

Dynamic Analysis

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CS6843 Program Analysis
IIT Madras
Jan 2016

Limitations of Static Analysis

- Reduced precision: Over-approximations
- Cannot perform input-dependent analysis

4

Outline

- Applications of dynamic analysis
 - Limitations of static analysis
 - Trade-offs
- Profiling techniques
- Finding invariants
 - Equality
 - Affine
- Dynamic type inferencing

2

Static versus Dynamic

- | | |
|-------------------|-------------------|
| • Sound | • Incomplete |
| • Imprecise | • Precise |
| • Input-oblivious | • Input-dependent |

- Choosing between static and dynamic analysis often requires a trade-off between soundness and precision.
- Current trend is to combine the two techniques to get better precision at improved scalability.

5

Applications

- Bug finding (testing)
- Data race detection
- Identifying security vulnerabilities
- Improved precision of static analysis
- Input-dependent analysis

3

Profiling

- Profiling is a method of collecting information of interest during program execution.
- The information is often useful to find **hot-spots** in the program.
- Examples
 - Number of times an instruction is executed
 - Number of page faults
 - Number of cache hits
 - Total memory used
 - ...

6

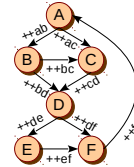
Profiling

- **Intrusive:** inserts instructions in the program (source, IR, assembly) **statically**, which get executed at **runtime**
 - File log
 - Memory locations pointed to by a pointer
 - Execution time of a function
- **Non-intrusive:** the program is unaltered; uses external means to profile
 - Hardware counters
 - Program execution time

7

Edge Profiling

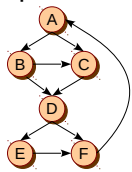
- Path profile is approximated as an edge profile
- The frequency of each edge is calculated – which is used to find the path frequency



10

Path Profiling

- Consider a program with an entry node and an exit node. There are several execution paths (traces) that the program takes from entry to exit.
- The task is to find the frequency of execution of each path.

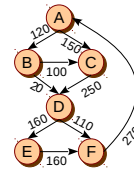


Path	Frequency
ACDF	90
ACDEF	60
ABCDF	0
ABCDEF	100
ABDF	20
ABDEF	0

8

Edge Profiling

- Path profile is approximated as an edge profile
- The frequency of each edge is calculated – which is used to find the path frequency



Path	Frequency
ACDF	110
ACDEF	150
ABCDF	100
ABCDEF	100
ABDF	20
ABDEF	20

Choose the minimum edge-frequency in the path

11

Path Profiling

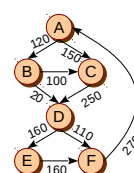
- Naïve path profiling is expensive: instrumenting each path may lead to exponential blow up in computation and storage
- This can lead to unacceptable program slowdown

9

Path vs. Edge Profiling

- Path profile is approximated as an edge profile
- The frequency of each edge is calculated – which is used to find the path frequency

Can this instrumentation be optimized?
Can we have better precision?



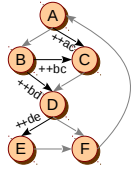
Path	Path Frequency (actual)	Path Frequency (estimated)
ACDF	90	110
ACDEF	60	150
ABCDF	0	100
ABCDEF	100	100
ABDF	20	20
ABDEF	0	20

12

Efficient Edge Profiling

- Observation: We do not need to instrument every edge.
- How to find a minimal, low-cost set of edges to instrument?
- Use a spanning tree (instrument non-st edges):
 - reduced instrumentation along paths,
 - not all edges carry instrumentation

Classwork: Find counts for uninstrumented edges.

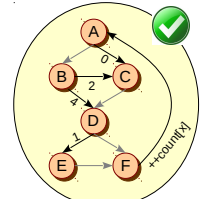
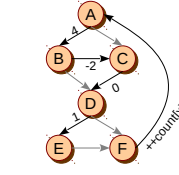
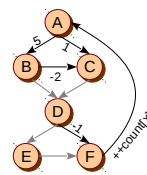


Path	Frequency
C → D	ac + bc
D → F	ac + bc + bd - de
E → F	de
A → B	bc + bd
F → A	ac + bc + bd

13

Efficient Path Profiling

- Path numbering is not unique



Path	x
ACDF	0
ACDEF	1
ABCDF	2
ABCDEF	3
ABDF	4
ABDEF	5

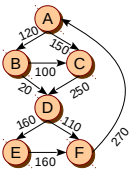
In all the above cases, the path numbering is the same, number of instrumented edges (5) is the same

So, which instrumentation should we choose?

