

Functions

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CUDA Function Declarations

	Executed on the:	Callable from only the:
<code>__device__ float DeviceFunc()</code>	device	device
<code>__global__ void KernelFunc()</code>	device	host
<code>__host__ float HostFunc()</code>	host	host

- `__global__` defines a kernel. It must return `void`.
- A program may have several functions of each kind.
- The same function of any kind may be called multiple times.
- Host == CPU, Device == GPU.

Function Types (1/2)

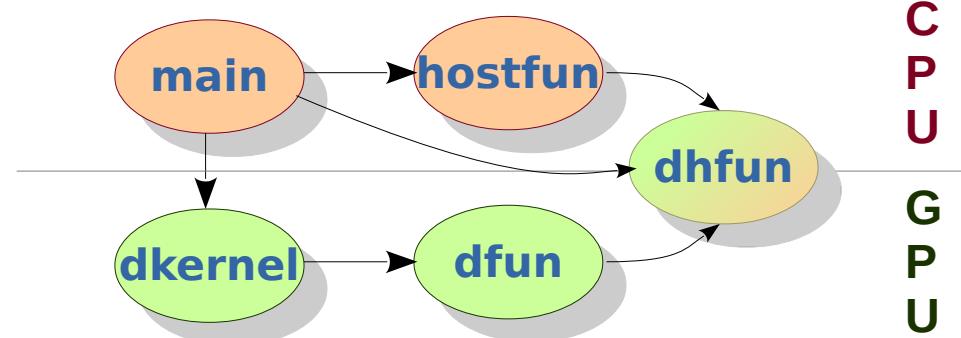
```
#include <stdio.h>
#include <cuda.h>
__host__ __device__ void dhfun() {
    printf("I can run on both CPU and GPU.\n");
}
__device__ unsigned dfun(unsigned *vector, unsigned vectorsize, unsigned id) {
    if (id == 0) dhfun();
    if (id < vectorsize) {
        vector[id] = id;
        return 1;
    } else {
        return 0;
    }
}
__global__ void dkernel(unsigned *vector, unsigned vectorsize) {
    unsigned id = blockIdx.x * blockDim.x + threadIdx.x;
    dfun(vector, vectorsize, id);
}
__host__ void hostfun() {
    printf("I am simply like another function running on CPU. Calling dhfun\n");
    dhfun();
}
```

Function Types (2/2)

```
#define BLOCKSIZE    1024
int main(int nn, char *str[]) {
    unsigned N = atoi(str[1]);
    unsigned *vector, *hvector;
    cudaMalloc(&vector, N * sizeof(unsigned));
    hvector = (unsigned *)malloc(N * sizeof(unsigned));

    unsigned nblocks = ceil((float)N / BLOCKSIZE);
    printf("nblocks = %d\n", nblocks);

dkernel<<<nblocks, BLOCKSIZE>>>(vector, N);
    cudaMemcpy(hvector, vector, N * sizeof(unsigned),
cudaMemcpyDeviceToHost);
    for (unsigned ii = 0; ii < N; ++ii) {
        printf("%4d ", hvector[ii]);
    }
    printf("\n");
hostfun();
dhfun();
    return 0;
}
```



What are the other arrows possible in this diagram?

with HostAlloc'ed Memory

`__host__ __device__`
functions are friends with
HostAlloc'ed memory.

```
__host__ __device__ void fun(int *counter) {
    ++*counter;
}

__global__ void printk(int *counter) {
    fun(counter);
    printf("printk (after fun): %d\n", *counter);
}

int main() {
    int *counter;
    cudaHostAlloc(&counter, sizeof(int), 0);

    *counter = 0;
    printf("main: %d\n", *counter);

    printk <<<1, 1>>>(counter);
    cudaDeviceSynchronize();

    fun(counter);
    printf("main (after fun): %d\n", *counter);

    return 0;
}
```

What is the
output of
this code?

