# Matrices

CS6015 : Linear Algebra

# Matrix : Definition

- A matrix is a rectangular array of numbers and each of the numbers in the matrix is called an entry.
- The size (dimension) of a matrix with n rows and m columns is denoted by  $n \times m$ . In denoting the size of a matrix we always list the number of rows first and the number of columns second.
- Example :

$$\begin{bmatrix} 4 & 3 & 0 & 6 & -1 & 0 \\ 0 & 2 & -4 & -7 & 1 & 3 \\ -6 & 1 & 15 & \frac{1}{2} & -1 & 0 \end{bmatrix}$$

Matrix of size (dimension)  $3 \times 4$ 

#### Matrix : example

Matrix of size (dimension)  $4 \times 1$  (Column Vector)

Matrix of size (dimension)  $1 \times 5$  (Row Vector)

- We will often need to refer to specific entries in a matrix and so we'll need a notation to take care of that. The entry in the *i*<sup>th</sup> row and *j*<sup>th</sup> column of the matrix *A* is denoted by, *a<sub>ij</sub>*.
- The lower case letter we use to denote the entries of a matrix will always match with the upper case letter we use to denote the matrix. So the entries of the matrix *B* will be denoted by *b<sub>ij</sub>*.

# Terminologies

• Here are some important terminologies, with examples, related to matrices



#### Matrix Arithmetic and Operation

- Equality: A = B provided dimensions of A and B are equal and  $a_{ij} = b_{ij}$  for all *i* and *j*. Matrices of different sizes cannot be equal.
- Addition, Subtraction:  $A_{n \times m} \pm B_{n \times m} = [a_{ij} \pm b_{ij}]$ . Matrices of different sizes cannot be added or subtracted.
- Scalar Multiple:  $cA = [ca_{ij}]$ ; c is any number.
- Multiplication:  $A_{n \times p} * B_{p \times m} = A.B_{n \times m}$
- **Transpose:**  $A = [a_{ij}]_{n \times m}$  then  $A^T = [a_{ji}]_{m \times n} \forall i, j$
- **Trace:**  $tr(A) = \sum_{i=1}^{n} a_{ii}$ . If A is not square then trace is not defined.

Properties of Matrix Arithmetic and the Transpose

- $\bullet A + B = B + A$
- A + (B + C) = (A + B) + C
- A(BC) = (AB)C
- $A(B \pm C) = AB \pm AC$
- $(B \pm C)A = BA \pm CA$
- $a(B \pm C) = aB \pm aC$
- $(a \pm b)C = aC \pm bC$
- (ab)C = a(bC)
- a(BC) = (aB)C = B(aC)
- A (B)  $\neq B$  (A), in general.

Letters in caps define matrices, while that in small denote scalars. Properties of Matrix Arithmetic and the Transpose

- A + 0 = 0 + A = A
- A A = 0
- 0 A = A
- 0A = 0 and A0 = 0
- $A^n A^m = A^{n+m}$
- $(A^n)^m = A^{nm}$
- $(A^T)^T = A$
- $(A \pm B)^T = A^T \pm B^T$
- $(cA)^T = cA^T$
- $(AB)^T = B^T A^T$

Letters in caps define matrices, while that in small denote scalars.

## Inverse of square matrix

- If A is a square matrix of size n and we can find another matrix of the same size, say B, such that  $AB = BA = I_n$
- Then we call **A invertible** and we say that **B** is an **inverse** of the matrix **A**.
- We will denote the inverse as  $A^{-1}$ .
- Not every matrix has an inverse.
  - A square matrix that has an inverse is said to be nonsingular.
  - A square matrix that does not have an inverse is said to be singular.

