CS7015 (Deep Learning) : Lecture 3 Sigmoid Neurons, Gradient Descent, Feedforward Neural Networks, Representation Power of Feedforward Neural Networks

Mitesh M. Khapra

Department of Computer Science and Engineering Indian Institute of Technology Madras

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

Acknowledgements

- For Module 3.4, I have borrowed ideas from the videos by Ryan Harris on "visualize backpropagation" (available on youtube)
- \bullet For Module 3.5, I have borrowed ideas from this excellent book a which is available online
- I am sure I would have been influenced and borrowed ideas from other sources and I apologize if I have failed to acknowledge them

 $^{a} {\rm http://neural networks and deep learning.com/chap4.html}$

イロト (局) (日) (日) (日) (の)

Module 3.1: Sigmoid Neuron

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

◆□▶ ◆課▶ ◆臣▶ ◆臣▶ 臣 の�?

• Enough about boolean functions!

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

- Enough about boolean functions!
- What about arbitrary functions of the form y = f(x) where $x \in \mathbb{R}^n$ (instead of $\{0,1\}^n$) and $y \in \mathbb{R}$ (instead of $\{0,1\}$)?

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへの

- Enough about boolean functions!
- What about arbitrary functions of the form y = f(x) where $x \in \mathbb{R}^n$ (instead of $\{0,1\}^n$) and $y \in \mathbb{R}$ (instead of $\{0,1\}$)?
- Can we have a network which can (approximately) represent such functions ?

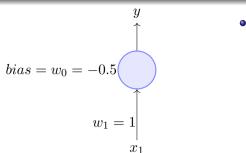
《曰》 《曰》 《曰》 《曰》 [] []

- Enough about boolean functions!
- What about arbitrary functions of the form y = f(x) where $x \in \mathbb{R}^n$ (instead of $\{0,1\}^n$) and $y \in \mathbb{R}$ (instead of $\{0,1\}$)?
- Can we have a network which can (approximately) represent such functions ?
- Before answering the above question we will have to first graduate from *perceptrons* to *sigmoidal neurons* ...

(日) (日) (日) (日) (日) (日) (日)

Recall

 \bullet A perceptron will fire if the weighted sum of its inputs is greater than the threshold $(-w_0)$



• The thresholding logic used by a perceptron is very harsh !

◆□▶ ◆圖▶ ◆臣▶ ◆臣▶ ─臣 ─のへで

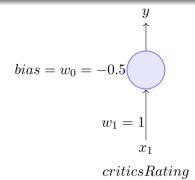
$$bias = w_0 = -0.5$$

$$w_1 = 1$$

$$x_1$$

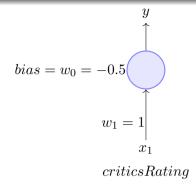
- The thresholding logic used by a perceptron is very harsh !
- For example, let us return to our problem of deciding whether we will like or dislike a movie

イロト イポト イヨト イヨト ヨー のくで

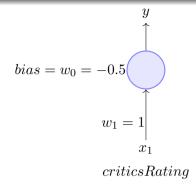


- The thresholding logic used by a perceptron is very harsh !
- For example, let us return to our problem of deciding whether we will like or dislike a movie
- Consider that we base our decision only on one input $(x_1 = criticsRating$ which lies between 0 and 1)

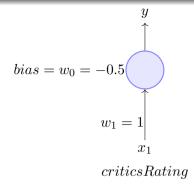
イロト (局) (日) (日) (日) (の)



- The thresholding logic used by a perceptron is very harsh !
- For example, let us return to our problem of deciding whether we will like or dislike a movie
- Consider that we base our decision only on one input $(x_1 = criticsRating$ which lies between 0 and 1)
- If the threshold is 0.5 ($w_0 = -0.5$) and $w_1 = 1$ then what would be the decision for a movie with *criticsRating* = 0.51 ?

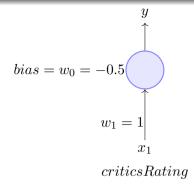


- The thresholding logic used by a perceptron is very harsh !
- For example, let us return to our problem of deciding whether we will like or dislike a movie
- Consider that we base our decision only on one input $(x_1 = criticsRating$ which lies between 0 and 1)
- If the threshold is 0.5 ($w_0 = -0.5$) and $w_1 = 1$ then what would be the decision for a movie with *criticsRating* = 0.51 ? (like)



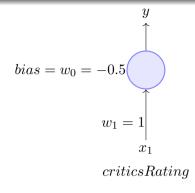
- The thresholding logic used by a perceptron is very harsh !
- For example, let us return to our problem of deciding whether we will like or dislike a movie
- Consider that we base our decision only on one input $(x_1 = criticsRating$ which lies between 0 and 1)
- If the threshold is 0.5 ($w_0 = -0.5$) and $w_1 = 1$ then what would be the decision for a movie with *criticsRating* = 0.51 ? (like)
- What about a movie with criticsRating = 0.49?

イロト (局) (日) (日) (日) (の)



- The thresholding logic used by a perceptron is very harsh !
- For example, let us return to our problem of deciding whether we will like or dislike a movie
- Consider that we base our decision only on one input $(x_1 = criticsRating$ which lies between 0 and 1)
- If the threshold is 0.5 ($w_0 = -0.5$) and $w_1 = 1$ then what would be the decision for a movie with *criticsRating* = 0.51 ? (like)
- What about a movie with criticsRating = 0.49? (dislike)

イロト (局) (日) (日) (日) (の)



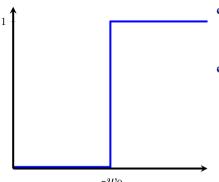
- The thresholding logic used by a perceptron is very harsh !
- For example, let us return to our problem of deciding whether we will like or dislike a movie
- Consider that we base our decision only on one input $(x_1 = criticsRating$ which lies between 0 and 1)
- If the threshold is 0.5 ($w_0 = -0.5$) and $w_1 = 1$ then what would be the decision for a movie with *criticsRating* = 0.51 ? (like)
- What about a movie with criticsRating = 0.49? (dislike)
- It seems harsh that we would like a movie with rating 0.51 but not one with a rating of 0.49

イロト イポト イヨト イヨト ヨー のくで

• This behavior is not a characteristic of the specific problem we chose or the specific weight and threshold that we chose

◆□▶ ◆圖▶ ◆臣▶ ◆臣▶ ─臣 ─のへで

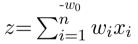
Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

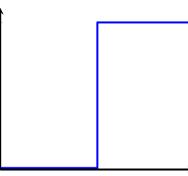


h

- This behavior is not a characteristic of the specific problem we chose or the specific weight and threshold that we chose
- It is a characteristic of the perceptron function itself which behaves like a step function

イロト (局) (日) (日) (日) (の)





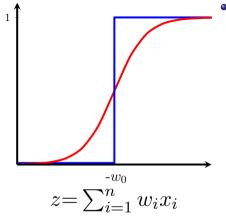
- This behavior is not a characteristic of the specific problem we chose or the specific weight and threshold that we chose
- It is a characteristic of the perceptron function itself which behaves like a step function
- There will always be this sudden change in the decision (from 0 to 1) when $\sum_{i=1}^{n} w_i x_i$ crosses the threshold $(-w_0)$

・ロト ・得 ト ・ヨト ・ヨト ・ヨー

$$z = \sum_{i=1}^{-w_0} w_i x_i$$

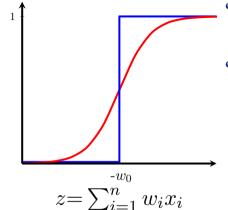
- This behavior is not a characteristic of the specific problem we chose or the specific weight and threshold that we chose
- It is a characteristic of the perceptron function itself which behaves like a step function
- There will always be this sudden change in the decision (from 0 to 1) when $\sum_{i=1}^{n} w_i x_i$ crosses the threshold $(-w_0)$
- For most real world applications we would expect a smoother decision function which gradually changes from 0 to 1

 $z = \sum_{i=1}^{-w_0} w_i x_i$



• Introducing sigmoid neurons where the output function is much smoother than the step function

◆□▶ ◆圖▶ ◆臣▶ ◆臣▶ ─臣 ─のへで

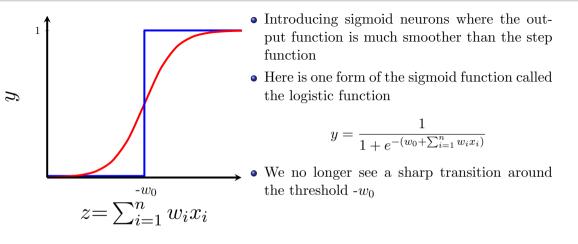


h

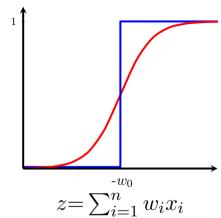
- Introducing sigmoid neurons where the output function is much smoother than the step function
- Here is one form of the sigmoid function called the logistic function

$$y = \frac{1}{1 + e^{-(w_0 + \sum_{i=1}^n w_i x_i)}}$$

イロト (局) (日) (日) (日) (の)



◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 - のへで

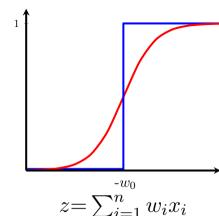


- Introducing sigmoid neurons where the output function is much smoother than the step function
- Here is one form of the sigmoid function called the logistic function

$$y = \frac{1}{1 + e^{-(w_0 + \sum_{i=1}^{n} w_i x_i)}}$$

- We no longer see a sharp transition around the threshold $-w_0$
- Also the output y is no longer binary but a real value between 0 and 1 which can be interpreted as a probability

・ロト ・得 ト ・ヨト ・ヨト ・ヨー

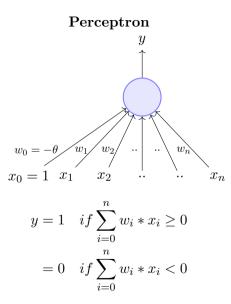


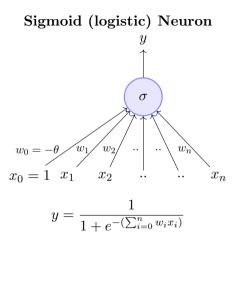
- Introducing sigmoid neurons where the output function is much smoother than the step function
- Here is one form of the sigmoid function called the logistic function

$$y = \frac{1}{1 + e^{-(w_0 + \sum_{i=1}^{n} w_i x_i)}}$$

- We no longer see a sharp transition around the threshold $-w_0$
- Also the output y is no longer binary but a real value between 0 and 1 which can be interpreted as a probability
- Instead of a like/dislike decision we get the probability of liking the movie

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへの

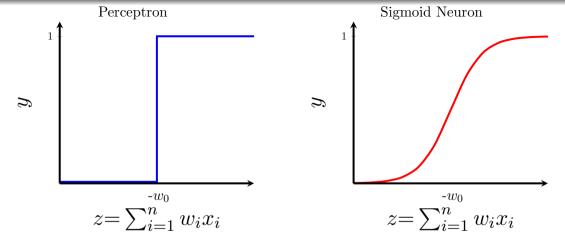




◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 - のへで

8/62

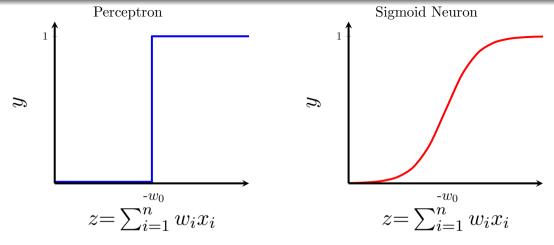
Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



Not smooth, not continuous (at w0), **not**

differentiable

イロト イポト イヨト イヨト ヨー のくで



Not smooth, not continuous (at w0), **not**

 ${\it differentiable}$

Smooth, continuous, differentiable

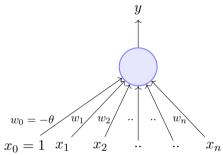
イロト イポト イヨト イヨト ヨー のくで

Module 3.2: A typical Supervised Machine Learning Setup

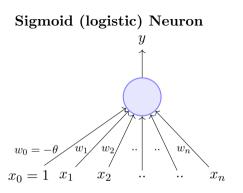
Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

• What next ?

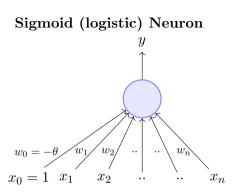
Sigmoid (logistic) Neuron



◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 - のへで

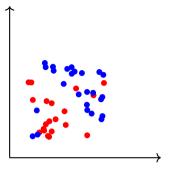


- What next ?
- Well, just as we had an algorithm for learning the weights of a perceptron, we also need a way of learning the weights of a sigmoid neuron



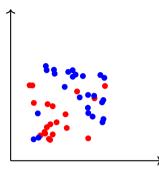
- What next ?
- Well, just as we had an algorithm for learning the weights of a perceptron, we also need a way of learning the weights of a sigmoid neuron
- Before we see such an algorithm we will revisit the concept of **error**

・ロト ・雪ト ・ヨト ・ヨー



• Earlier we mentioned that a single perceptron cannot deal with this data because it is not linearly separable

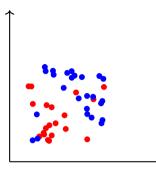
イロト 不得下 イヨト イヨト



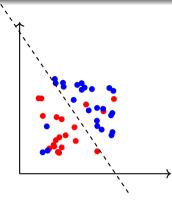
• Earlier we mentioned that a single perceptron cannot deal with this data because it is not linearly separable

• What does "cannot deal with" mean?

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



- Earlier we mentioned that a single perceptron cannot deal with this data because it is not linearly separable
- What does "cannot deal with" mean?
- What would happen if we use a perceptron model to classify this data ?

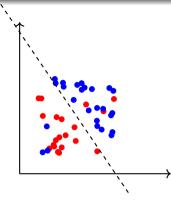


- Earlier we mentioned that a single perceptron cannot deal with this data because it is not linearly separable
- What does "cannot deal with" mean?
- What would happen if we use a perceptron model to classify this data ?

化固定 化压力 化压力

3

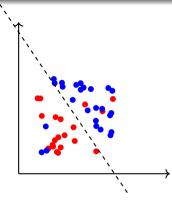
• We would probably end up with a line like this ...



- Earlier we mentioned that a single perceptron cannot deal with this data because it is not linearly separable
- What does "cannot deal with" mean?
- What would happen if we use a perceptron model to classify this data ?

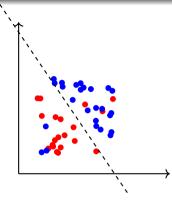
-

- We would probably end up with a line like this ...
- This line doesn't seem to be too bad



- Earlier we mentioned that a single perceptron cannot deal with this data because it is not linearly separable
- What does "cannot deal with" mean?
- What would happen if we use a perceptron model to classify this data ?
- We would probably end up with a line like this ...
- This line doesn't seem to be too bad
- Sure, it misclassifies 3 blue points and 3 red points but we could live with this error in **most** real world applications

-



- Earlier we mentioned that a single perceptron cannot deal with this data because it is not linearly separable
- What does "cannot deal with" mean?
- What would happen if we use a perceptron model to classify this data ?
- We would probably end up with a line like this ...
- This line doesn't seem to be too bad
- Sure, it misclassifies 3 blue points and 3 red points but we could live with this error in **most** real world applications
- From now on, we will accept that it is hard to drive the error to 0 in most cases and will instead aim to reach the minimum possible error

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

▲□▶ ▲圖▶ ▲圖▶ ▲圖▶ / 圖 / のへで

• Data: $\{x_i, y_i\}_{i=1}^n$

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 - のへで

- Data: ${x_i, y_i}_{i=1}^n$
- Model: Our approximation of the relation between \mathbf{x} and y. For example,

- Data: ${x_i, y_i}_{i=1}^n$
- Model: Our approximation of the relation between \mathbf{x} and y. For example,

$$\hat{y} = \frac{1}{1 + e^{-(\mathbf{w^T}\mathbf{x})}}$$

- Data: ${x_i, y_i}_{i=1}^n$
- Model: Our approximation of the relation between \mathbf{x} and y. For example,

$$\begin{split} \hat{y} &= \frac{1}{1 + e^{-(\mathbf{w}^{T}\mathbf{x})}} \\ or \quad \hat{y} &= \mathbf{w}^{T}\mathbf{x} \end{split}$$

- Data: ${x_i, y_i}_{i=1}^n$
- Model: Our approximation of the relation between \mathbf{x} and y. For example,

$$\hat{y} = \frac{1}{1 + e^{-(\mathbf{w}^{T}\mathbf{x})}}$$
or $\hat{y} = \mathbf{w}^{T}\mathbf{x}$
or $\hat{y} = \mathbf{x}^{T}\mathbf{W}\mathbf{x}$

• Data: ${x_i, y_i}_{i=1}^n$

• Model: Our approximation of the relation between \mathbf{x} and y. For example,

$$\hat{y} = \frac{1}{1 + e^{-(\mathbf{w}^{T}\mathbf{x})}}$$
or $\hat{y} = \mathbf{w}^{T}\mathbf{x}$
or $\hat{y} = \mathbf{x}^{T}\mathbf{W}\mathbf{x}$

or just about any function

- Data: ${x_i, y_i}_{i=1}^n$
- Model: Our approximation of the relation between \mathbf{x} and y. For example,

$$\hat{y} = \frac{1}{1 + e^{-(\mathbf{w}^{T}\mathbf{x})}}$$
or $\hat{y} = \mathbf{w}^{T}\mathbf{x}$
or $\hat{y} = \mathbf{x}^{T}\mathbf{W}\mathbf{x}$

or just about any function

• **Parameters:** In all the above cases, w is a parameter which needs to be learned from the data

- Data: $\{x_i, y_i\}_{i=1}^n$
- Model: Our approximation of the relation between \mathbf{x} and y. For example,

$$\hat{y} = \frac{1}{1 + e^{-(\mathbf{w}^{T}\mathbf{x})}}$$
or $\hat{y} = \mathbf{w}^{T}\mathbf{x}$
or $\hat{y} = \mathbf{x}^{T}\mathbf{W}\mathbf{x}$

or just about any function

- **Parameters:** In all the above cases, w is a parameter which needs to be learned from the data
- Learning algorithm: An algorithm for learning the parameters (w) of the model (for example, perceptron learning algorithm, gradient descent, etc.)