with a Device-only Function

```
__host__ __device__ void fun(int *counter) {
    ++*counter;
    __syncthreads();
}

__global__ void printk(int *counter) {
    fun(counter);
    printf("printk (after fun): %d\n", *counter);
}

int main() {
    int *counter;
    cudaHostAlloc(&counter, sizeof(int), 0);

    *counter = 0;
    printf("main: %d\n", *counter);

    printk <<<1, 1>>>(counter);
    cudaDeviceSynchronize();

    fun(counter);
    printf("main (after fun): %d\n", *counter);

    return 0;
}
```

`__syncthreads()`
is not available
on CPU.

with a CPU-only Memory

```
__host__ __device__ void fun(int *counter) {
    ++*counter;
}

__global__ void printk(int *counter) {
    fun(counter);
    printf("printk (after fun): %d\n", *counter);
}

int main() {
    int *counter;
    // cudaHostAlloc(&counter, sizeof(int), 0);
    cudaMalloc(&counter, sizeof(int));

    *counter = 0;
    printf("main: %d\n", *counter);

    printk <<<1, 1>>>(counter);
    cudaDeviceSynchronize();

    fun(counter);
    printf("main (after fun): %d\n", *counter);

    return 0;
}
```

counter cannot
be accessed
on CPU.

Global Variables

```
int counter;

__host__ __device__ void fun() {
    ++counter;
}

__global__ void printk() {
    fun();
    printf("printk (after fun): %d\n", counter);
}

int main() {

    counter = 0;
    printf("main: %d\n", counter);

    printk <<<1, 1>>>();
    cudaDeviceSynchronize();

    fun();
    printf("main (after fun): %d\n", counter);

    return 0;
}
```

counter cannot
be accessed
on **GPU**.

Global Variables

```
__host__ __device__ int counter;  
  
__host__ __device__ void fun() {  
    ++counter;  
}  
__global__ void printf() {  
    fun();  
    printf("printf (after fun): %d\n", counter);  
}  
int main() {  
  
    counter = 0;  
    printf("main: %d\n", counter);  
  
    printf <<<1, 1>>>();  
    cudaDeviceSynchronize();  
  
    fun();  
    printf("main (after fun): %d\n", counter);  
  
    return 0;  
}
```

Variables
cannot be
declared as
`__host__`.

Global Variables

```
__device__ int counter;  
  
__host__ __device__ void fun() {  
    ++counter;  
}  
__global__ void printk() {  
    fun();  
    printf("printk (after fun): %d\n", counter);  
}  
int main() {  
  
    printk <<<1, 1>>>();  
    cudaDeviceSynchronize();  
  
    return 0;  
}
```

Warning during compilation,
but works fine.

Classwork

Write a CUDA code to increment all elements in an array. Call this code from host as well as device.

Homework: Can you avoid the for loop in **fun**?

```
__host__ __device__ void fun(int *arr) {
    for (unsigned ii = 0; ii < N; ++ii)
        ++arr[ii];
}

__global__ void dfun(int *arr) {
    fun(arr);
}

int main() {
    int arr[N], *darr;

    cudaMalloc(&darr, N * sizeof(int));

    for (unsigned ii = 0; ii < N; ++ii)
        arr[ii] = ii;
    cudaMemcpy(darr, arr, N * sizeof(int),
              cudaMemcpyHostToDevice);

    fun(arr);
    dfun<<<1, 1>>>(darr);
    cudaDeviceSynchronize();

    return 0;
}
```

Classwork: Pranav's idea

Write a CUDA code to increment all elements in an array. Call this code from host as well as device.

Homework: Can you avoid the for loop in **fun**?

```
__host__ __device__ void fun(int *arr, int nn) {
    for (unsigned ii = 0; ii < nn; ++ii)
        ++arr[ii];
}

__global__ void dfun(int *arr) {
    fun(arr + threadIdx.x, 1);
    // need to change for more blocks.
}

int main() {
    int arr[N], *darr;

    cudaMalloc(&darr, N * sizeof(int));

    for (unsigned ii = 0; ii < N; ++ii)
        arr[ii] = ii;
    cudaMemcpy(darr, arr, N * sizeof(int),
              cudaMemcpyHostToDevice);

    fun(arr, N);
    dfun<<<1, 1>>>(darr);
    cudaDeviceSynchronize();

    return 0;
}
```

