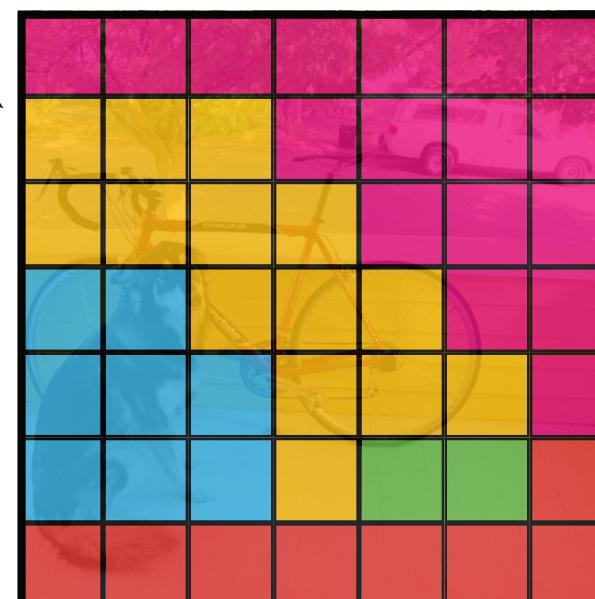
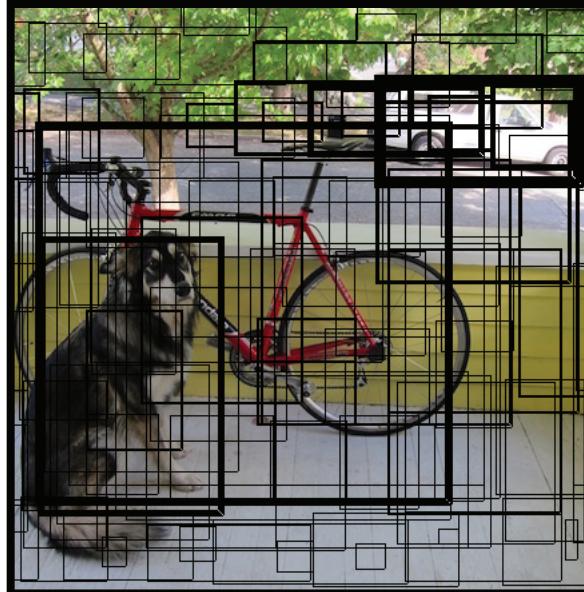
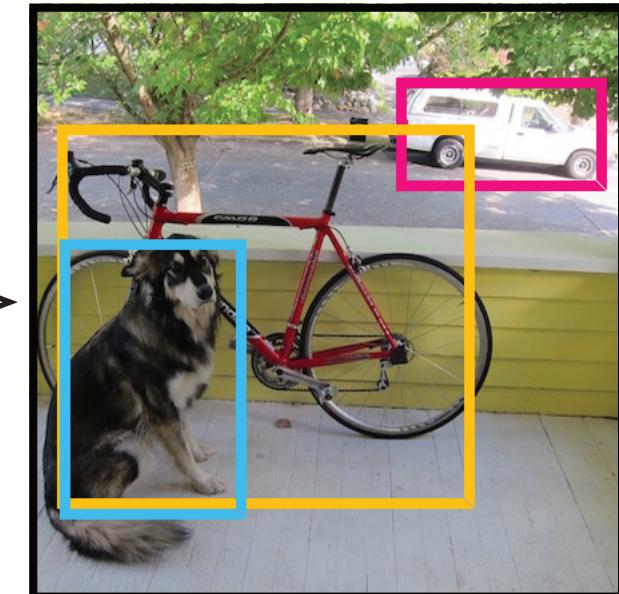


$S \times S$  grid on input



Class probability map



Final detections