- Data: $\{x_i, y_i\}_{i=1}^n$
- Model: Our approximation of the relation between \mathbf{x} and y. For example,

$$\hat{y} = \frac{1}{1 + e^{-(\mathbf{w}^{T}\mathbf{x})}}$$
or $\hat{y} = \mathbf{w}^{T}\mathbf{x}$
or $\hat{y} = \mathbf{x}^{T}\mathbf{W}\mathbf{x}$

or just about any function

- **Parameters:** In all the above cases, w is a parameter which needs to be learned from the data
- Learning algorithm: An algorithm for learning the parameters (w) of the model (for example, perceptron learning algorithm, gradient descent, etc.)
- **Objective/Loss/Error function:** To guide the learning algorithm

・ロト ・ 日 ・ モ ト ・ 日 ・ ・ つ へ つ ・

- Data: $\{x_i, y_i\}_{i=1}^n$
- Model: Our approximation of the relation between \mathbf{x} and y. For example,

$$\hat{y} = \frac{1}{1 + e^{-(\mathbf{w}^{T}\mathbf{x})}}$$
or $\hat{y} = \mathbf{w}^{T}\mathbf{x}$
or $\hat{y} = \mathbf{x}^{T}\mathbf{W}\mathbf{x}$

or just about any function

- **Parameters:** In all the above cases, w is a parameter which needs to be learned from the data
- Learning algorithm: An algorithm for learning the parameters (w) of the model (for example, perceptron learning algorithm, gradient descent, etc.)
- Objective/Loss/Error function: To guide the learning algorithm the learning algorithm should aim to minimize the loss function

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

▲□▶ ▲□▶ ▲目▶ ▲目▶ 目 のへぐ

• Data: $\{x_i = movie, y_i = like/dislike\}_{i=1}^n$

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

▲□▶ ▲圖▶ ▲≣▶ ▲≣▶ 三回 のへで

- Data: $\{x_i = movie, y_i = like/dislike\}_{i=1}^n$
- Model: Our approximation of the relation between \mathbf{x} and y (the probability of liking a movie).

- Data: $\{x_i = movie, y_i = like/dislike\}_{i=1}^n$
- Model: Our approximation of the relation between \mathbf{x} and y (the probability of liking a movie).

$$\hat{y} = \frac{1}{1 + e^{-(\mathbf{w}^{T}\mathbf{x})}}$$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへで

- Data: $\{x_i = movie, y_i = like/dislike\}_{i=1}^n$
- Model: Our approximation of the relation between \mathbf{x} and y (the probability of liking a movie).

$$\hat{y} = \frac{1}{1 + e^{-(\mathbf{w}^{T}\mathbf{x})}}$$

• Parameter: w

- Data: $\{x_i = movie, y_i = like/dislike\}_{i=1}^n$
- Model: Our approximation of the relation between \mathbf{x} and y (the probability of liking a movie).

$$\hat{y} = \frac{1}{1 + e^{-(\mathbf{w}^{\mathrm{T}}\mathbf{x})}}$$

• Parameter: w

• Learning algorithm: Gradient Descent [we will see soon]

- Data: $\{x_i = movie, y_i = like/dislike\}_{i=1}^n$
- Model: Our approximation of the relation between \mathbf{x} and y (the probability of liking a movie).

$$\hat{y} = \frac{1}{1 + e^{-(\mathbf{w}^{\mathrm{T}}\mathbf{x})}}$$

• Parameter: w

- Learning algorithm: Gradient Descent [we will see soon]
- Objective/Loss/Error function:

- Data: $\{x_i = movie, y_i = like/dislike\}_{i=1}^n$
- Model: Our approximation of the relation between \mathbf{x} and y (the probability of liking a movie).

$$\hat{y} = \frac{1}{1 + e^{-(\mathbf{w}^{\mathrm{T}}\mathbf{x})}}$$

• Parameter: w

- Learning algorithm: Gradient Descent [we will see soon]
- Objective/Loss/Error function: One possibility is

$$\mathscr{L}(\mathbf{w}) = \sum_{i=1}^{n} (\hat{y}_i - y_i)^2$$

- Data: $\{x_i = movie, y_i = like/dislike\}_{i=1}^n$
- Model: Our approximation of the relation between \mathbf{x} and y (the probability of liking a movie).

$$\hat{y} = \frac{1}{1 + e^{-(\mathbf{w}^{\mathrm{T}}\mathbf{x})}}$$

• Parameter: w

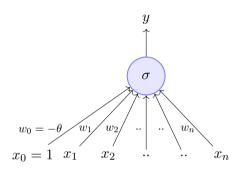
- Learning algorithm: Gradient Descent [we will see soon]
- Objective/Loss/Error function: One possibility is

$$\mathscr{L}(\mathbf{w}) = \sum_{i=1}^{n} (\hat{y}_i - y_i)^2$$

The learning algorithm should aim to find a w which minimizes the above function (squared error between y and \hat{y})

Module 3.3: Learning Parameters: (Infeasible) guess work

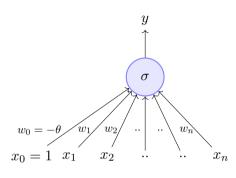
Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



$$f(x) = \frac{1}{1 + e^{-(w \cdot x + b)}}$$

• Keeping this supervised ML setup in mind, we will now focus on this **model** and discuss an **algorithm** for learning the **parameters** of this model from some given **data** using an appropriate **objective function**

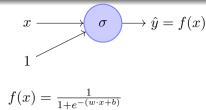
- 4月 * 4日 * 4日 * 日 * 900



$$f(x) = \frac{1}{1 + e^{-(w \cdot x + b)}}$$

- Keeping this supervised ML setup in mind, we will now focus on this **model** and discuss an **algorithm** for learning the **parameters** of this model from some given **data** using an appropriate **objective function**
- σ stands for the sigmoid function (logistic function in this case)

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のへで



- Keeping this supervised ML setup in mind, we will now focus on this **model** and discuss an **algorithm** for learning the **parameters** of this model from some given **data** using an appropriate **objective function**
- σ stands for the sigmoid function (logistic function in this case)
- For ease of explanation, we will consider a very simplified version of the model having just 1 input

▲ロト ▲母ト ▲ヨト ▲ヨト ヨー のくぐ

$$x \xrightarrow{w} \sigma \longrightarrow \hat{y} = f(x)$$

$$1 \xrightarrow{b}$$

 $f(x) = \frac{1}{1 + e^{-(w \cdot x + b)}}$

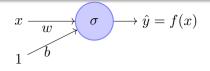
- Keeping this supervised ML setup in mind, we will now focus on this **model** and discuss an **algorithm** for learning the **parameters** of this model from some given **data** using an appropriate **objective function**
- σ stands for the sigmoid function (logistic function in this case)
- For ease of explanation, we will consider a very simplified version of the model having just 1 input
- Further to be consistent with the literature, from now on, we will refer to w_0 as b (bias)

$$x \xrightarrow{w} \sigma \longrightarrow \hat{y} = f(x)$$

$$1 \xrightarrow{b}$$

 $f(x) = \frac{1}{1 + e^{-(w \cdot x + b)}}$

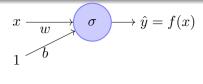
- Keeping this supervised ML setup in mind, we will now focus on this **model** and discuss an **algorithm** for learning the **parameters** of this model from some given **data** using an appropriate **objective function**
- σ stands for the sigmoid function (logistic function in this case)
- For ease of explanation, we will consider a very simplified version of the model having just 1 input
- Further to be consistent with the literature, from now on, we will refer to w_0 as b (bias)
- Lastly, instead of considering the problem of predicting like/dislike, we will assume that we want to predict *criticsRating(y)* given *imdbRating(x)* (for no particular reason)



$$f(x) = \frac{1}{1 + e^{-(w \cdot x + b)}}$$

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

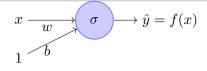
◆□ ▶ < 畳 ▶ < 差 ▶ < 差 ▶ 差 の Q ♀ 17/62</p>



$$f(x) = \frac{1}{1 + e^{-(w \cdot x + b)}}$$

Input for training $\{x_i, y_i\}_{i=1}^N \to N \text{ pairs of } (x, y)$

◆□▶ ◆□▶ ◆目▶ ◆目▶ 目 のへぐ



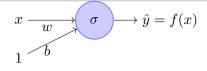
$$f(x) = \frac{1}{1 + e^{-(w \cdot x + b)}}$$

Input for training $\{x_i, y_i\}_{i=1}^N \to N \text{ pairs of } (x, y)$

Training objective

Find w and b such that: minimize $\mathscr{L}(w, b) = \sum_{i=1}^{N} (y_i - f(x_i))^2$

◆□▶ ◆□▶ ◆□▶ ◆□▶ □ ○ ○ ○ ○



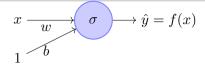
$$f(x) = \frac{1}{1 + e^{-(w \cdot x + b)}}$$

Input for training $\{x_i, y_i\}_{i=1}^N \to N \text{ pairs of } (x, y)$

Training objective

Find w and b such that: minimize $\mathscr{L}(w, b) = \sum_{i=1}^{N} (y_i - f(x_i))^2$

◆□▶ ◆□▶ ◆□▶ ◆□▶ □ ○ ○ ○ ○

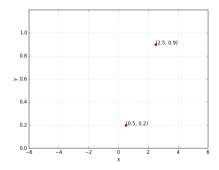


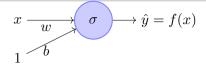
$$f(x) = \frac{1}{1 + e^{-(w \cdot x + b)}}$$



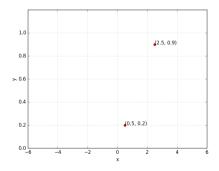
• Suppose we train the network with (x, y) = (0.5, 0.2) and (2.5, 0.9)

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへで





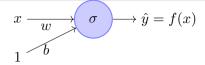
$$f(x) = \frac{1}{1 + e^{-(w \cdot x + b)}}$$



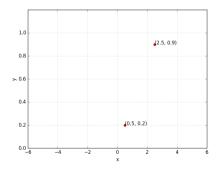
What does it mean to train the network?

- Suppose we train the network with (x, y) = (0.5, 0.2) and (2.5, 0.9)
- At the end of training we expect to find w*, b* such that:

▲ロ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ● ● ● ● ● ●



$$f(x) = \frac{1}{1 + e^{-(w \cdot x + b)}}$$

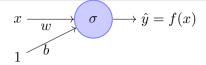


What does it mean to train the network?

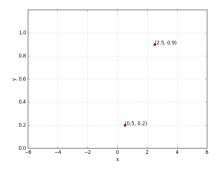
- Suppose we train the network with (x, y) = (0.5, 0.2) and (2.5, 0.9)
- At the end of training we expect to find w^{*}, b^{*} such that:

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへで

• $f(0.5) \to 0.2$ and $f(2.5) \to 0.9$



$$f(x) = \frac{1}{1 + e^{-(w \cdot x + b)}}$$

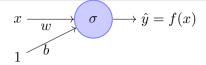


What does it mean to train the network?

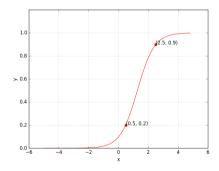
- Suppose we train the network with (x, y) = (0.5, 0.2) and (2.5, 0.9)
- At the end of training we expect to find w*, b* such that:
- $f(0.5) \rightarrow 0.2$ and $f(2.5) \rightarrow 0.9$

In other words...

• We hope to find a sigmoid function such that (0.5, 0.2) and (2.5, 0.9) lie on this sigmoid



$$f(x) = \frac{1}{1 + e^{-(w \cdot x + b)}}$$



What does it mean to train the network?

- Suppose we train the network with (x, y) = (0.5, 0.2) and (2.5, 0.9)
- At the end of training we expect to find w*, b* such that:
- $f(0.5) \rightarrow 0.2$ and $f(2.5) \rightarrow 0.9$

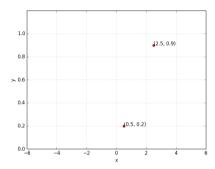
In other words...

• We hope to find a sigmoid function such that (0.5, 0.2) and (2.5, 0.9) lie on this sigmoid

Let us see this in more detail....

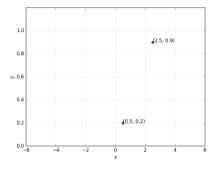
Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

◆□▶ ◆□▶ ◆□▶ ◆□▶ □ のへぐ



$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}}$$

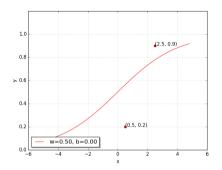
< □ > < @ > < 差 > < 差 > 差 の Q ペ 19/62



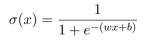
• Can we try to find such a w^*, b^* manually

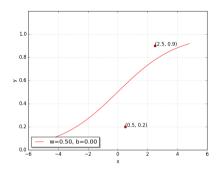
$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}}$$

▲□▶ ▲圖▶ ▲ 臣▶ ▲ 臣▶ ― 臣 … のへで



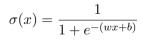
- Can we try to find such a w^*, b^* manually
- Let us try a random guess.. (say, w = 0.5, b = 0)

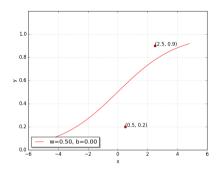




- Can we try to find such a w^*, b^* manually
- Let us try a random guess.. (say, w = 0.5, b = 0)

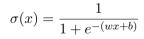
• Clearly not good, but how bad is it ?

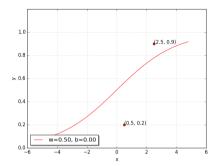




- Can we try to find such a w^*, b^* manually
- Let us try a random guess.. (say, w = 0.5, b = 0)

- Clearly not good, but how bad is it ?
- Let us revisit $\mathscr{L}(w, b)$ to see how bad it is ...



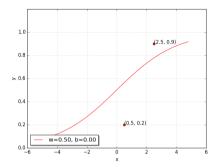


$$\mathscr{L}(w,b) = \frac{1}{2} * \sum_{i=1}^{N} (y_i - f(x_i))^2$$

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}}$

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

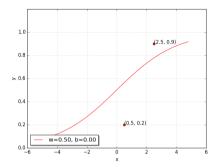
▲□▶ ▲□▶ ▲目▶ ▲目▶ ▲□▶ ▲□▶



$$\mathcal{L}(w,b) = \frac{1}{2} * \sum_{i=1}^{N} (y_i - f(x_i))^2$$
$$= \frac{1}{2} * (y_1 - f(x_1))^2 + (y_2 - f(x_2))^2$$

▲□ → ▲圖 → ▲ 볼 → ▲ 볼 → ♪ ♪ ♡ 𝔅 19/62

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}}$$

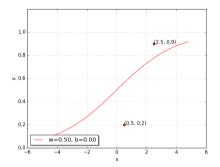


$$\mathscr{L}(w,b) = \frac{1}{2} * \sum_{i=1}^{N} (y_i - f(x_i))^2$$

= $\frac{1}{2} * (y_1 - f(x_1))^2 + (y_2 - f(x_2))^2$
= $\frac{1}{2} * (0.9 - f(2.5))^2 + (0.2 - f(0.5))^2$

▲□ → ▲圖 → ▲ 볼 → ▲ 볼 → ♪ ♪ ♡ 𝔅 19/62

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}}$$

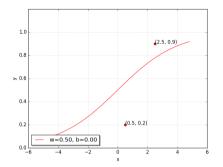


$$\mathcal{L}(w,b) = \frac{1}{2} * \sum_{i=1}^{N} (y_i - f(x_i))^2$$

= $\frac{1}{2} * (y_1 - f(x_1))^2 + (y_2 - f(x_2))^2$
= $\frac{1}{2} * (0.9 - f(2.5))^2 + (0.2 - f(0.5))^2$
= 0.073

▲□ → ▲圖 → ▲ 볼 → ▲ 볼 → ♪ ♪ ♡ 𝔅 19/62

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}}$$



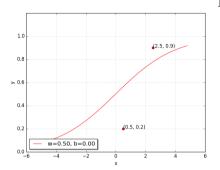
$$\mathcal{L}(w,b) = \frac{1}{2} * \sum_{i=1}^{N} (y_i - f(x_i))^2$$

= $\frac{1}{2} * (y_1 - f(x_1))^2 + (y_2 - f(x_2))^2$
= $\frac{1}{2} * (0.9 - f(2.5))^2 + (0.2 - f(0.5))^2$
= 0.073

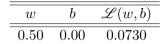
▲□▶ ▲圖▶ ▲ 臣▶ ▲ 臣▶ ― 臣 … のへで

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}}$$

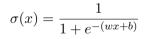
We want $\mathscr{L}(w,b)$ to be as close to 0 as possible

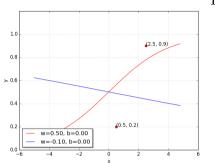


Let us try some other values of w, b



◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 - のへで

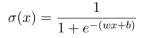




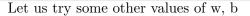
Let us try some other values of w, b

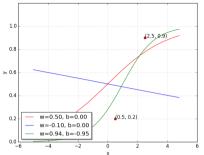
w	b	$\mathscr{L}(w,b)$
0.50	0.00	0.0730
-0.10	0.00	0.1481

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 - のへで

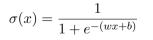


Oops!! this made things even worse...