Thrust

- Thrust is a parallel algorithms library (similar in spirit to STL on CPU).
- Supports vectors and associated transforms.
- Programmer is oblivious to where code executes – on CPU or GPU.
- Makes use of C++ features such as functors, and host device functions.

```
#include <thrust/host_vector.h>
#include <thrust/device_vector.h>
#include <iostream>
int main(void) {
    // H has storage for 4 integers
    thrust::host_vector<int> H(4);
    // initialize individual elements
    H[0] = 14; H[1] = 20; H[2] = 38; H[3] = 46;
    // H.size() returns the size of vector H
    std::cout << "H has size " << H.size() << std::endl;
    // print contents of H
    for(int i = 0; i < H.size(); i++) std::cout << "H[" << i << "] = " << H[i] << std::endl;
    // resize H
    H.resize(2);
    std::cout << "H now has size " << H.size() << std::endl;
    // Copy host_vector H to device_vector D
    thrust::device_vector<int> D = H;
    // elements of D can be modified
    D[0] = 99; D[1] = 88;
    // H and D are automatically deleted when the function returns
    return 0;
}
```

```
#include <thrust/host_vector.h>
#include <thrust/device_vector.h>
#include <thrust/copy.h>
#include <thrust/fill.h>
#include <thrust/sequence.h>
#include <iostream>

int main(void) {
    // initialize all ten integers of a device_vector to 1
    thrust::device_vector<int> D(10, 1);

    // set the first seven elements of a vector to 9
    thrust::fill(D.begin(), D.begin() + 7, 9);

    // initialize a host_vector with the first five elements of D
    thrust::host_vector<int> H(D.begin(), D.begin() + 5);

    // set the elements of H to 0, 1, 2, 3, ...
    thrust::sequence(H.begin(), H.end());

    // copy all of H back to the beginning of D
    thrust::copy(H.begin(), H.end(), D.begin());

    // print D
    for(int i = 0; i < D.size(); i++)
        std::cout << "D[" << i << "] = " << D[i] << std::endl;

    return 0;
}
```

Thrust Details

```
thrust::host_vector<int> hnums(1024);
thrust::device_vector<int> dnums;

dnums = hnums; // calls cudaMemcpy

// initialization.
thrust::device_vector<int> dnum2(hnums.begin(), hnums.end());
hnums = dnum2; // array resizing happens automatically.

std::cout << dnums[3] << std::endl;

thrust::transform(dsrc.begin(), dsrc.end(), dsr2.begin(),
                  ddst.begin(), addFunc);
```

Thrust Functions

- `find(begin, end, value);`
- `find_if(begin, end, predicate);`
- `copy, copy_if.`
- `count, count_if.`
- `equal.`
- `min_element, max_element.`
- `merge, sort, reduce.`
- `transform.`
- `...`

Thrust Algorithms

- Dual implementations: host and device
- Iterators as arguments must be on the same device
 - except *copy*, which can copy across devices
 - Otherwise, compiler issues error

```
#include <thrust/device_vector.h>
#include <thrust/transform.h>
#include <thrust/sequence.h>
#include <thrust/copy.h>
#include <thrust/fill.h>
#include <thrust/replace.h>
#include <thrust/functional.h>
#include <iostream>
int main(void) {
    // allocate three device_vectors with 10 elements
    thrust::device_vector<int> X(10);
    thrust::device_vector<int> Y(10);
    thrust::device_vector<int> Z(10);
    // initialize X to 0,1,2,3, ...
    thrust::sequence(X.begin(), X.end());
    // compute Y = -X
    thrust::transform(X.begin(), X.end(), Y.begin(), thrust::negate<int>());
    // fill Z with twos
    thrust::fill(Z.begin(), Z.end(), 2);
    // compute Y = X mod 2
    thrust::transform(X.begin(), X.end(), Z.begin(), Y.begin(), thrust::modulus<int>());
    // replace all the ones in Y with tens
    thrust::replace(Y.begin(), Y.end(), 1, 10);
    // print Y
    thrust::copy(Y.begin(), Y.end(), std::ostream_iterator<int>(std::cout, "\n"));
    return 0;
}
```