16

Edge Profiling

- Edge profile may not always be a good indicator of a path profile
- Efficient edge profiling requires a unique variable along each instrumented edge (non-spanning tree edge)



Path	Frequency	Actual Freq.	Actual Freq. 2
ACDF	110	90	110
ACDEF	150	60	40
ABCDF	100	0	0
ABCDEF	100	100	100
ABDF	20	20	0
ABDEF	20	0	20

But path profiling is expensive

14

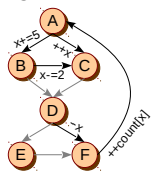
Efficient Path Profiling

1. Assign integer values to edges such that no two paths compute the same path-sum.
2. Use a spanning tree to select edges to instrument and compute the appropriate increment.
3. Select appropriate instrumentation.
4. After collecting the run-time profile, derive the execution paths.

17

Efficient Path Profiling

- Since index variable across all paths
- Path linearization: Unique (and consecutive) path numbering, which enables indexing
- Most hardware support registers, fast increment and indexing



Path	x
ACDF	0
ACDEF	1
ABCDF	2
ABCDEF	3
ABDF	4
ABDEF	5

Classwork: Prove that such a path numbering is unique.

Check the value of x for each path.

15

Efficient Path Profiling

1. Assign integer values to edges such that no two paths compute the same path-sum.
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4. After collecting the run-time profile, derive the execution paths.

NumPaths(node) = 0

NumPaths(leaf) = 1

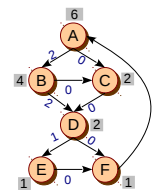
In reverse topological order

For each edge $v \rightarrow w$ {

$Val(v \rightarrow w) = NumPaths(v)$

$NumPaths(v) += NumPaths(w)$

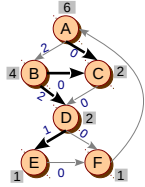
}



18

Efficient Path Profiling

1. Assign integer values to edges such that no two paths compute the same path-sum.
 2. Use a spanning tree to select edges to instrument and compute the appropriate increment.
 3. Select appropriate instrumentation.
 4. After collecting the run-time profile, derive the execution paths.
- Find a spanning tree.
 - Find **chord** (non-ST) edges.
 - For each chord, find fundamental cycle.

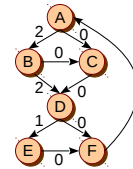


19

Efficient Path Profiling

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Path Regeneration
Path id → Path mapping?



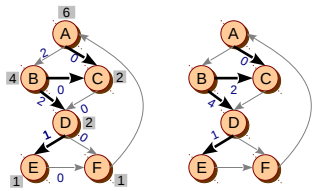
Path	id
ACDF	0
ACDEF	1
ABCDF	2
ABCDEF	3
ABDF	4
ABDEF	5

22

Efficient Path Profiling

1. Assign integer values to edges such that no two paths compute the same path-sum.
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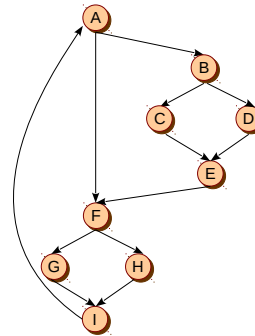
Chord AC: cycle ACDF : 0
Chord BC: cycle ABCDF : 2
Chord BD: cycle ABDF : 4
Chord DE: cycle DEF : 1



20

Classwork

- Find the instrumentation for the following CFG



23

Efficient Path Profiling

1. Assign integer values to edges such that no two paths compute the same path-sum.
 2. Use a spanning tree to select edges to instrument and compute the appropriate increment.
 3. Select appropriate instrumentation.
 4. After collecting the run-time profile, derive the execution paths.
- Prelude:* Allocate and initialize the array of counters
- Postlude:* Write the array to permanent storage
- Main:*
- Initialize path register r in the entry vertex
 - Increment path memory counter in the exit vertex
 - Optimizations

21