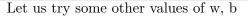


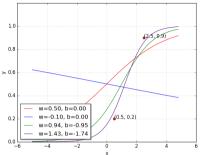
w	b	$\mathscr{L}(w,b)$
0.50	0.00	0.0730
-0.10	0.00	0.1481
0.94	-0.94	0.0214



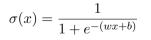
Perhaps it would help to push w and b in the other direction...

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへで



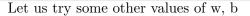


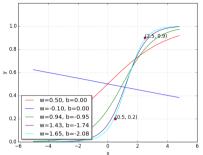
w	b	$\mathscr{L}(w,b)$
0.50	0.00	0.0730
-0.10	0.00	0.1481
0.94	-0.94	0.0214
1.42	-1.73	0.0028



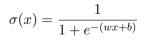
Let us keep going in this direction, *i.e.*, increase w and decrease b

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへで



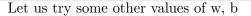


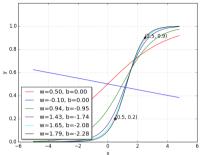
w	b	$\mathscr{L}(w,b)$
0.50	0.00	0.0730
-0.10	0.00	0.1481
0.94	-0.94	0.0214
1.42	-1.73	0.0028
1.65	-2.08	0.0003



Let us keep going in this direction, *i.e.*, increase w and decrease b

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへで





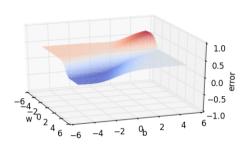
w	b	$\mathscr{L}(w,b)$
0.50	0.00	0.0730
-0.10	0.00	0.1481
0.94	-0.94	0.0214
1.42	-1.73	0.0028
1.65	-2.08	0.0003
1.78	-2.27	0.0000

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}}$$

With some guess work and intuition we were able to find the right values for w and b

Let us look at something better than our "guess work" algorithm....

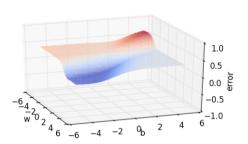
Since we have only 2 points and 2 parameters (w, b) we can easily plot L(w, b) for different values of (w, b) and pick the one where L(w, b) is minimum



Random search on error surface

Since we have only 2 points and 2 parameters (w, b) we can easily plot L(w, b) for different values of (w, b) and pick the one where L(w, b) is minimum

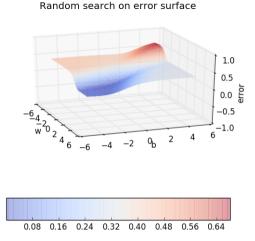




Random search on error surface

- Since we have only 2 points and 2 parameters (w, b) we can easily plot L(w, b) for different values of (w, b) and pick the one where L(w, b) is minimum
- But of course this becomes intractable once you have many more data points and many more parameters !!



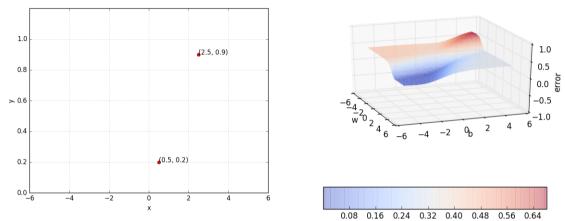


- Since we have only 2 points and 2 parameters (w, b) we can easily plot L(w, b) for different values of (w, b) and pick the one where L(w, b) is minimum
- But of course this becomes intractable once you have many more data points and many more parameters !!
- Further, even here we have plotted the error surface only for a small range of (w, b) [from (-6, 6) and not from $(-\inf, \inf)$]

・ロト ・ 一下・ ・ 日 ・ ・ 日 ・ ・ 日 ・

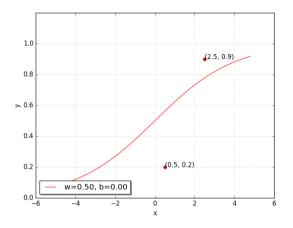
Let us look at the geometric interpretation of our "guess work" algorithm in terms of this error surface

▲日▶ ▲□▶ ▲日▶ ▲日▶ 日 うらつ

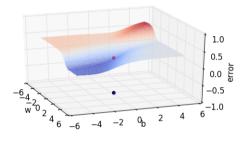


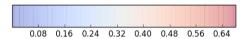
Random search on error surface

▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 - のへで

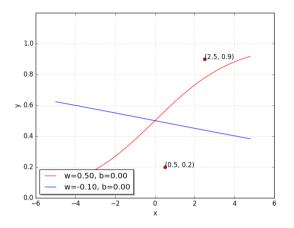


Random search on error surface

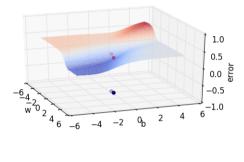


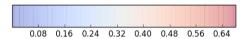


<□ > < 母 > < 喜 > < 喜 > ■ ● < 23/62

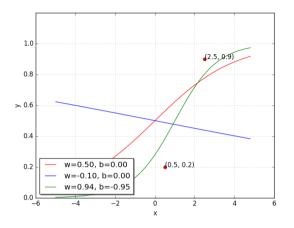


Random search on error surface

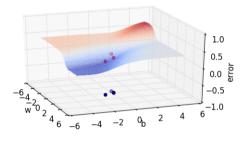


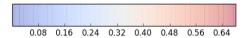


▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 - のへで

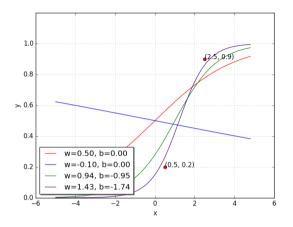


Random search on error surface

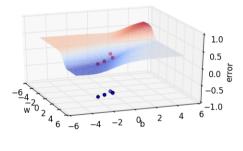


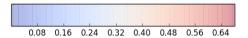


▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 のへで

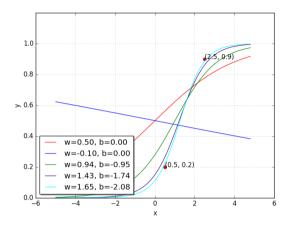


Random search on error surface

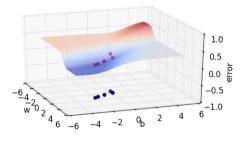


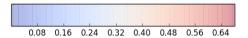


▲□▶ ▲圖▶ ▲臣▶ ▲臣▶ 三臣 - のへで

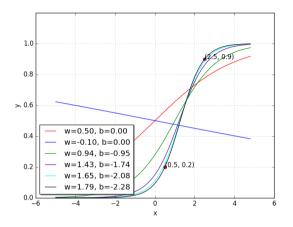


Random search on error surface

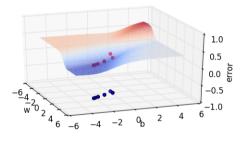


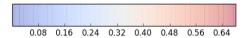


▲□▶ ▲圖▶ ▲臣▶ ▲臣▶ 三臣 - のへで



Random search on error surface





▲□▶ ▲圖▶ ▲臣▶ ▲臣▶ 三臣 - のへで

Module 3.4: Learning Parameters : Gradient Descent

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 のへで

Now let us see if there is a more efficient and principled way of doing this

Goal

Find a better way of traversing the error surface so that we can reach the minimum value quickly without resorting to brute force search!

vector of parameters, say, randomly initialized

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

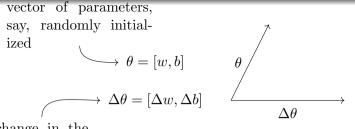
<□ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

$$\longrightarrow \theta = [w, b]$$

$$\longrightarrow \Delta \theta = [\Delta w, \Delta b]$$

change in the values of w, b

▲□▶ ▲圖▶ ▲臣▶ ▲臣▶ ―臣 ― 釣�(?)



change in the values of w, b

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

◆□▶ ◆□▶ ◆三▶ ◆三▶ ●□ のへで

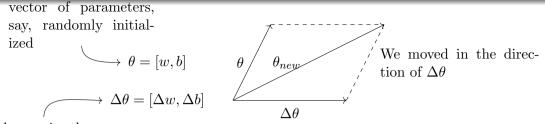
vector of parameters, say, randomly initialized $\theta = [w, b]$

 $\rightarrow \Delta \theta = [\Delta w,$

$$\begin{bmatrix} \theta & \theta_{new} \\ \Delta b \end{bmatrix} \xrightarrow{} \Delta \theta$$

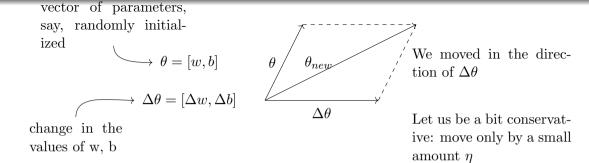
change in the values of w, b

◆□ > ◆母 > ◆臣 > ◆臣 > 善臣 - のへで



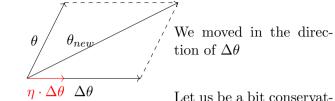
change in the values of w, b

◆□ > ◆母 > ◆臣 > ◆臣 > ○ ● ● ● ●



 $\longrightarrow \theta = [w, b]$

 $\Delta \theta = [\Delta w, \Delta b]$



change in the values of w, b

Let us be a bit conservative: move only by a small amount η

 $\longrightarrow \theta = [w, b]$

7

- 7

We moved in the direction of $\Delta \theta$

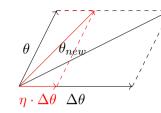
Let us be a bit conservative: move only by a small amount η

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへで

change in the values of w, b

$$\longrightarrow \theta = [w, b]$$

$$\longrightarrow \Delta \theta = [\Delta w, \Delta b]$$



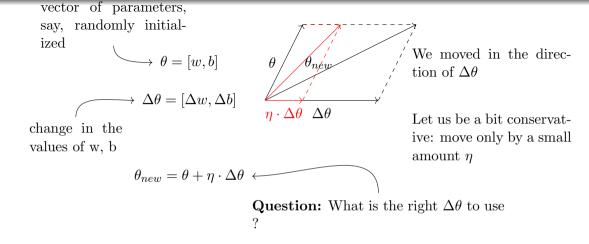
We moved in the direction of $\Delta \theta$

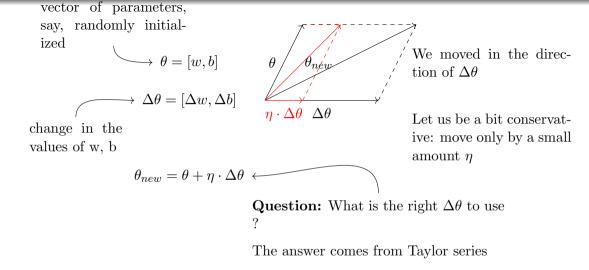
Let us be a bit conservative: move only by a small amount η

▲□▶ ▲御▶ ▲臣▶ ▲臣▶ ―臣 …のへで

change in the values of w, b

$$\theta_{new} = \theta + \eta \cdot \Delta \theta$$





Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

▲□▶ ▲圖▶ ▲圖▶ ▲圖▶ / 圖 / のへで

$$\mathscr{L}(\theta + \eta u) = \mathscr{L}(\theta) + \eta * u^T \nabla_{\theta} \mathscr{L}(\theta) + \frac{\eta^2}{2!} * u^T \nabla^2 \mathscr{L}(\theta) u + \frac{\eta^3}{3!} * \dots + \frac{\eta^4}{4!} * \dots$$

▲□▶ ▲圖▶ ▲圖▶ ▲圖▶ / 圖 / のへで

$$\begin{aligned} \mathscr{L}(\theta + \eta u) &= \mathscr{L}(\theta) + \eta * u^T \nabla_{\theta} \mathscr{L}(\theta) + \frac{\eta^2}{2!} * u^T \nabla^2 \mathscr{L}(\theta) u + \frac{\eta^3}{3!} * \dots + \frac{\eta^4}{4!} * \dots \\ &= \mathscr{L}(\theta) + \eta * u^T \nabla_{\theta} \mathscr{L}(\theta) \; [\eta \; is \; typically \; small, \; so \; \eta^2, \eta^3, \dots \to 0] \end{aligned}$$

▲□▶ ▲圖▶ ▲圖▶ ▲圖▶ / 圖 / のへで

$$\begin{aligned} \mathscr{L}(\theta + \eta u) &= \mathscr{L}(\theta) + \eta * u^T \nabla_{\theta} \mathscr{L}(\theta) + \frac{\eta^2}{2!} * u^T \nabla^2 \mathscr{L}(\theta) u + \frac{\eta^3}{3!} * \dots + \frac{\eta^4}{4!} * \dots \\ &= \mathscr{L}(\theta) + \eta * u^T \nabla_{\theta} \mathscr{L}(\theta) \ [\eta \ is \ typically \ small, \ so \ \eta^2, \eta^3, \dots \to 0] \end{aligned}$$

Note that the move (ηu) would be favorable only if,

 $\mathscr{L}(\theta + \eta u) - \mathscr{L}(\theta) < 0$ [i.e., if the new loss is less than the previous loss]

$$\begin{aligned} \mathscr{L}(\theta + \eta u) &= \mathscr{L}(\theta) + \eta * u^T \nabla_{\theta} \mathscr{L}(\theta) + \frac{\eta^2}{2!} * u^T \nabla^2 \mathscr{L}(\theta) u + \frac{\eta^3}{3!} * \dots + \frac{\eta^4}{4!} * \dots \\ &= \mathscr{L}(\theta) + \eta * u^T \nabla_{\theta} \mathscr{L}(\theta) \ [\eta \ is \ typically \ small, \ so \ \eta^2, \eta^3, \dots \to 0] \end{aligned}$$

Note that the move (ηu) would be favorable only if,

 $\mathscr{L}(\theta + \eta u) - \mathscr{L}(\theta) < 0$ [i.e., if the new loss is less than the previous loss]

This implies,

$$u^T \nabla_{\theta} \mathscr{L}(\theta) < 0$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへで

$u^T \nabla_{\theta} \mathscr{L}(\theta) < 0$

But, what is the range of $u^T \nabla_{\theta} \mathscr{L}(\theta)$?

▲□▶ ▲御▶ ▲臣▶ ▲臣▶ ―臣 …のへで

$u^T \nabla_{\theta} \mathscr{L}(\theta) < 0$

But, what is the range of $u^T \nabla_{\theta} \mathscr{L}(\theta)$? Let us see....

