b$

Check if b is in $C(A)$.

$$\left[\begin{array}{cc|c} -1 & 1 & 1 \\ +1 & 1 & 1 \\ 2 & 1 & 3 \end{array} \right] \rightarrow \dots \rightarrow \left[\begin{array}{cc|c} 1 & -1 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 2 \end{array} \right]$$

↑
inconsistent system

So $b \notin C(A)$.

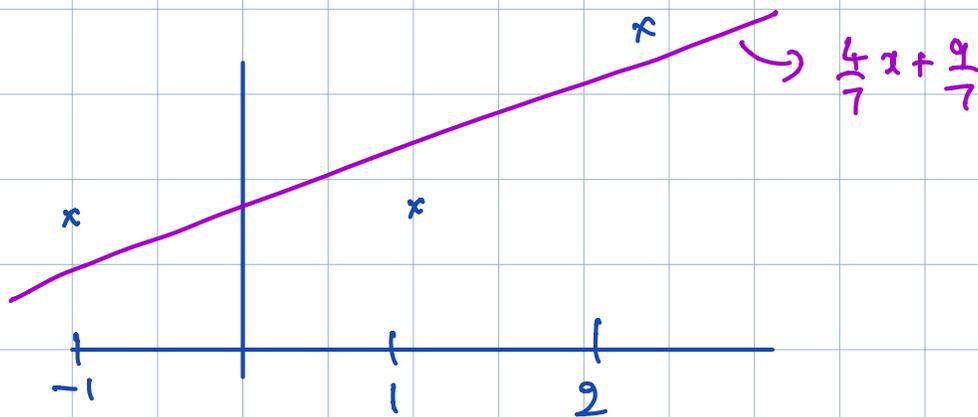
Least-squares: $A^T A \hat{\theta} = A^T b$

$$A^T A = \begin{bmatrix} 6 & 2 \\ 2 & 3 \end{bmatrix}$$

$$\begin{bmatrix} 6 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} \hat{\theta}^1 \\ \hat{\theta}^2 \end{bmatrix} = \begin{bmatrix} 6 \\ 5 \end{bmatrix}$$

$$\hat{\theta}^1 = \frac{6}{7}$$

$$\hat{\theta}^2 = \frac{9}{7}$$



$$P_1 = \frac{6}{7}, \quad P_2 = \frac{13}{7}, \quad P_3 = \frac{17}{7}$$

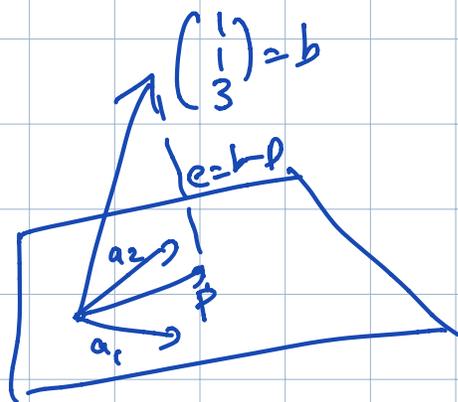
$$E^2 = \|b - A\hat{\theta}\|^2$$

$$= \left[1 - \left(-\frac{4}{7} + \frac{9}{7} \right) \right]^2 +$$

$$+ \left[1 - \left(\frac{4}{7} + \frac{9}{7} \right) \right]^2 + \left[3 - \left(\frac{8}{7} + \frac{9}{7} \right) \right]^2$$

$$= + \frac{2}{7}$$

$$e = b - p = \left(\frac{2}{7}, -\frac{6}{7}, \frac{4}{7} \right)$$



$$e \perp \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix}$$

" a_1

$$e \perp \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

" a_2

BIAS-VARIANCE TRADEOFF

$f(\cdot)$ \rightarrow predictor i.e., $f(x)$ is the prediction for input feature x , & y is the target
 Suppose (x, y) are chosen using some distribution D .
 Then, the expected loss or the "risk" is

$$R(f) = E \left((f(x) - y)^2 \right)$$

↙ over x, y

Claim: $f^*(x) = E[y|x]$ is the best predictor,
ie., f^* minimized $R(f)$.