Thrust User-Defined Functors

```
// calculate result[] = (a * x[]) + y[]
struct saxpy {
    const float _a;
    saxpy(int a) : _a(a) { }

    __host__ __device__
    float operator()(const float& x, const float& y) const {
        return a * x + y;
    }
};

thrust::device_vector<float> x, y, result;
thrust::transform(x.begin(), x.end(), y.begin(), result.begin(), saxpy(a));
```

Classwork

- Create two 32-element vectors:
 - X on host, Y on device
- Fill X with 10, fill Y with sequence 0..31
- Compute $Z = X - Y$
- Compute $Z = X * Y$
 - // element-wise multiplication

Thrust Reductions

- Recall reductions in $\log(n)$ barriers
- No need to worry about blocks, synchronization.

```
int x, y;  
thrust::host_vector<int> hvec;  
thrust::device_vector<int> dvec;  
// (thrust::reduce is a sum operation by default)  
x = thrust::reduce(hvec.begin(), hvec.end()); // on CPU  
y = thrust::reduce(dvec.begin(), dvec.end()); // on GPU  
  
y = thrust::reduce(dvec.begin(), dvec.end(),  
                  (int)0, thrust::plus<int>());
```

Classwork: Implement count using reduction.

```
struct mycount {
    int _a;
    mycount(int a):_a(a){}
    __host__ __device__
    int operator()(const int x, const int y) const {
        return (y == _a ? x + 1 : x);
    }
};

int main() {
    thrust::host_vector<int> vec(10, 0);
    vec[1] = 5;
    vec[4] = 5;
    vec[9] = 5;

    int result = thrust::reduce(vec.begin(), vec.end(),
                               (int)0, mycount(5));
    std::cout << result << std::endl;
    return 0;
}
```

Prefix Sum / Scan

```
#include <thrust/scan.h>

int data[6] = {1, 0, 2, 2, 1, 3};

// in-place scan

thrust::inclusive_scan(data, data + 6, data);

// data is now {1, 1, 3, 5, 6, 9}

thrust::exclusive_scan(data, data + 6, data);

// data is now {0, 1, 1, 3, 5, 6}
```

Classwork: Find output

```
int main() {  
    int data[] = {-5, 0, 2, -3, 2, 4, 0, -1, 2, 8};  
    int sizedata = sizeof(data) / sizeof(*data);  
    thrust::maximum<int> binop;  
    thrust::exclusive_scan(data, data + sizedata,  
                          data, 1, binop);  
    for (unsigned ii = 0; ii < sizedata; ++ii) {  
        std::cout << data[ii] << " ";  
    }  
    std::cout << std::endl;  
    return 0;  
}
```

1 1 1 2 2 2 4 4 4 4

Set Operations

```
#include <thrust/set_operations.h>
```

```
...
```

```
int A1[6] = {0, 1, 3, 4, 5, 6, 9};
```

```
int A2[5] = {1, 3, 5, 7, 9};
```

```
int result[N];
```

```
thrust::set_difference(A1, A1+6, A2, A2+5, result);
```



Must be sorted

result is {0, 4, 6}.

Set Operations

```
#include <thrust/set_operations.h>
```

```
...
```

```
int A1[] = {9, 6, 5, 4, 3, 1, 0};
```

```
int A2[5] = {9, 7, 5, 3, 1};
```

```
int result[N];
```

```
thrust::set_difference(A1, A1+7, A2, A2+5, result,  
thrust::greater<int>());
```

result is {6, 4, 0}.

Sorting

```
#include <thrust/sort.h>
```

```
...
```

```
const int N = 6;
int A[N] = {1, 4, 2, 8, 5, 7};
thrust::sort(A, A + N);
// A is now {1, 2, 4, 5, 7, 8}
```

```
int keys[N] = { 1, 4, 2, 8, 5, 7};
char values[N] = {'a', 'b', 'c', 'd', 'e', 'f'};
thrust::sort_by_key(keys, keys + N, values);
// keys is now { 1, 2, 4, 5, 7, 8}
// values is now {'a', 'c', 'b', 'e', 'f', 'd'}
```