・ロト ・ 四ト ・ ヨト ・ ヨト

$u^T \nabla_{\theta} \mathscr{L}(\theta) < 0$

But, what is the range of $u^T \nabla_{\theta} \mathscr{L}(\theta)$? Let us see.... Let β be the angle between u and $\nabla_{\theta} \mathscr{L}(\theta)$, then we know that,

$u^T \nabla_{\theta} \mathscr{L}(\theta) < 0$

But, what is the range of $u^T \nabla_{\theta} \mathscr{L}(\theta)$? Let us see.... Let β be the angle between u and $\nabla_{\theta} \mathscr{L}(\theta)$, then we know that,

$$-1 \le \cos(\beta) = \frac{u^T \nabla_{\theta} \mathscr{L}(\theta)}{||u|| \ast ||\nabla_{\theta} \mathscr{L}(\theta)||} \le 1$$

$u^T \nabla_{\theta} \mathscr{L}(\theta) < 0$

But, what is the range of $u^T \nabla_{\theta} \mathscr{L}(\theta)$? Let us see.... Let β be the angle between u and $\nabla_{\theta} \mathscr{L}(\theta)$, then we know that,

$$-1 \le \cos(\beta) = \frac{u^T \nabla_{\theta} \mathscr{L}(\theta)}{||u|| \ast ||\nabla_{\theta} \mathscr{L}(\theta)||} \le 1$$

$u^T \nabla_{\theta} \mathscr{L}(\theta) < 0$

But, what is the range of $u^T \nabla_{\theta} \mathscr{L}(\theta)$? Let us see.... Let β be the angle between u and $\nabla_{\theta} \mathscr{L}(\theta)$, then we know that,

$$-1 \le \cos(\beta) = \frac{u^T \nabla_{\theta} \mathscr{L}(\theta)}{||u|| * ||\nabla_{\theta} \mathscr{L}(\theta)||} \le 1$$

multiply throughout by $k = ||u|| * ||\nabla_{\theta} \mathscr{L}(\theta)||$

$$-k \leq k * \cos(\beta) = u^T \nabla_{\theta} \mathscr{L}(\theta) \leq k$$

$$u^T \nabla_{\theta} \mathscr{L}(\theta) < 0$$

But, what is the range of $u^T \nabla_{\theta} \mathscr{L}(\theta)$? Let us see.... Let β be the angle between u and $\nabla_{\theta} \mathscr{L}(\theta)$, then we know that,

$$-1 \le \cos(\beta) = \frac{u^T \nabla_{\theta} \mathscr{L}(\theta)}{||u|| * ||\nabla_{\theta} \mathscr{L}(\theta)||} \le 1$$

multiply throughout by $k = ||u|| * ||\nabla_{\theta} \mathscr{L}(\theta)||$

$$-k \le k * \cos(\beta) = u^T \nabla_{\theta} \mathscr{L}(\theta) \le k$$

Thus, $\mathscr{L}(\theta + \eta u) - \mathscr{L}(\theta) = u^T \nabla_{\theta} \mathscr{L}(\theta) = k * \cos(\beta)$ will be most negative when $\cos(\beta) = -1$ *i.e.*, when β is 180°

▲ロ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ● ● ● ● ● ●

• The direction u that we intend to move in should be at 180° w.r.t. the gradient

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

30/62

- The direction u that we intend to move in should be at 180° w.r.t. the gradient
- In other words, move in a direction opposite to the gradient

- The direction u that we intend to move in should be at 180° w.r.t. the gradient
- In other words, move in a direction opposite to the gradient

Parameter Update Equations

$$w_{t+1} = w_t - \eta \nabla w_t$$

$$b_{t+1} = b_t - \eta \nabla b_t$$

$$where, \nabla w_t = \frac{\partial \mathscr{L}(w, b)}{\partial w}_{at \ w = w_t, b = b_t}, \nabla b = \frac{\partial \mathscr{L}(w, b)}{\partial b}_{at \ w = w_t, b = b_t}$$

▲ロ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ● ● ● ● ● ●

- The direction u that we intend to move in should be at 180° w.r.t. the gradient
- In other words, move in a direction opposite to the gradient

Parameter Update Equations

$$w_{t+1} = w_t - \eta \nabla w_t$$

$$b_{t+1} = b_t - \eta \nabla b_t$$

$$where, \nabla w_t = \frac{\partial \mathscr{L}(w, b)}{\partial w}_{at \ w = w_t, b = b_t}, \nabla b = \frac{\partial \mathscr{L}(w, b)}{\partial b}_{at \ w = w_t, b = b_t}$$

So we now have a more principled way of moving in the w-b plane than our "guess work" algorithm

▲ロ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ● ● ● ● ● ●

• Let us create an algorithm from this rule ...

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへで

• Let us create an algorithm from this rule ...

Algorithm: gradient_descent()

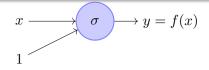
 $\begin{array}{l} t \leftarrow 0;\\ max_iterations \leftarrow 1000;\\ \textbf{while } t < max_iterations \ \textbf{do} \\ \middle| \begin{array}{c} w_{t+1} \leftarrow w_t - \eta \nabla w_t;\\ b_{t+1} \leftarrow b_t - \eta \nabla b_t;\\ t \leftarrow t+1; \end{array} \\ \textbf{end} \end{array}$

• Let us create an algorithm from this rule ...

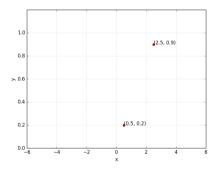
Algorithm: gradient_descent()

 $\begin{array}{l}t \leftarrow 0;\\max_iterations \leftarrow 1000;\\ \textbf{while } t < max_iterations \ \textbf{do}\\ & \left|\begin{array}{c}w_{t+1} \leftarrow w_t - \eta \nabla w_t;\\b_{t+1} \leftarrow b_t - \eta \nabla b_t;\\t \leftarrow t+1;\end{array}\right.\\ \textbf{end}\end{array}$

• To see this algorithm in practice let us first derive ∇w and ∇b for our toy neural network

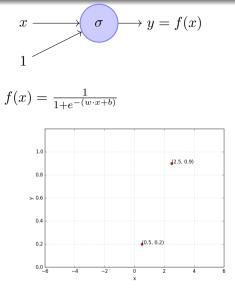


 $f(x) = \frac{1}{1 + e^{-(w \cdot x + b)}}$



Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

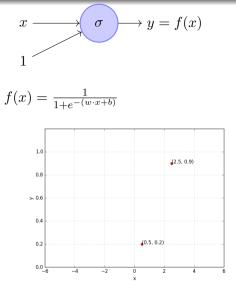
<□ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □



Let's assume there is only 1 point to fit (x, y)

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 - のへで

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

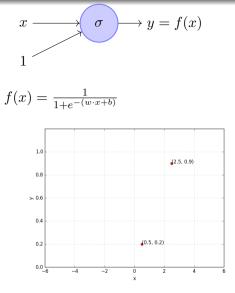


Let's assume there is only 1 point to fit (x, y)

$$\mathscr{L}(w,b) = \frac{1}{2} * (f(x) - y)^2$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 - のへで

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



Let's assume there is only 1 point to fit (x, y)

$$\mathcal{L}(w,b) = \frac{1}{2} * (f(x) - y)^2$$
$$\nabla w = \frac{\partial \mathcal{L}(w,b)}{\partial w} = \frac{\partial}{\partial w} [\frac{1}{2} * (f(x) - y)^2]$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 - のへで

$$\nabla w = \frac{\partial}{\partial w} \left[\frac{1}{2} * (f(x) - y)^2\right]$$

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

◆□ → < 畳 → < Ξ → < Ξ → Ξ の Q ○ 33/62</p>

$$\nabla w = \frac{\partial}{\partial w} \left[\frac{1}{2} * (f(x) - y)^2 \right]$$
$$= \frac{1}{2} * \left[2 * (f(x) - y) * \frac{\partial}{\partial w} (f(x) - y) \right]$$

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

◆□ → < 畳 → < Ξ → < Ξ → Ξ の Q ○ 33/62</p>

$$\nabla w = \frac{\partial}{\partial w} \left[\frac{1}{2} * (f(x) - y)^2 \right]$$

= $\frac{1}{2} * \left[2 * (f(x) - y) * \frac{\partial}{\partial w} (f(x) - y) \right]$
= $(f(x) - y) * \frac{\partial}{\partial w} (f(x))$

◆□ → < 畳 → < Ξ → < Ξ → Ξ の Q ○ 33/62</p>

$$\nabla w = \frac{\partial}{\partial w} \left[\frac{1}{2} * (f(x) - y)^2 \right]$$

= $\frac{1}{2} * \left[2 * (f(x) - y) * \frac{\partial}{\partial w} (f(x) - y) \right]$
= $(f(x) - y) * \frac{\partial}{\partial w} (f(x))$
= $(f(x) - y) * \frac{\partial}{\partial w} \left(\frac{1}{1 + e^{-(wx+b)}} \right)$

◆□ → < 畳 → < Ξ → < Ξ → Ξ の Q ○ 33/62</p>

$$\nabla w = \frac{\partial}{\partial w} \left[\frac{1}{2} * (f(x) - y)^2 \right]$$

= $\frac{1}{2} * \left[2 * (f(x) - y) * \frac{\partial}{\partial w} (f(x) - y) \right]$
= $(f(x) - y) * \frac{\partial}{\partial w} (f(x))$
= $(f(x) - y) * \frac{\partial}{\partial w} \left(\frac{1}{1 + e^{-(wx+b)}} \right)$

$$\frac{\partial}{\partial w} \Big(\frac{1}{1 + e^{-(wx+b)}} \Big)$$

◆□ → < □ → < Ξ → < Ξ → Ξ の Q ↔ 33/62</p>

$$\nabla w = \frac{\partial}{\partial w} \left[\frac{1}{2} * (f(x) - y)^2 \right]$$

= $\frac{1}{2} * \left[2 * (f(x) - y) * \frac{\partial}{\partial w} (f(x) - y) \right]$
= $(f(x) - y) * \frac{\partial}{\partial w} (f(x))$
= $(f(x) - y) * \frac{\partial}{\partial w} \left(\frac{1}{1 + e^{-(wx+b)}} \right)$

$$\begin{split} & \frac{\partial}{\partial w} \Big(\frac{1}{1 + e^{-(wx+b)}} \Big) \\ & = \frac{-1}{(1 + e^{-(wx+b)})^2} \frac{\partial}{\partial w} (e^{-(wx+b)})) \end{split}$$

◆□ → < 畳 → < Ξ → < Ξ → Ξ の Q ○ 33/62</p>

$$\begin{aligned} \nabla w &= \frac{\partial}{\partial w} \left[\frac{1}{2} * (f(x) - y)^2 \right] \\ &= \frac{1}{2} * \left[2 * (f(x) - y) * \frac{\partial}{\partial w} (f(x) - y) \right] \\ &= (f(x) - y) * \frac{\partial}{\partial w} (f(x)) \\ &= (f(x) - y) * \frac{\partial}{\partial w} (f(x)) \\ &= (f(x) - y) * \frac{\partial}{\partial w} \left(\frac{1}{1 + e^{-(wx+b)}} \right) \end{aligned} \qquad \begin{aligned} &= \frac{\partial}{\partial w} \left(\frac{1}{1 + e^{-(wx+b)}} \right) \\ &= \frac{-1}{(1 + e^{-(wx+b)})^2} \frac{\partial}{\partial w} (e^{-(wx+b)}) \\ &= \frac{-1}{(1 + e^{-(wx+b)})^2} * (e^{-(wx+b)}) \frac{\partial}{\partial w} (-(wx+b)) \end{aligned}$$

◆□ → < 畳 → < Ξ → < Ξ → Ξ の Q ○ 33/62</p>

$$\begin{aligned} \nabla w &= \frac{\partial}{\partial w} \left[\frac{1}{2} * (f(x) - y)^2 \right] \\ &= \frac{1}{2} * \left[2 * (f(x) - y) * \frac{\partial}{\partial w} (f(x) - y) \right] \\ &= (f(x) - y) * \frac{\partial}{\partial w} (f(x)) \\ &= (f(x) - y) * \frac{\partial}{\partial w} (f(x)) \\ &= (f(x) - y) * \frac{\partial}{\partial w} \left(\frac{1}{1 + e^{-(wx+b)}} \right) \end{aligned} \qquad \begin{aligned} &= \frac{-1}{(1 + e^{-(wx+b)})^2} \frac{\partial}{\partial w} (e^{-(wx+b)})) \\ &= \frac{-1}{(1 + e^{-(wx+b)})^2} * (e^{-(wx+b)}) \frac{\partial}{\partial w} (-(wx+b))) \\ &= \frac{-1}{(1 + e^{-(wx+b)})} * \frac{e^{-(wx+b)}}{(1 + e^{-(wx+b)})} * (-x) \end{aligned}$$

< □ > < □ > < □ > < Ξ > < Ξ > Ξ の Q ↔ 33/62

$$\nabla w = \frac{\partial}{\partial w} \left[\frac{1}{2} * (f(x) - y)^2 \right]$$

= $\frac{1}{2} * \left[2 * (f(x) - y) * \frac{\partial}{\partial w} (f(x) - y) \right]$
= $(f(x) - y) * \frac{\partial}{\partial w} (f(x))$
= $(f(x) - y) * \frac{\partial}{\partial w} \left(\frac{1}{1 + e^{-(wx+b)}} \right)$

$$\begin{split} &\frac{\partial}{\partial w} \Big(\frac{1}{1+e^{-(wx+b)}} \Big) \\ &= \frac{-1}{(1+e^{-(wx+b)})^2} \frac{\partial}{\partial w} (e^{-(wx+b)})) \\ &= \frac{-1}{(1+e^{-(wx+b)})^2} * (e^{-(wx+b)}) \frac{\partial}{\partial w} (-(wx+b))) \\ &= \frac{-1}{(1+e^{-(wx+b)})} * \frac{e^{-(wx+b)}}{(1+e^{-(wx+b)})} * (-x) \\ &= \frac{1}{(1+e^{-(wx+b)})} * \frac{e^{-(wx+b)}}{(1+e^{-(wx+b)})} * (x) \end{split}$$

◆□ → < □ → < Ξ → < Ξ → Ξ の Q ↔ 33/62</p>

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

$$\begin{aligned} \nabla w &= \frac{\partial}{\partial w} [\frac{1}{2} * (f(x) - y)^2] \\ &= \frac{1}{2} * [2 * (f(x) - y) * \frac{\partial}{\partial w} (f(x) - y)] \\ &= (f(x) - y) * \frac{\partial}{\partial w} (f(x)) \\ &= (f(x) - y) * \frac{\partial}{\partial w} \Big(\frac{1}{1 + e^{-(wx + b)}} \Big) \\ &= (f(x) - y) * f(x) * (1 - f(x)) * x \end{aligned}$$

$$\frac{\partial}{\partial w} \left(\frac{1}{1 + e^{-(wx+b)}} \right)$$

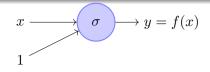
$$= \frac{-1}{(1 + e^{-(wx+b)})^2} \frac{\partial}{\partial w} (e^{-(wx+b)}))$$

$$= \frac{-1}{(1 + e^{-(wx+b)})^2} * (e^{-(wx+b)}) \frac{\partial}{\partial w} (-(wx+b)))$$

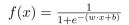
$$= \frac{-1}{(1 + e^{-(wx+b)})} * \frac{e^{-(wx+b)}}{(1 + e^{-(wx+b)})} * (-x)$$

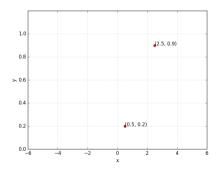
$$= \frac{1}{(1 + e^{-(wx+b)})} * \frac{e^{-(wx+b)}}{(1 + e^{-(wx+b)})} * (x)$$

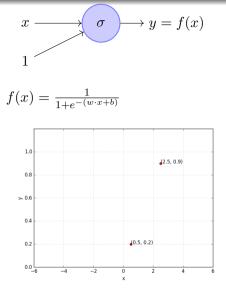
$$= f(x) * (1 - f(x)) * x$$



◆□▶ ◆□▶ ◆□▶ ◆□▶ □ ○ ○ ○ ○



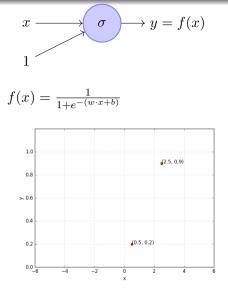




$$\nabla w = (f(x) - y) * f(x) * (1 - f(x)) * x$$

◆□▶ ◆□▶ ◆□▶ ◆□▶ □ ○ ○ ○ ○

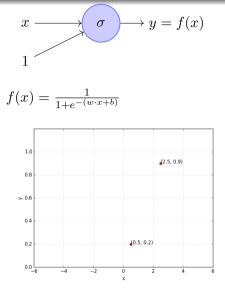
Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



$$\nabla w = (f(x) - y) * f(x) * (1 - f(x)) * x$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへで

For two points,

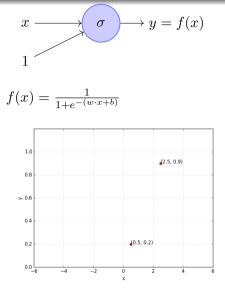


$$\nabla w = (f(x) - y) * f(x) * (1 - f(x)) * x$$

For two points,

$$\nabla w = \sum_{i=1}^{2} (f(x_i) - y_i) * f(x_i) * (1 - f(x_i)) * x_i$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへで



$$\nabla w = (f(x) - y) * f(x) * (1 - f(x)) * x$$

For two points,

$$\nabla w = \sum_{i=1}^{2} (f(x_i) - y_i) * f(x_i) * (1 - f(x_i)) * x_i$$
$$\nabla b = \sum_{i=1}^{2} (f(x_i) - y_i) * f(x_i) * (1 - f(x_i))$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへで

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

X = [0.5, 2.5]Y = [0.2, 0.9]