Pf: $E \left((f(x) - y)^2 \right)$

$$= E \left[\left(f(x) - E[y|x] + E[y|x] - y \right)^2 \right]$$

$$(*) \quad E \left((f(x) - y)^2 \right) = E \left(f(x) - E[y|x] \right)^2 + E \left[\left(E[y|x] - y \right)^2 \right]$$

↑
predictor f present only in this term

noise term ←

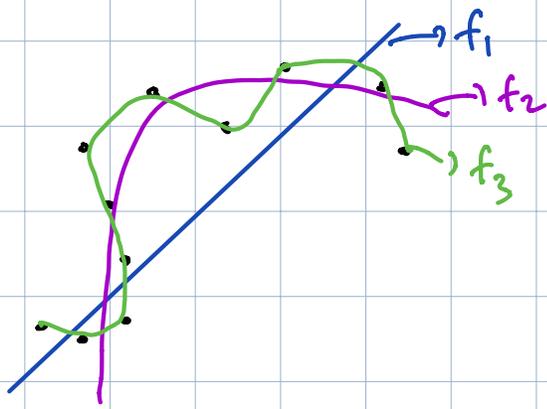
(*) is minimized for $f = E[y|x]$ ▣

In a typical ML setting, $R(f)$ cannot be evaluated for a given f , since the underlying distributions are unknown.

So, collect training data $\{ (x_i, y_i), i=1 \dots n \}$

sampled iid from \mathcal{D} , and minimize

Empirical risk $\rightarrow R_n(f) = \frac{1}{n} \sum_{i=1}^n (f(x_i) - y_i)^2$



Intuitively,

f_1 is very simple

f_3 is very accurate

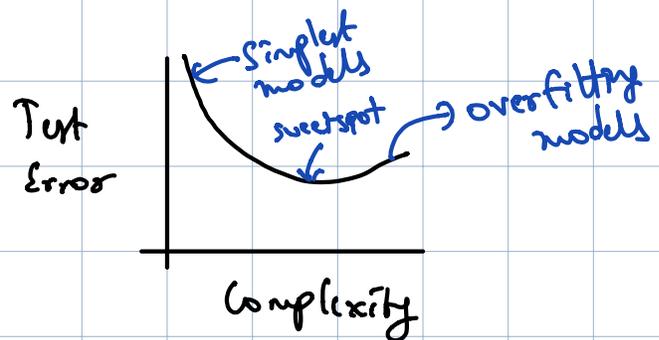
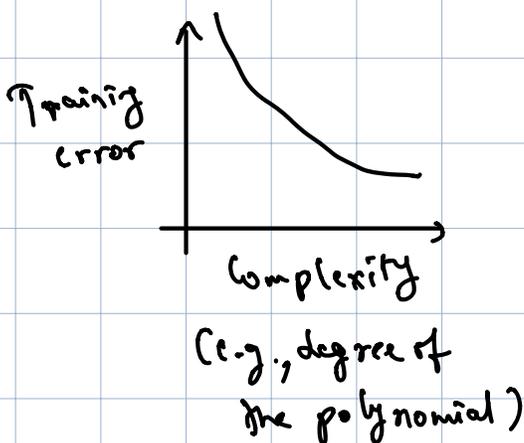
Maybe f_2 is the right fit

So, it is not enough to use $R_n(f)$ to judge f , since f_3 minimizes $R_n(f)$ (& fits noise). This phenomenon is referred to as "overfitting".

or generalization

$$\text{Test error for } f = \frac{1}{m} \sum_{i=1}^m (\bar{y}_i - f(\bar{x}_i))^2, \text{ where}$$

$\{(\bar{x}_i, \bar{y}_i), i=1 \dots m\}$ is the test data generated using distribution \mathcal{D} (used for generating training data as well).