#### Important properties of the inverse matrix

Suppose that A and B are invertible matrices of the same size. Then,

- a) AB is invertible and  $(AB)^{-1} = B^{-1}A^{-1}$
- b)  $A^{-1}$  is invertible and  $(A^{-1})^{-1} = A$
- c) For  $n = 0,1,2 \dots A^n$  is invertible and  $(A^n)^{-1} = A^{-n} = (A^{-1})^n$

d) If *c* is any non zero scalar then *cA* is invertible

and 
$$(cA)^{-1} = \frac{1}{c}A^{-1}$$
.  
*e*)  $A^{T}$  is invertible and  $(A^{T})^{-1} = (A^{-1})^{T}$ 

#### **Inverse Calculation**

• The matrix 
$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

will be *invertible* if  $ad - bc \neq 0$ 

and *singular* if ad - bc = 0.

• If the matrix is invertible its inverse will be,

$$A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

# Special Matrices : Diagonal Matrix

• **Diagonal Matrix:** A square matrix is called **diagonal** if it has the following form

$$D = \begin{bmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & d_n \end{bmatrix}$$

- Suppose D is a diagonal matrix and  $d_i$ , i = 1, ..., n are the entries on the main diagonal.
- If one or more of the  $d_i$ 's are zero then the matrix is singular.

#### Diagonal Matrix (contd.)

• On the other hand if  $d_i \neq 0$ ,  $\forall i$  then the matrix is invertible and the inverse is,

$$D^{-1} = \begin{bmatrix} \frac{1}{d_1} & 0 & 0 & \dots & 0 \\ 0 & \frac{1}{d_2} & 0 & \dots & 0 \\ 0 & 0 & \frac{1}{d_3} & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \frac{1}{d_n} \end{bmatrix}$$

## Triangular matrix

 $U = \begin{bmatrix} u_{11} & u_{12} & u_{13} & \cdots & u_{1n} \\ 0 & u_{22} & u_{23} & \cdots & u_{2n} \\ 0 & 0 & u_{33} & \cdots & u_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & u_{nn} \end{bmatrix}_{n \times n} \qquad L = \begin{bmatrix} l_{11} & 0 & 0 & \cdots & 0 \\ l_{21} & l_{22} & 0 & \cdots & 0 \\ l_{31} & l_{32} & l_{33} & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ l_{n1} & l_{n2} & l_{n3} & \cdots & l_{nn} \end{bmatrix}_{n \times n}$ 

**Upper Triangular Matrix** 

Lower Triangular Matrix

- If A is a triangular matrix with main diagonal entries a<sub>11</sub>, a<sub>22</sub>, ..., a<sub>nn</sub> then if one or more of the a<sub>ii</sub>'s are zero the matrix will be singular.
- On the other hand if a<sub>ii</sub> ≠ 0 ∀i then the matrix is *invertible*.

#### Symmetric and anti-symmetric matrices

Suppose that A is an  $n \times m$  matrix, then A will be called **symmetric** if A = AT.

Some properties of symmetric matrices are:

- a) For any matrix A, both  $AA^T$  and  $A^TA$  are symmetric.
- b) If A is an invertible symmetric matrix then  $A^{-1}$  is also symmetric.
- *c)* If *A* is invertible then *AA*<sup>T</sup> and *A*<sup>T</sup>*A* are both invertible.

#### Anti-Symmetric or Skew-Symmetric:

An anti-symmetric matrix is a square matrix that satisfies the identity  $\mathbf{A} = -\mathbf{A}^{T_{.}}$ 

**Other Special forms of matrices:** 

- Toeplitz matrix
- Block Circulant Matrix
- Orthogonal (also, -skew -sym)
- PD, PSD, ...
- Tri-diagonal system
- Hessian
- Jacobian
- Adjoint and Adjugate matrices
- (skew-) Hermitian (or self-adjoint ) matrix
- Covariance matrix
- Periodic matrices

- Compound Matrix
- g-inv & Pseudo-inv
- GRAM matrix
- Kernel of matrix
- Schur Complement
- PERM (n)
- Skew-symmetric
- DFT Matrix
- Idempotent Matrices
- Vandermonde Matrices