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

◆□ → < 畳 → < Ξ → < Ξ → Ξ の Q ○ 35/62</p>



def f(w,b,x) : #sigmoid with parameters w,b
 return 1.0 / (1.0 + np.exp(-(w*x + b)))

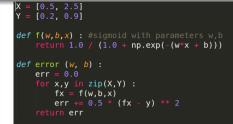
Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

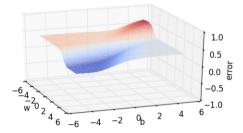
<□ > < 母 > < ≧ > < ≧ > ≧ > りへで 35/62

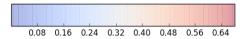
	[0.5, 2.5] [0.2, 0.9]
def	<pre>f(w,b,x) : #sigmoid with parameters w, return 1.0 / (1.0 + np.exp(-(w*x + b))</pre>
def	<pre>error (w, b) : err = 0.0 for x,y in zip(X,Y) : fx = f(w,b,x) err += 0.5 * (fx - y) ** 2 return err</pre>

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

< □ ▶ < 酉 ▶ < 壹 ▶ < 壹 ▶ Ξ ∽ Q ^Q _{35/62}

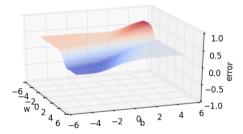


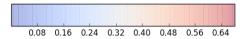




Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

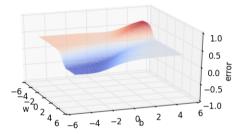


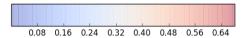




Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

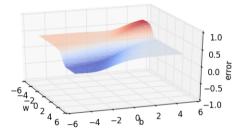






▲口 > ▲ □ > ▲ □ > ▲ □ > ▲ □ > ▲ □ > ▲ □ > ▲ □ > ▲ □ >

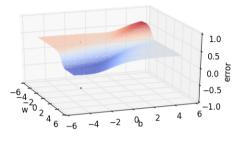








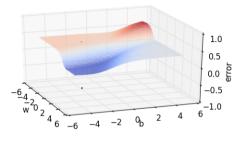
Gradient descent on the error surface







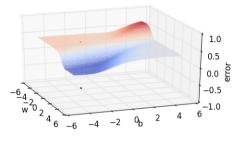
Gradient descent on the error surface







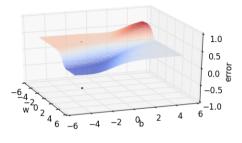
Gradient descent on the error surface







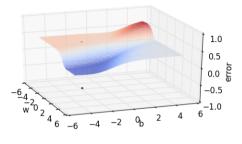
Gradient descent on the error surface







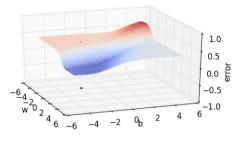
Gradient descent on the error surface







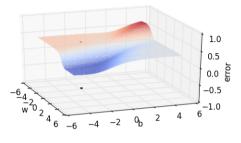
Gradient descent on the error surface







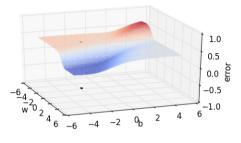
Gradient descent on the error surface







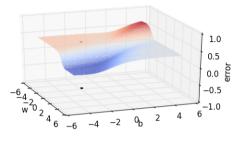
Gradient descent on the error surface







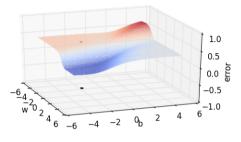
Gradient descent on the error surface







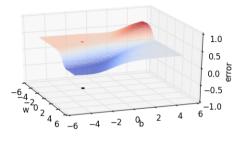
Gradient descent on the error surface







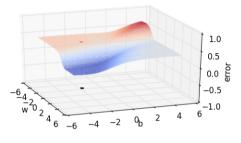
Gradient descent on the error surface







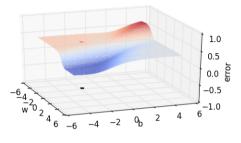
Gradient descent on the error surface







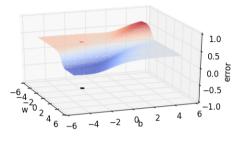
Gradient descent on the error surface







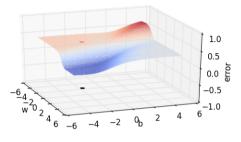
Gradient descent on the error surface







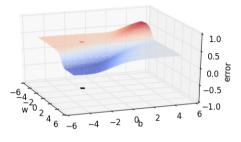
Gradient descent on the error surface







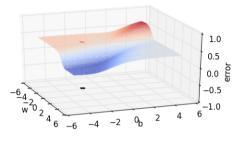
Gradient descent on the error surface







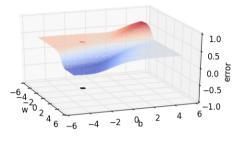
Gradient descent on the error surface







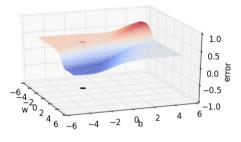
Gradient descent on the error surface







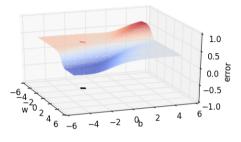
Gradient descent on the error surface







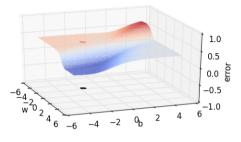
Gradient descent on the error surface







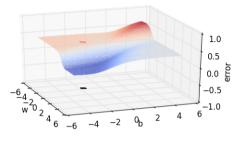
Gradient descent on the error surface







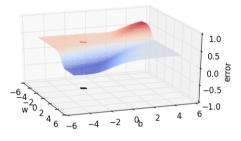
Gradient descent on the error surface







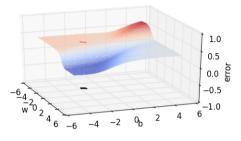
Gradient descent on the error surface







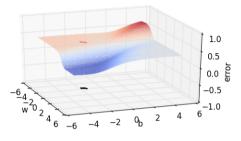
Gradient descent on the error surface







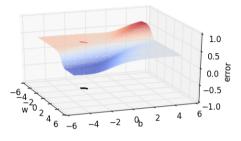
Gradient descent on the error surface







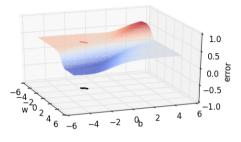
Gradient descent on the error surface







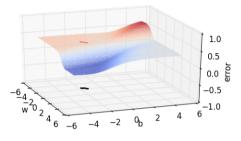
Gradient descent on the error surface







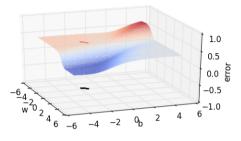
Gradient descent on the error surface







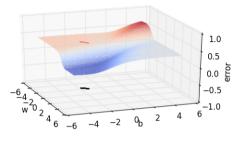
Gradient descent on the error surface







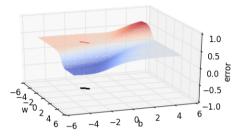
Gradient descent on the error surface







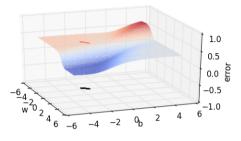
Gradient descent on the error surface







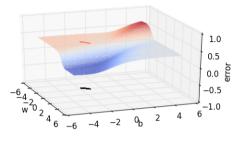
Gradient descent on the error surface







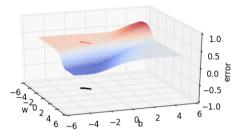
Gradient descent on the error surface







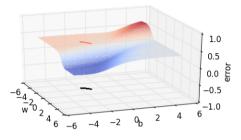
Gradient descent on the error surface







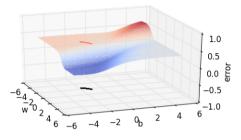
Gradient descent on the error surface







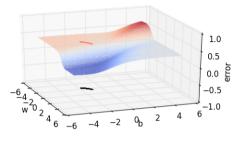
Gradient descent on the error surface







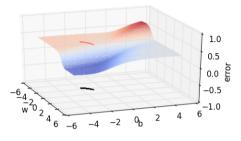
Gradient descent on the error surface







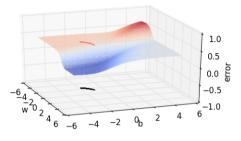
Gradient descent on the error surface







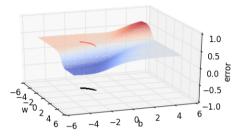
Gradient descent on the error surface







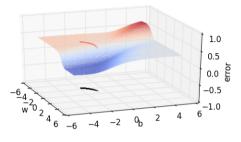
Gradient descent on the error surface







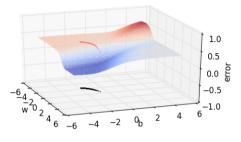
Gradient descent on the error surface







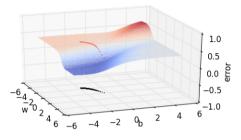
Gradient descent on the error surface







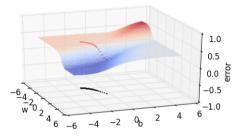
Gradient descent on the error surface







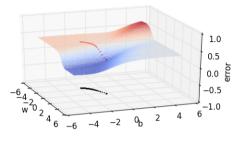
Gradient descent on the error surface







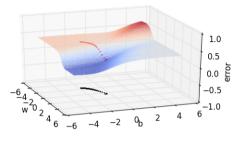
Gradient descent on the error surface







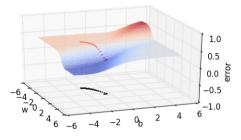
Gradient descent on the error surface







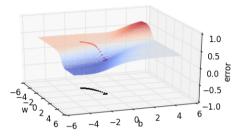
Gradient descent on the error surface







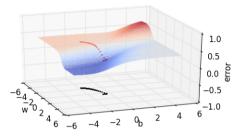
Gradient descent on the error surface







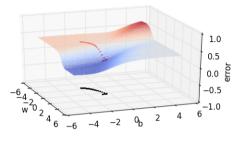
Gradient descent on the error surface







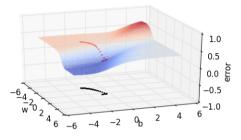
Gradient descent on the error surface







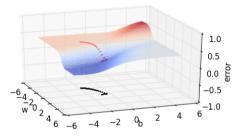
Gradient descent on the error surface







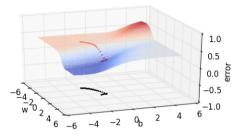
Gradient descent on the error surface







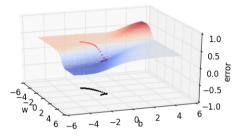
Gradient descent on the error surface







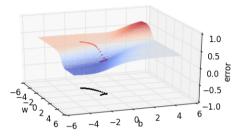
Gradient descent on the error surface







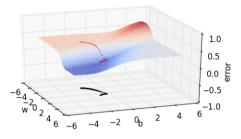
Gradient descent on the error surface







Gradient descent on the error surface

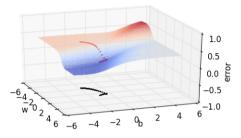




Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



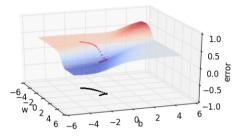
Gradient descent on the error surface







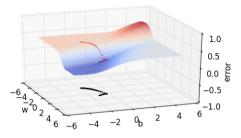
Gradient descent on the error surface







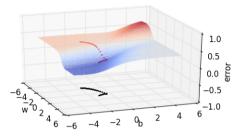
Gradient descent on the error surface







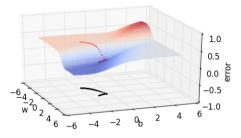
Gradient descent on the error surface







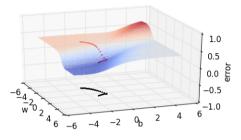
Gradient descent on the error surface







Gradient descent on the error surface

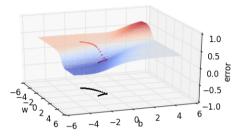




Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



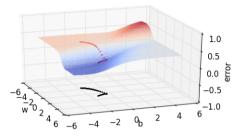
Gradient descent on the error surface







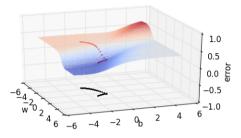
Gradient descent on the error surface







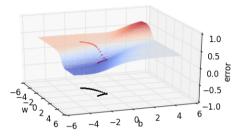
Gradient descent on the error surface







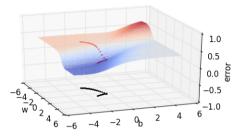
Gradient descent on the error surface







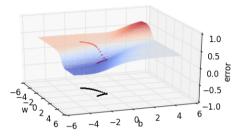
Gradient descent on the error surface







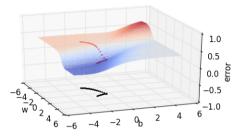
Gradient descent on the error surface







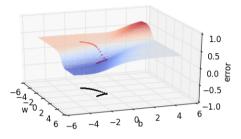
Gradient descent on the error surface

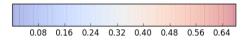






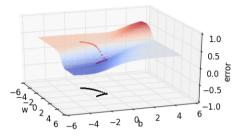
Gradient descent on the error surface







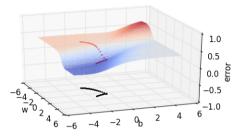
Gradient descent on the error surface







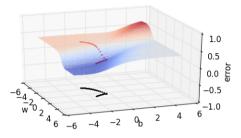
Gradient descent on the error surface







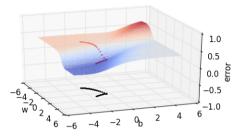
Gradient descent on the error surface







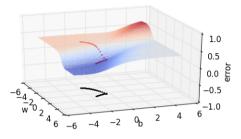
Gradient descent on the error surface







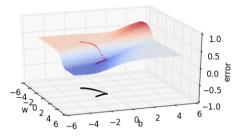
Gradient descent on the error surface







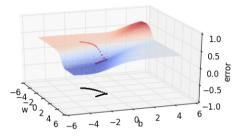
Gradient descent on the error surface







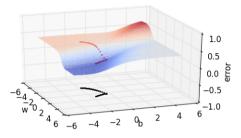
Gradient descent on the error surface







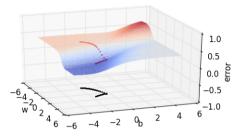
Gradient descent on the error surface







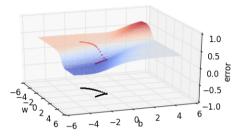
Gradient descent on the error surface







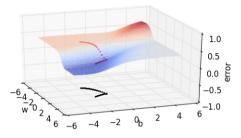
Gradient descent on the error surface







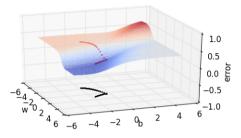
Gradient descent on the error surface







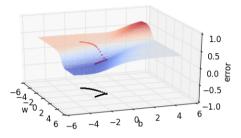
Gradient descent on the error surface







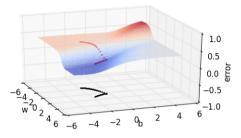
Gradient descent on the error surface







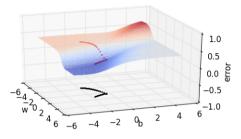
Gradient descent on the error surface







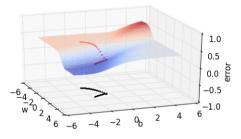
Gradient descent on the error surface







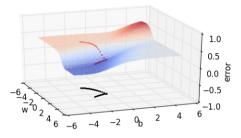
Gradient descent on the error surface







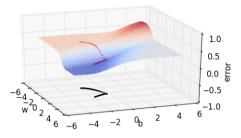
Gradient descent on the error surface







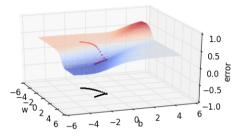
Gradient descent on the error surface







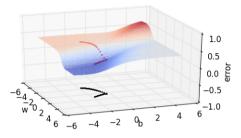
Gradient descent on the error surface







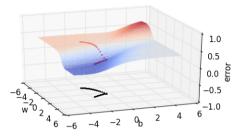
Gradient descent on the error surface







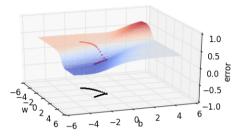
Gradient descent on the error surface







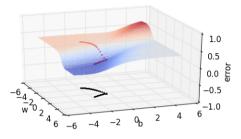
Gradient descent on the error surface







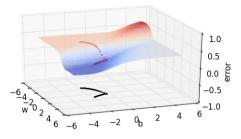
Gradient descent on the error surface







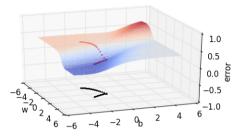
Gradient descent on the error surface







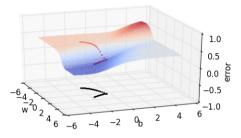
Gradient descent on the error surface







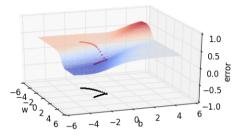
Gradient descent on the error surface







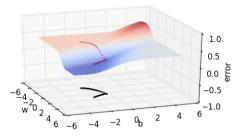
Gradient descent on the error surface







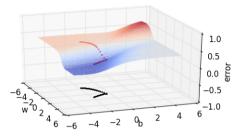
Gradient descent on the error surface







Gradient descent on the error surface





• Later on in the course we will look at gradient descent in much more detail and discuss its variants

▲□▶ ▲圖▶ ▲臣▶ ▲臣▶ 三臣 - のへで

- Later on in the course we will look at gradient descent in much more detail and discuss its variants
- For the time being it suffices to know that we have an algorithm for learning the parameters of a sigmoid neuron

- Later on in the course we will look at gradient descent in much more detail and discuss its variants
- For the time being it suffices to know that we have an algorithm for learning the parameters of a sigmoid neuron
- So where do we head from here ?