Goal:

$$\min_f E((f_D(x) - y)^2)$$

$f_D(\cdot) \rightarrow$ predictor learnt using some dataset D .

$$E((f_D(x) - y)^2)$$

$$= E((f_D(x) - E(y|x))^2) + E((E(y|x) - y)^2)$$

\downarrow
(I)

\uparrow
noise term
(unavoidable)

$$(I) = E((f_D(x) - E(y|x))^2)$$

$$= E\left[(f_D(x) - E_D(f_D(x)))^2\right]$$

$$+ 2(f_D(x) - E_D(f_D(x)))(E_D(f_D(x)) - E(y|x))$$

$$E_D(f_D(x)) = E(f_D(x)|x)$$

Fix x &
average over
many datasets,
say D_1, D_2, \dots

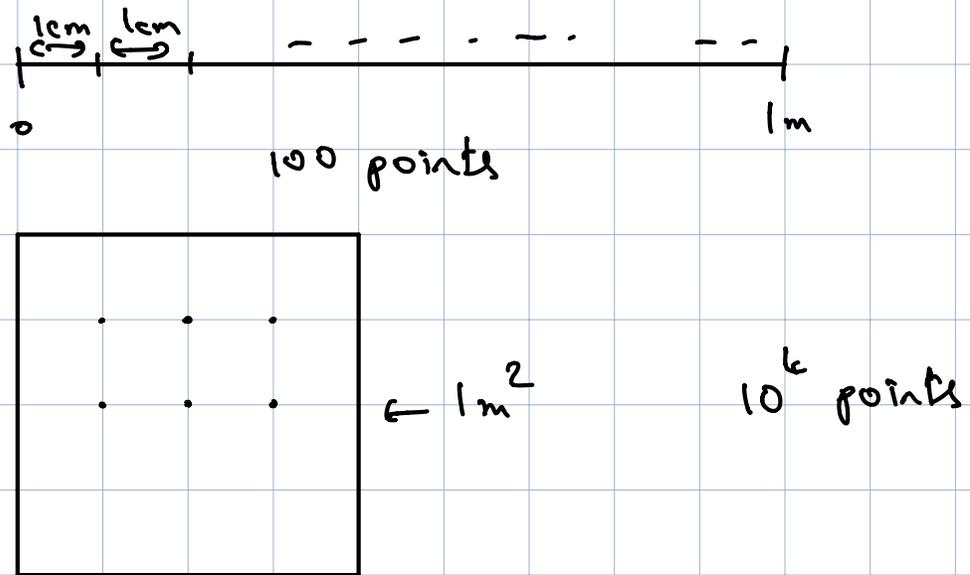
$$= E\left[(f_D(x) - E_D(f_D(x)))^2\right] \rightsquigarrow \text{Variance}$$

$$+ E\left[(E_D(f_D(x)) - E(y|x))^2\right] \rightsquigarrow (\text{Bias})^2$$

It is easy to see that as f grows complex, the bias decreases.

Claim: As f grows complex, variance increases.

"Curse of dimensionality".



points required to sample a unit hypercube grows exponentially with the dimension

$\min_{f \in \mathcal{F}_1} \hat{R}(f)$, $\min_{f \in \mathcal{F}_2} \hat{R}(f)$, ... & so on, where

$\mathcal{F}_i =$ set of all polynomials with degree at most i .

Vector of Co-efficients of a polynomial in \mathcal{F}_i sit in \mathbb{R}^{d+1}

With increasing i , one needs to explore more points to find the best f in \mathcal{F}_i

(OR)

Given a fixed # of points, the parameter space is explored less efficiently for higher order \mathcal{F}_i , leading to errors.

Regularized version of regression:- (Ridge regression)

$$\hat{R}_n(f) = \min_w \frac{1}{2} \sum_{i=1}^n (w^T x_i - y_i)^2 + \lambda \|w\|^2$$

Too small a $\lambda \rightarrow$ no effect of regularization
(overfit)

Too large a $\lambda \rightarrow$ under fit

Ref: Table 1.2

Illustration of bias-variance tradeoff for a linear model;

Consider the model $y = w^T x + \epsilon$, $\epsilon \sim N(0, \frac{1}{\beta})$

The ML estimate \hat{w}_{ML} for w , given $\mathcal{D} = \{(x_i, y_i), i=1, \dots, n\}$

$$\hat{w}_{ML} = (A^T A)^{-1} A^T Y, \text{ where}$$

$$A = \begin{pmatrix} x_1^T \\ \vdots \\ x_n^T \end{pmatrix}, \quad Y = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}, \quad \eta = \begin{pmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{pmatrix}$$