イロト イヨト イヨト ヨー りへつ

Module 3.5: Representation Power of a Multilayer Network of Sigmoid Neurons

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

▲ロ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ● ● ● ● ● ●

Representation power of a multilayer network of sigmoid neurons

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

A multilayer network of perceptrons with a single hidden layer can be used to represent any boolean function precisely (no errors) Representation power of a multilayer network of sigmoid neurons

◆□▶ ◆母▶ ◆ヨ▶ ◆ヨ▶ ヨー のへで

A multilayer network of perceptrons with a single hidden layer can be used to represent any boolean function precisely (no errors) Representation power of a multilayer network of sigmoid neurons

A multilayer network of neurons with a single hidden layer can be used to approximate any continuous function to any desired precision

◆□▶ ◆母▶ ◆ヨ▶ ◆ヨ▶ ヨー のへで

A multilayer network of perceptrons with a single hidden layer can be used to represent any boolean function precisely (no errors) Representation power of a multilayer network of sigmoid neurons

A multilayer network of neurons with a single hidden layer can be used to approximate any continuous function to any desired precision

In other words, there is a guarantee that for any function $f(x) : \mathbb{R}^n \to \mathbb{R}^m$, we can always find a neural network (with 1 hidden layer containing enough neurons) whose output g(x) satisfies $|g(x) - f(x)| < \epsilon$!!

◆□▶ ◆母▶ ◆ヨ▶ ◆ヨ▶ ヨー のへで

A multilayer network of perceptrons with a single hidden layer can be used to represent any boolean function precisely (no errors) Representation power of a multilayer network of sigmoid neurons

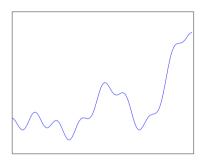
A multilayer network of neurons with a single hidden layer can be used to approximate any continuous function to any desired precision

In other words, there is a guarantee that for any function $f(x) : \mathbb{R}^n \to \mathbb{R}^m$, we can always find a neural network (with 1 hidden layer containing enough neurons) whose output g(x) satisfies $|g(x) - f(x)| < \epsilon$!!

Proof: We will see an illustrative proof of this... [Cybenko, 1989], [Hornik, 1991]

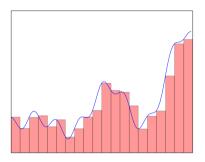
▲□▶ ▲御▶ ▲臣▶ ▲臣▶ ―臣 …のへで

- $\bullet\,$ See this link* for an excellent illustration of this proof
- The discussion in the next few slides is based on the ideas presented at the above link



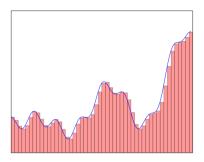
• We are interested in knowing whether a network of neurons can be used to represent an arbitrary function (like the one shown in the figure)

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

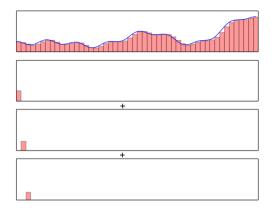


- We are interested in knowing whether a network of neurons can be used to represent an arbitrary function (like the one shown in the figure)
- We observe that such an arbitrary function can be approximated by several "tower" functions

▲ロ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ● ● ● ● ● ●

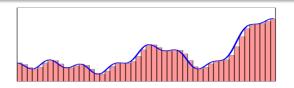


- We are interested in knowing whether a network of neurons can be used to represent an arbitrary function (like the one shown in the figure)
- We observe that such an arbitrary function can be approximated by several "tower" functions
- More the number of such "tower" functions, better the approximation



- We are interested in knowing whether a network of neurons can be used to represent an arbitrary function (like the one shown in the figure)
- We observe that such an arbitrary function can be approximated by several "tower" functions
- More the number of such "tower" functions, better the approximation
- To be more precise, we can approximate any arbitrary function by a sum of such "tower" functions

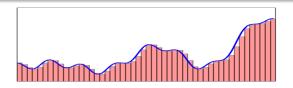
イロト (日本) (日本) (日本) (日本) (日本)



• We make a few observations

◆□▶ ◆圖▶ ◆臣▶ ◆臣▶ ─臣 ─の�?

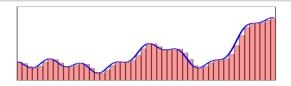
Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



- We make a few observations
- All these "tower" functions are similar and only differ in their heights and positions on the x-axis

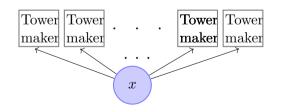
▲ロ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ● ● ● ● ● ●

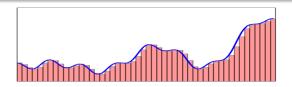
Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



- We make a few observations
- All these "tower" functions are similar and only differ in their heights and positions on the x-axis
- Suppose there is a black box which takes the original input (x) and constructs these tower functions

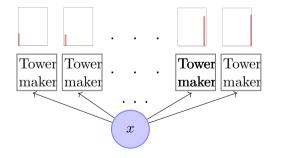
(日本)(日本)(日本)(日本)(日本)



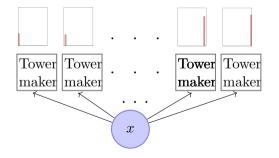


- We make a few observations
- All these "tower" functions are similar and only differ in their heights and positions on the x-axis
- Suppose there is a black box which takes the original input (x) and constructs these tower functions

3

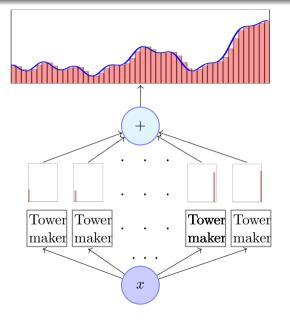






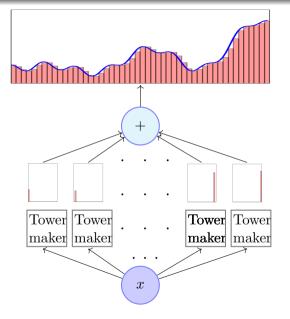
- We make a few observations
- All these "tower" functions are similar and only differ in their heights and positions on the x-axis
- Suppose there is a black box which takes the original input (x) and constructs these tower functions
- We can then have a simple network which can just add them up to approximate the function

-



- We make a few observations
- All these "tower" functions are similar and only differ in their heights and positions on the x-axis
- Suppose there is a black box which takes the original input (x) and constructs these tower functions
- We can then have a simple network which can just add them up to approximate the function

3



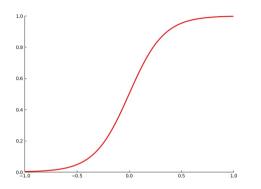
- We make a few observations
- All these "tower" functions are similar and only differ in their heights and positions on the x-axis
- Suppose there is a black box which takes the original input (x) and constructs these tower functions
- We can then have a simple network which can just add them up to approximate the function
- Our job now is to figure out what is inside this blackbox

3

We will figure this out over the next few slides ...

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

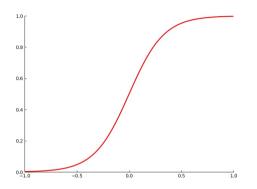
▲□▶ ▲圖▶ ▲ 臣▶ ▲ 臣▶ ― 臣 … のへで



• If we take the logistic function and set w to a very high value we will recover the step function

イロト 不得 トイヨト イヨト

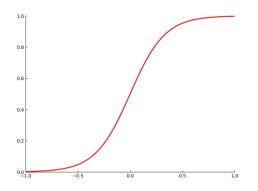
Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

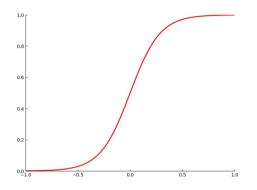
3

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



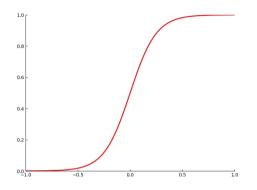
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 0, b = 0$



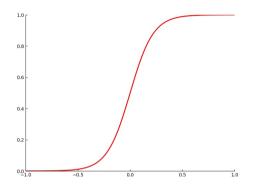
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 1, b = 0$



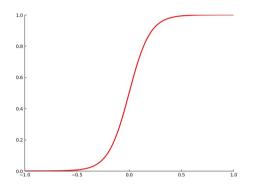
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 2, b = 0$



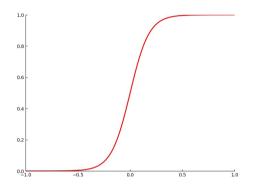
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 3, b = 0$



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

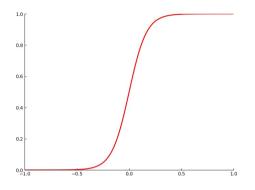
 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 4, b = 0$



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

《日》 《圖》 《日》 《日》

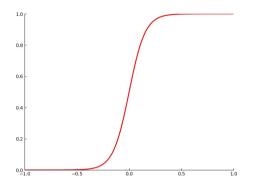
 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 5, b = 0$



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

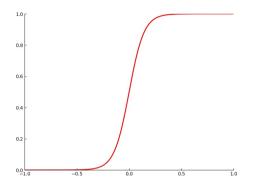
《日》 《圖》 《日》 《日》

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 6, b = 0$



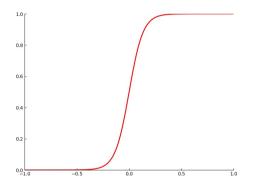
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 7, b = 0$



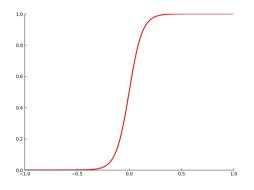
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 8, b = 0$



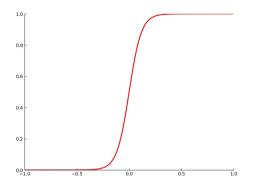
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 9, b = 0$



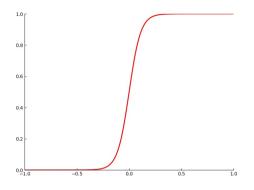
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 10, b = 0$



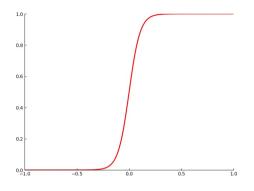
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 11, b = 0$



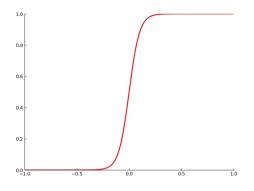
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 12, b = 0$



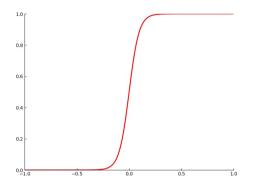
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 13, b = 0$



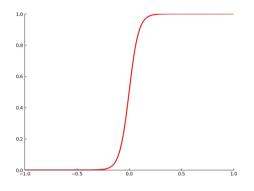
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 14, b = 0$



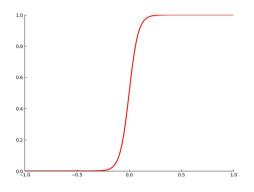
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 15, b = 0$



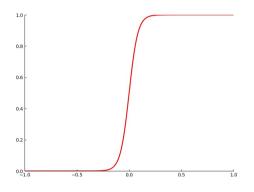
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 16, b = 0$



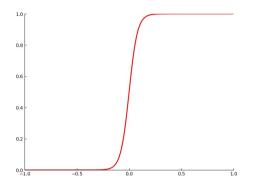
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 17, b = 0$



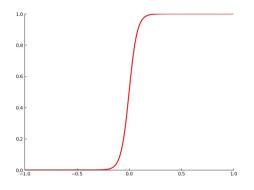
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 18, b = 0$



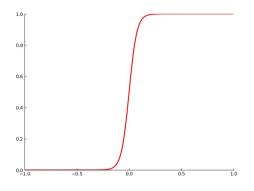
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 19, b = 0$



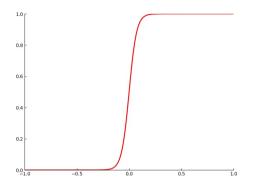
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 20, b = 0$



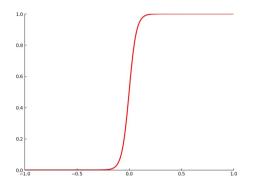
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 21, b = 0$



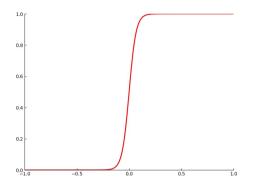
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 22, b = 0$



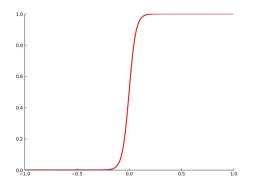
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 23, b = 0$



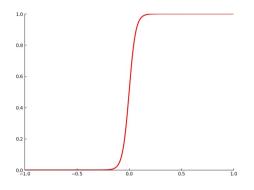
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 24, b = 0$



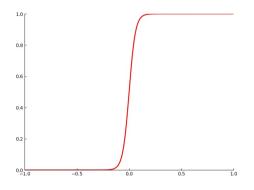
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 25, b = 0$



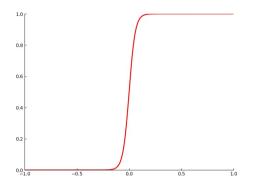
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 26, b = 0$



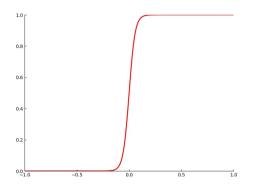
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 27, b = 0$



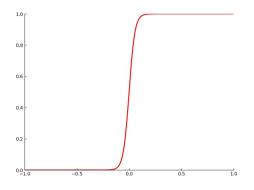
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 28, b = 0$



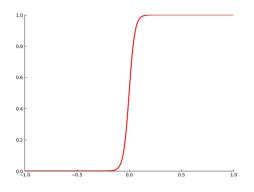
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 29, b = 0$



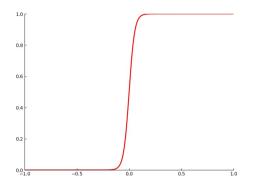
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 30, b = 0$



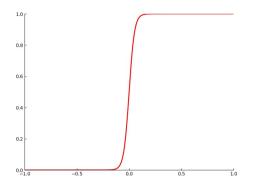
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 31, b = 0$



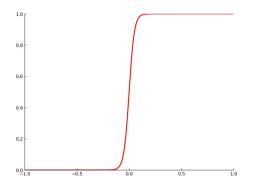
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 32, b = 0$



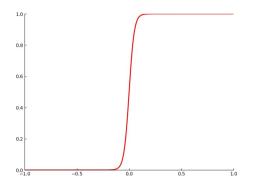
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 33, b = 0$



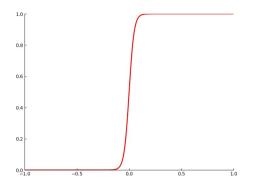
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 34, b = 0$



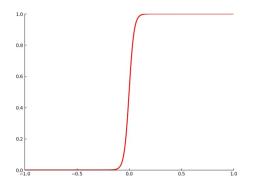
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 35, b = 0$



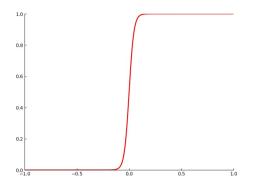
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 36, b = 0$



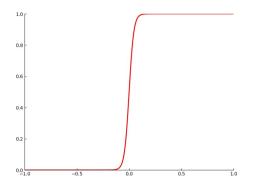
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 37, b = 0$



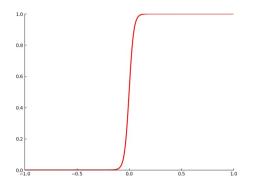
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 38, b = 0$



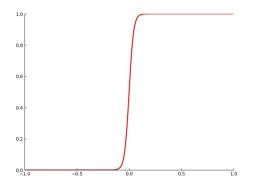
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 39, b = 0$



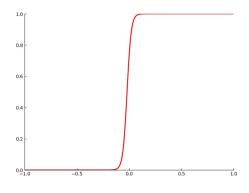
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 40, b = 0$



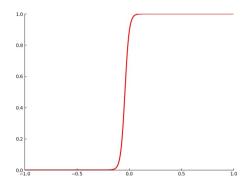
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 41, b = 0$



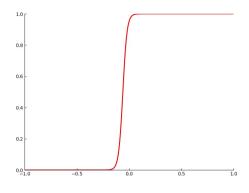
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 1$$



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

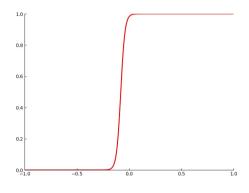
$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 2$$



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

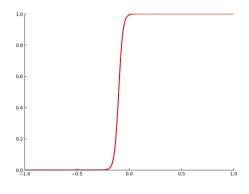
- 御下 - 王下 - 王下

$$\sigma(x) = \frac{1}{1+e^{-(wx+b)}} w = 50, b = 3$$



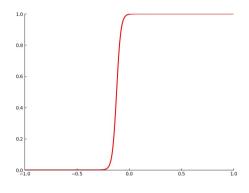
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 4$$



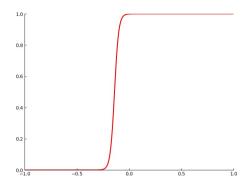
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 5$$



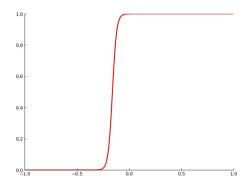
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 6$$



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

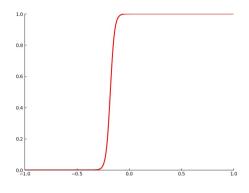
$$\sigma(x) = \frac{1}{1+e^{-(wx+b)}} w = 50, b = 7$$



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

- 4 周 ト 4 日 ト 4 日 ト

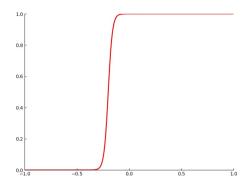
$$\sigma(x) = \frac{1}{1+e^{-(wx+b)}} w = 50, b = 8$$



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

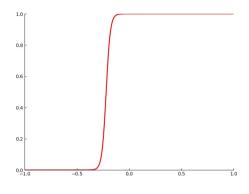
- 4 周 ト 4 日 ト 4 日 ト

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 9$$



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 10$$

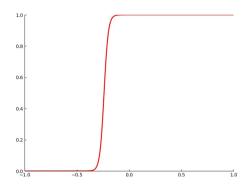


- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

・ロト ・雪ト ・ヨト

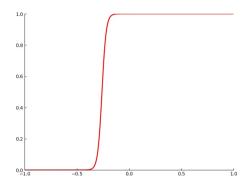
3

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 11$



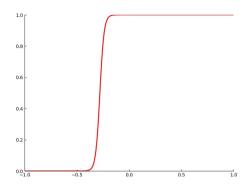
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 12$$



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 13$$

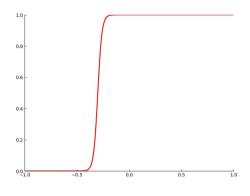


- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

・ロト ・雪ト ・ヨト

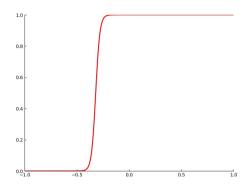
3

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} w = 50, b = 14$



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

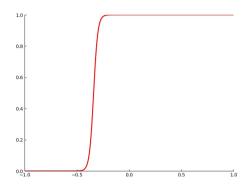
$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 15$$



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

3

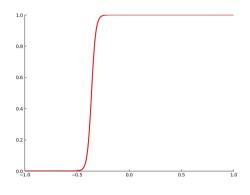
 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} w = 50, b = 16$



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

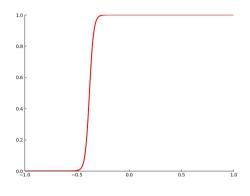
3

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} w = 50, b = 17$



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 18$$

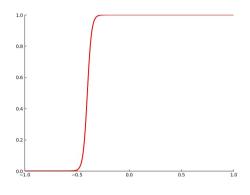


- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

・ロト ・雪ト ・ヨト

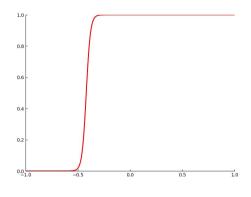
3

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} w = 50, b = 19$



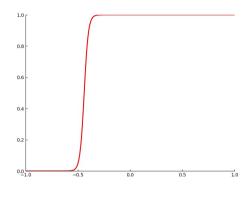
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 20$$



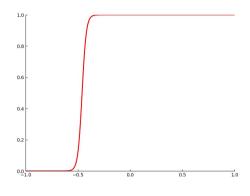
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} w = 50, b = 21$$



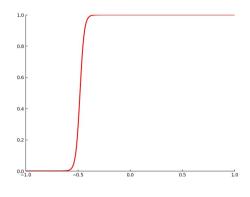
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} w = 50, b = 22$$



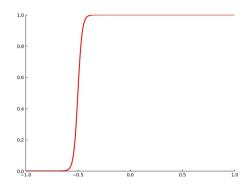
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 23$$



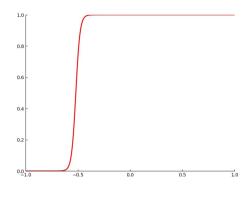
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 24$$



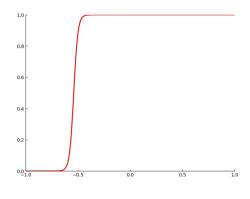
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 25$$



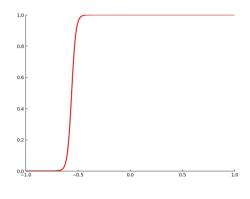
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 26$$



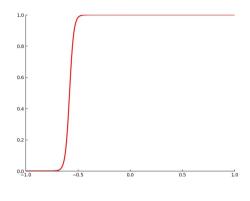
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 27$$



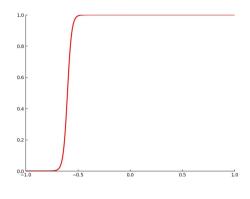
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 28$$



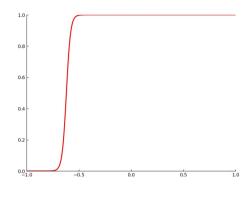
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} w = 50, b = 29$$



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 30$$

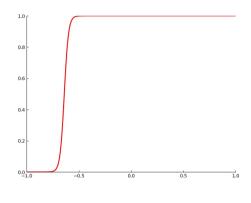


- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

(日本) (日本) (日本)

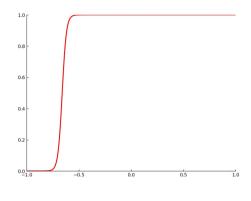
3

 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} w = 50, b = 31$



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

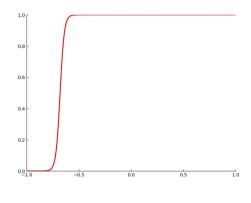
$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} w = 50, b = 32$$



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

э.

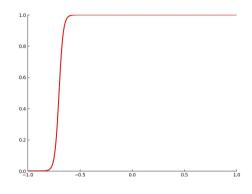
$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} \ w = 50, b = 33$$



- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

э.

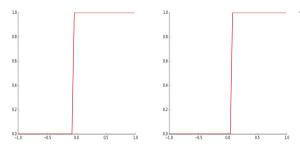
$$\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} w = 50, b = 34$$



 $\sigma(x) = \frac{1}{1 + e^{-(wx+b)}} w = 50, b = 35$

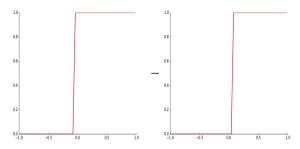
- If we take the logistic function and set w to a very high value we will recover the step function
- Let us see what happens as we change the value of w
- Further we can adjust the value of b to control the position on the x-axis at which the function transitions from 0 to 1

< ロ > (四) (四) (回) (u) (



• Now let us see what we get by taking two such sigmoid functions (with different b's) and subtracting one from the other

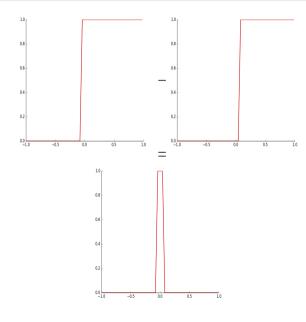
Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



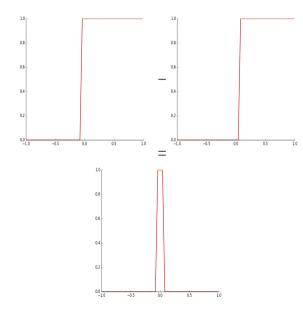
• Now let us see what we get by taking two such sigmoid functions (with different b's) and subtracting one from the other

イロト 不得 トイヨト イヨト

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



• Now let us see what we get by taking two such sigmoid functions (with different b's) and subtracting one from the other

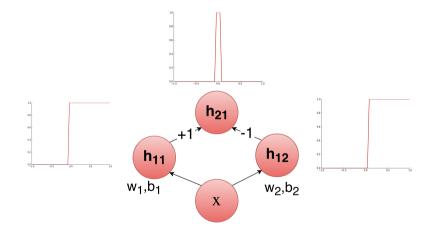


- Now let us see what we get by taking two such sigmoid functions (with different b's) and subtracting one from the other
- Voila! We have our tower function !!

(四) (日) (日)

• Can we come up with a neural network to represent this operation of subtracting one sigmoid function from another ?

46/62



Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

◆□ → < 畳 → < Ξ → < Ξ → Ξ < の Q ○ 47/62</p>

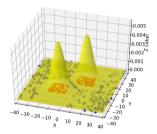
• What if we have more than one input?

▲□▶ ▲圖▶ ▲圖▶ ▲圖▶ / 圖 / のへで

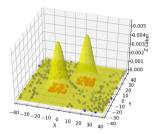
Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

- What if we have more than one input?
- Suppose we are trying to take a decision about whether we will find oil at a particular location on the ocean bed(Yes/No)

- What if we have more than one input?
- Suppose we are trying to take a decision about whether we will find oil at a particular location on the ocean bed(Yes/No)
- Further, suppose we base our decision on two factors: Salinity (x₁) and Pressure (x₂)



- What if we have more than one input?
- Suppose we are trying to take a decision about whether we will find oil at a particular location on the ocean bed(Yes/No)
- Further, suppose we base our decision on two factors: Salinity (x_1) and Pressure (x_2)
- We are given some data and it seems that y(oil|no-oil) is a complex function of x_1 and x_2

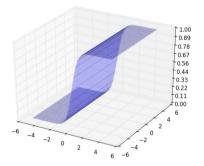


- What if we have more than one input?
- Suppose we are trying to take a decision about whether we will find oil at a particular location on the ocean bed(Yes/No)
- Further, suppose we base our decision on two factors: Salinity (x_1) and Pressure (x_2)
- We are given some data and it seems that y(oil|no-oil) is a complex function of x_1 and x_2
- We want a neural network to approximate this function

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

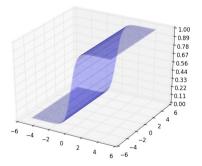
• This is what a 2-dimensional sigmoid looks like

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 - のへで

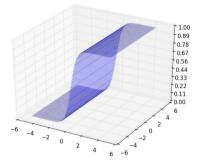


$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case



$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

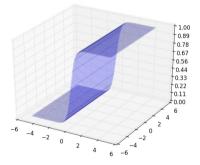


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

3

 $w_1 = 2, w_2 = 0, b = 0$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

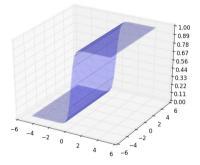


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

3

 $w_1 = 3, w_2 = 0, b = 0$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

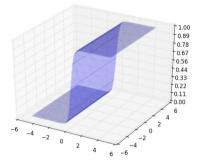


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

3

 $w_1 = 4, w_2 = 0, b = 0$

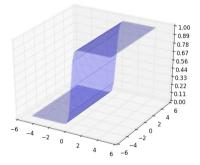
$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

$$w_1 = 5, w_2 = 0, b = 0$$

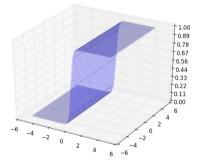
$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

$$w_1 = 6, w_2 = 0, b = 0$$

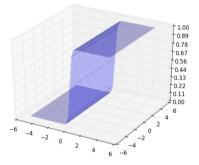
$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

$$w_1 = 7, w_2 = 0, b = 0$$

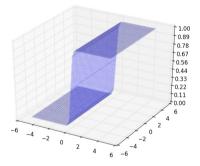
$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

$$w_1 = 8, w_2 = 0, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

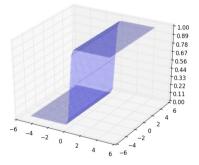


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

3

 $w_1 = 9, w_2 = 0, b = 0$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

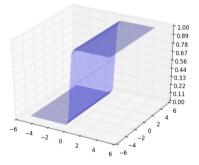


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

3

 $w_1 = 10, w_2 = 0, b = 0$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

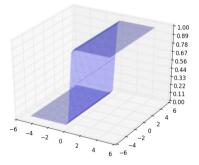


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

3

 $w_1 = 11, w_2 = 0, b = 0$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

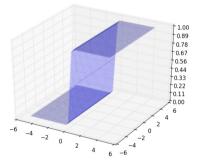


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

3

 $w_1 = 12, w_2 = 0, b = 0$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

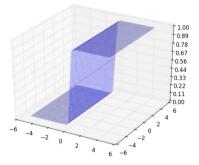


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

3

 $w_1 = 13, w_2 = 0, b = 0$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

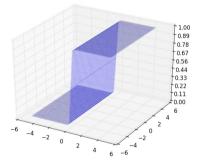


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

3

 $w_1 = 14, w_2 = 0, b = 0$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

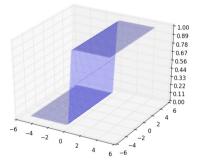


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

3

 $w_1 = 15, w_2 = 0, b = 0$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

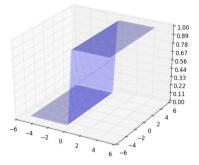


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

3

 $w_1 = 16, w_2 = 0, b = 0$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

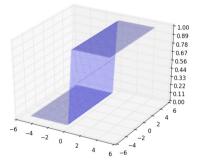


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

3

 $w_1 = 17, w_2 = 0, b = 0$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

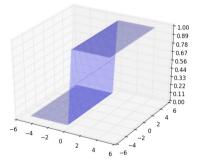


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

3

 $w_1 = 18, w_2 = 0, b = 0$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

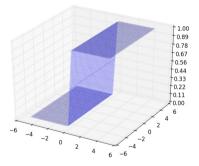


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

3

 $w_1 = 19, w_2 = 0, b = 0$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

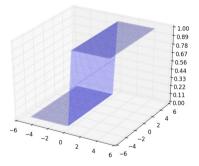


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

3

 $w_1 = 20, w_2 = 0, b = 0$

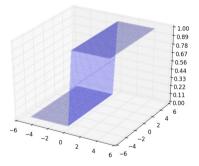
$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

$$w_1 = 21, w_2 = 0, b = 0$$

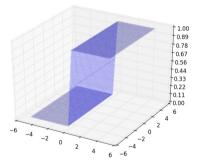
$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

$$w_1 = 22, w_2 = 0, b = 0$$

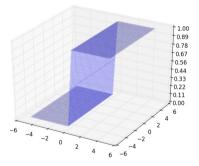
$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

3

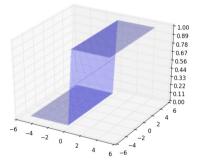
$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function

3

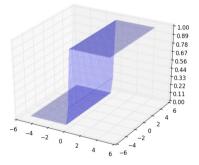
$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function
- What would happen if we change b?

3

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

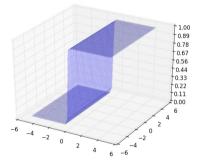


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function
- What would happen if we change b ?

-

$$w_1 = 25, w_2 = 0, b = 5$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

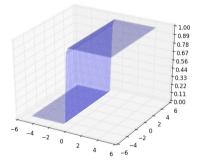


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function
- What would happen if we change b ?

(日本) (日本) (日本)

-

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

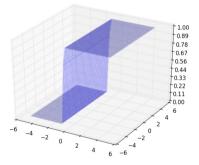


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function
- What would happen if we change b ?

(日本) (日本) (日本)

-

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

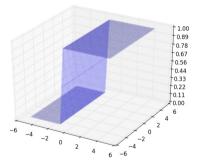


- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function
- What would happen if we change b ?

(日本) (日本) (日本)

-

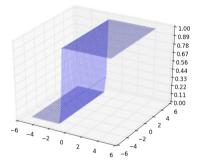
$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function
- What would happen if we change b ?

-

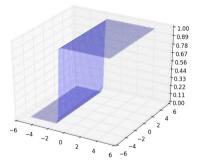
$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function
- What would happen if we change b ?

-

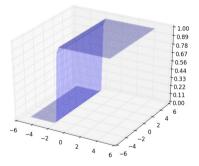
$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function
- What would happen if we change b?