"Assume cols of A are linearly independent",

$$\begin{aligned}
 (a) \quad E(\hat{w}_{ML}) &= E((A^T A)^{-1} A^T Y) \\
 &= (A^T A)^{-1} A^T EY \\
 &= (A^T A)^{-1} A^T AW \\
 &= w.
 \end{aligned}$$

$$\begin{aligned}
 (b) \quad \text{Var}(\hat{w}_{ML}) &= E((\hat{w}_{ML} - w)(\hat{w}_{ML} - w)^T) \\
 &= E\left[((A^T A)^{-1} A^T Y - w)((A^T A)^{-1} A^T Y - w)^T \right] \\
 &= E\left[((A^T A)^{-1} A^T Y - w)(Y^T A (A^T A)^{-1} - w^T) \right] \\
 &= (A^T A)^{-1} A^T E[Y Y^T] A (A^T A)^{-1} - w w^T \\
 &= (A^T A)^{-1} A^T E\left[(Aw + \eta)(Aw + \eta)^T \right] A (A^T A)^{-1} \\
 &\quad - w w^T \\
 &= (A^T A)^{-1} A^T \left[A w w^T A^T + \frac{1}{\beta} I_{n \times n} \right] A (A^T A)^{-1} \\
 &\quad - w w^T \\
 &= w w^T + \frac{1}{\beta} (A^T A)^{-1} - w w^T \\
 &= \frac{1}{\beta} (A^T A)^{-1}
 \end{aligned}$$

(c) Bias-variance decomposition

$$\begin{aligned} & E \left((f_D(x) - y)^2 \right) \\ &= E_{xy} \left(\underbrace{(E(y|x) - y)^2}_{\text{noise}} \right) + E_x \left[\underbrace{\left(E_D(f_D(x)) - E(y|x) \right)^2}_{\text{bias}} \right] \\ &\quad + E \left(\underbrace{f_D(x) - E_D(f_D(x))}_{\text{variance}} \right)^2 \end{aligned}$$

for linear case, $f_D(x) = \hat{w}_{ML}^T x$

$$\text{Bias} = E_0(\hat{w}_{ML}^T x) - w^T x = 0 \quad (\text{from part (a)})$$

$$\text{Variance} = E \left((f_D(x) - E_0(f_D(x)))^2 \mid x \right)$$

Let $\tilde{E} = E(\cdot | x)$

$$= \tilde{E} \left((x^T \hat{w}_{ML} - x^T w)^2 \right)$$

$$= \tilde{E} \left((x^T (A^T A)^{-1} A^T y - x^T w)^2 \right)$$

$$= \tilde{E} \left((x^T (A^T A)^{-1} A^T (Aw + \eta) - x^T w)^2 \right)$$

$$= \tilde{E} \left((x^T w + x^T (A^T A)^{-1} A^T \eta - x^T w)^2 \right)$$

$$\begin{aligned}
&= E \left(x^T (A^T A)^{-1} A^T \eta \right)^2 \\
&= E \left(\left(x^T (A^T A)^{-1} A^T \eta \right) \left(x^T (A^T A)^{-1} A^T \eta \right)^T \right) \\
&= x^T (A^T A)^{-1} A^T \underbrace{E(\eta \eta^T)}_{= \frac{1}{\beta} I_{\text{non}}} \left(x^T (A^T A)^{-1} A^T \right)^T \\
&= \frac{1}{\beta} x^T (A^T A)^{-1} A^T A (A^T A)^{-1} x \\
&= \frac{1}{\beta} x^T (A^T A)^{-1} x
\end{aligned}$$

H.W.

① Let $C = A (A^T A)^{-1} A^T$

Show that C is a projection matrix, i.e., C is symmetric & $C^2 = C$

② Check if $(I - C)$ is a projection matrix

③ Let $S = \text{span}(\text{cols of } A)$. Show that, for any $z \in \mathbb{R}^d$, Cz is the projection of z onto S .

④ Show that $A \hat{w}_{\text{OLS}}$ is orthogonal to $y - A \hat{w}_{\text{OLS}}$.

H.W. Redo the exercise for a ridge regression-based

estimate \hat{w}_{reg} .

(i) Write out the expression for \hat{w}_{reg}

given $D = \{ (x_i, y_i), i=1, \dots, n \}$

(ii) $E(\hat{w}_{\text{reg}}), \text{Var}(\hat{w}_{\text{reg}})$

(iii) calculate the bias & variance components.