-

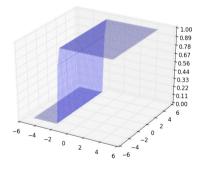
$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function
- What would happen if we change b ?

3

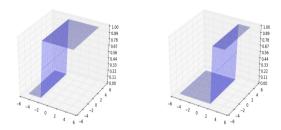
$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



$$w_1 = 25, w_2 = 0, b = 45$$

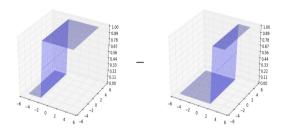
- This is what a 2-dimensional sigmoid looks like
- We need to figure out how to get a tower in this case
- First, let us set w_2 to 0 and see if we can get a two dimensional step function
- What would happen if we change b ?

3



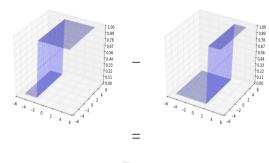
• What if we take two such step functions (with different *b* values) and subtract one from the other

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

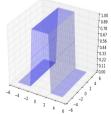


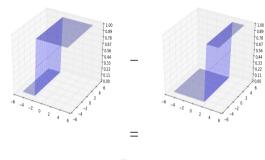
• What if we take two such step functions (with different *b* values) and subtract one from the other

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



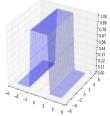
• What if we take two such step functions (with different *b* values) and subtract one from the other



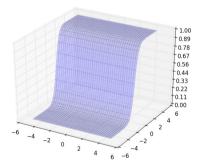


- What if we take two such step functions (with different *b* values) and subtract one from the other
- We still don't get a tower (or we get a tower which is open from two sides)

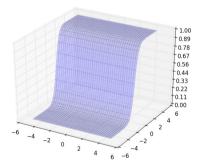
3



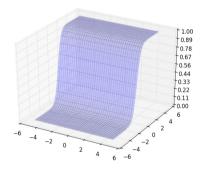
$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

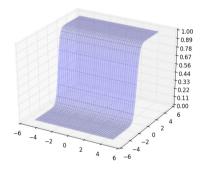


$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



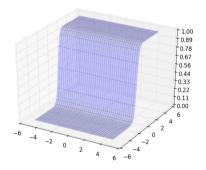
$$w_1 = 0, w_2 = 2, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



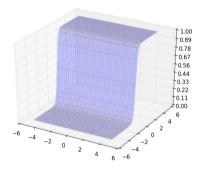
$$w_1 = 0, w_2 = 3, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



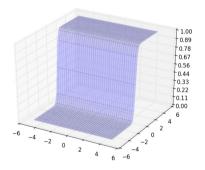
$$w_1 = 0, w_2 = 4, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



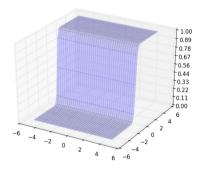
$$w_1 = 0, w_2 = 5, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



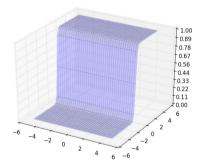
$$w_1 = 0, w_2 = 6, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



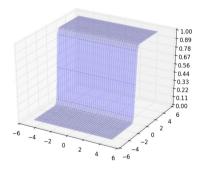
$$w_1 = 0, w_2 = 7, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



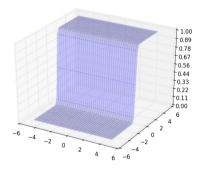
$$w_1 = 0, w_2 = 8, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



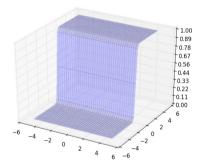
$$w_1 = 0, w_2 = 9, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



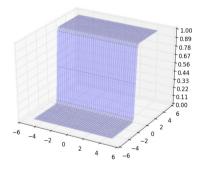
$$w_1 = 0, w_2 = 10, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



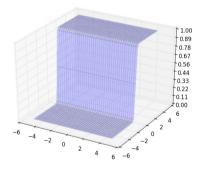
$$w_1 = 0, w_2 = 11, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



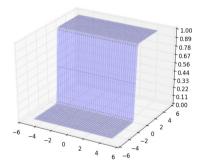
$$w_1 = 0, w_2 = 12, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



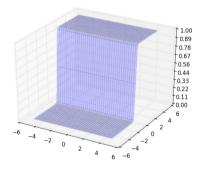
$$w_1 = 0, w_2 = 13, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



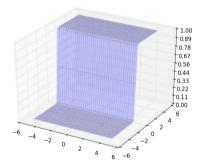
$$w_1 = 0, w_2 = 14, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



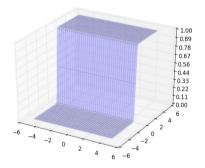
$$w_1 = 0, w_2 = 15, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



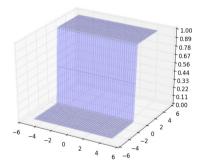
$$w_1 = 0, w_2 = 16, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



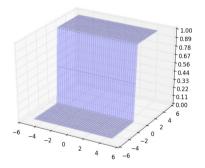
$$w_1 = 0, w_2 = 17, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



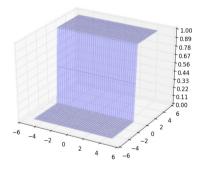
$$w_1 = 0, w_2 = 18, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



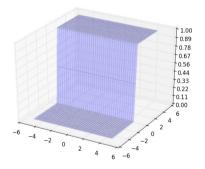
$$w_1 = 0, w_2 = 19, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



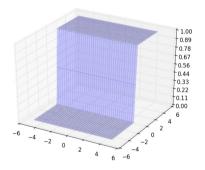
$$w_1 = 0, w_2 = 20, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



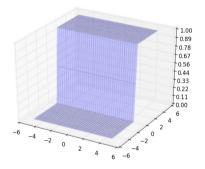
$$w_1 = 0, w_2 = 21, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



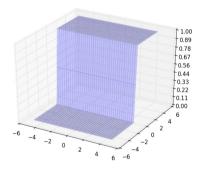
$$w_1 = 0, w_2 = 22, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



$$w_1 = 0, w_2 = 23, b = 0$$

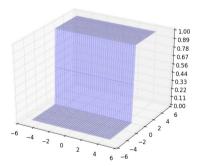
$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



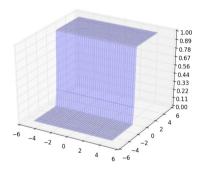
$$w_1 = 0, w_2 = 24, b = 0$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b_2)}}$$

▲ロ ▶ ▲ □ ▶ ▲ □ ▶ ▲ □ ▶ ● ● ● ● ● ●

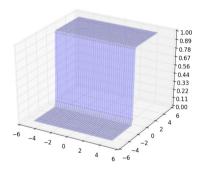


$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



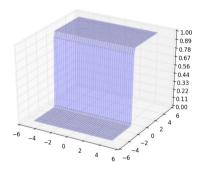
$$w_1 = 0, w_2 = 25, b = 5$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



$$w_1 = 0, w_2 = 25, b = 10$$

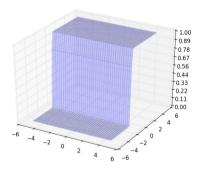
$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$



$$w_1 = 0, w_2 = 25, b = 15$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

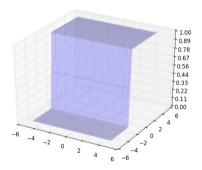
《日》 《圖》 《日》 《日》



$$w_1 = 0, w_2 = 25, b = 20$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

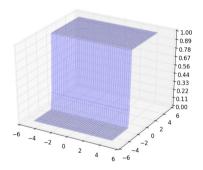
《日》 《圖》 《日》 《日》



$$w_1 = 0, w_2 = 25, b = 25$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

《日》 《圖》 《日》 《日》

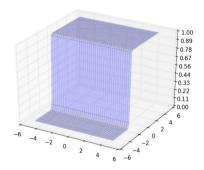


$$w_1 = 0, w_2 = 25, b = 30$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

《日》 《圖》 《日》 《日》

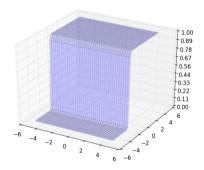
= 900



$$w_1 = 0, w_2 = 25, b = 35$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

《日》 《圖》 《日》 《日》



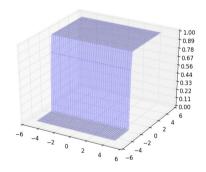
$$w_1 = 0, w_2 = 25, b = 40$$

$$y = \frac{1}{1 + e^{-(w_1 x_1 + w_2 x_2 + b)}}$$

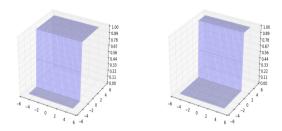
イロト 不得 トイヨト イヨト

3

 $\bullet\,$ And now we change b

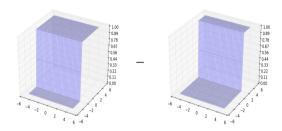


 $w_1 = 0, w_2 = 25, b = 45$



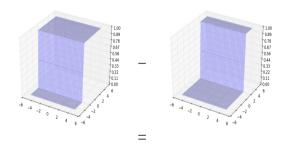
• Again, what if we take two such step functions (with different *b* values) and subtract one from the other

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



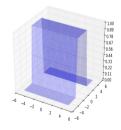
• Again, what if we take two such step functions (with different *b* values) and subtract one from the other

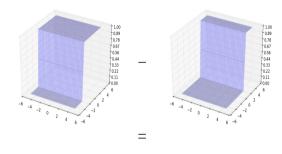
Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



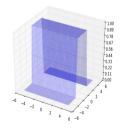
• Again, what if we take two such step functions (with different *b* values) and subtract one from the other

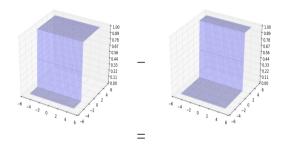
(4月) (日) (日) (日) (1000)





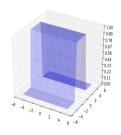
- Again, what if we take two such step functions (with different *b* values) and subtract one from the other
- We still don't get a tower (or we get a tower which is open from two sides)

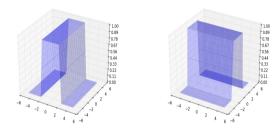




- Again, what if we take two such step functions (with different *b* values) and subtract one from the other
- We still don't get a tower (or we get a tower which is open from two sides)
- Notice that this open tower has a different orientation from the previous one

周下 イヨト イヨト

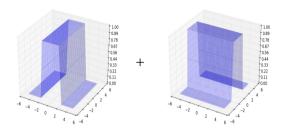




• Now what will we get by adding two such open towers ?

▲□▶ ▲御▶ ▲臣▶ ▲臣▶ ―臣 …のへで

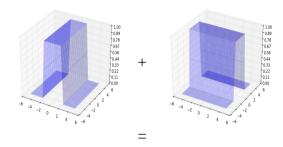
Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



• Now what will we get by adding two such open towers ?

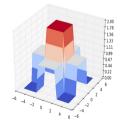
▲□▶ ▲御▶ ▲臣▶ ▲臣▶ ―臣 …のへで

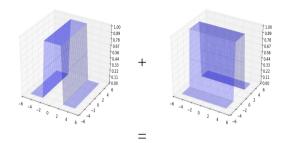
Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



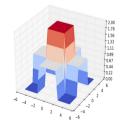
• Now what will we get by adding two such open towers ?

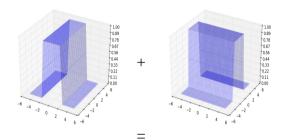
▲□▶ ▲御▶ ▲臣▶ ▲臣▶ ―臣 …のへで





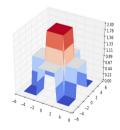
- Now what will we get by adding two such open towers ?
- We get a tower standing on an elevated base

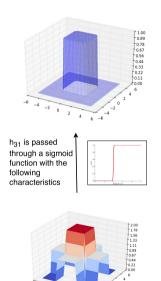




- Now what will we get by adding two such open towers ?
- We get a tower standing on an elevated base
- We can now pass this output through another sigmoid neuron to get the desired tower !

-



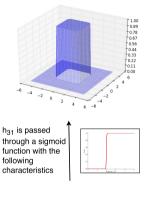


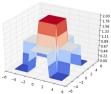
c -6

-6 -4 -2 0 2

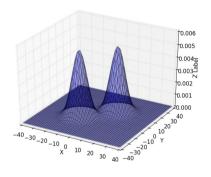
- Now what will we get by adding two such open towers ?
- We get a tower standing on an elevated base
- We can now pass this output through another sigmoid neuron to get the desired tower !

・ロト ・ 御 ト ・ ヨ ト ・ ヨ ト





- Now what will we get by adding two such open towers ?
- We get a tower standing on an elevated base
- We can now pass this output through another sigmoid neuron to get the desired tower !
- We can now approximate any function by summing up many such towers

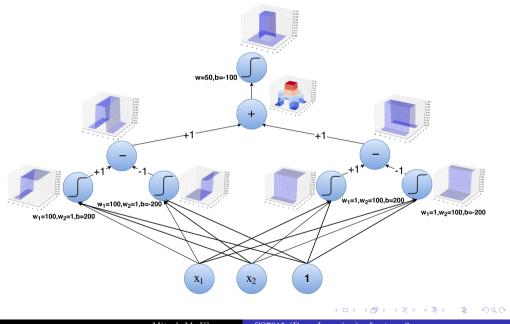


• For example, we could approximate the following function using a sum of several towers

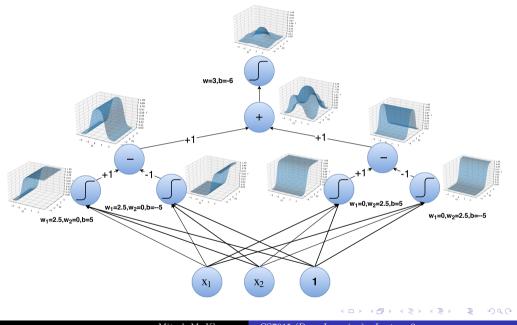
Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

• Can we come up with a neural network to represent this entire procedure of constructing a 3 dimensional tower ?

◆□▶ ◆圖▶ ◆臣▶ ◆臣▶ ─臣 ─の�?



Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3



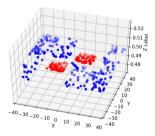
Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

Think

- For 1 dimensional input we needed 2 neurons to construct a tower
- For 2 dimensional input we needed 4 neurons to construct a tower
- How many neurons will you need to construct a tower in n dimensions ?

Time to retrospect

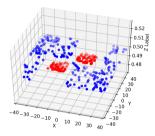
- Why do we care about approximating any arbitrary function ?
- Can we tie all this back to the classification problem that we have been dealing with ?



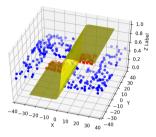
• We are interested in separating the blue points from the red points

Mitesh M. Khapra CS7015 (Deep Learning) : Lecture 3

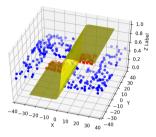
◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 - のへで



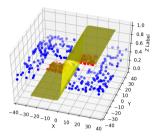
- We are interested in separating the blue points from the red points
- Suppose we use a single sigmoidal neuron to approximate the relation between $x = [x_1, x_2]$ and y



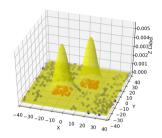
- We are interested in separating the blue points from the red points
- Suppose we use a single sigmoidal neuron to approximate the relation between $x = [x_1, x_2]$ and y



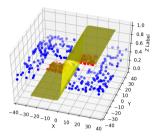
- We are interested in separating the blue points from the red points
- Suppose we use a single sigmoidal neuron to approximate the relation between x = [x₁, x₂] and y
- Obviously, there will be errors (some blue points get classified as 1 and some red points get classified as 0)



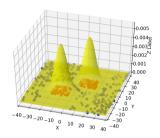
- We are interested in separating the blue points from the red points
- Suppose we use a single sigmoidal neuron to approximate the relation between x = [x₁, x₂] and y
- Obviously, there will be errors (some blue points get classified as 1 and some red points get classified as 0)



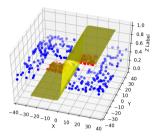
• This is what we actually want



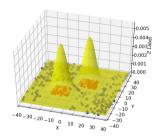
- We are interested in separating the blue points from the red points
- Suppose we use a single sigmoidal neuron to approximate the relation between x = [x₁, x₂] and y
- Obviously, there will be errors (some blue points get classified as 1 and some red points get classified as 0)



- This is what we actually want
- The illustrative proof that we just saw tells us that we can have a neural network with two hidden layers which can approximate the above function by a sum of towers



- We are interested in separating the blue points from the red points
- Suppose we use a single sigmoidal neuron to approximate the relation between x = [x₁, x₂] and y
- Obviously, there will be errors (some blue points get classified as 1 and some red points get classified as 0)



- This is what we actually want
- The illustrative proof that we just saw tells us that we can have a neural network with two hidden layers which can approximate the above function by a sum of towers
- Which means we can have a neural network which can exactly separate the blue points from the red points !!