

## Module 19.2: The concept of a latent variable



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- Recall that earlier we mentioned that the neighboring pixels in an image are dependent on each other
- Why is it so? (intuitively, because we expect them to have the same color, texture, etc.?)
- Let us probe this intuition a bit more and try to formalize it



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- Okay, But why is it not cloudy (gray)?



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- Okay, But why is it not cloudy (gray)?(because our friend decided to show us an image which depicts a sunny day)



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- But then why blue why not black? (because our friend decided to show us an image which depicts daytime as opposed to night time)
- Okay, But why is it not cloudy (gray)?(because our friend decided to show us an image which depicts a sunny day)
- These decisions made by our friend (sky, sunny, daytime, etc) are not explicitly known to us (they are hidden from us)



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- These decisions made by our friend (sky, sunny, daytime, etc) are not explicitly known to us (they are hidden from us)
- We only observe the images but what we observe depends on these latent (hidden) decisions



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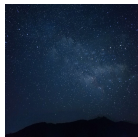


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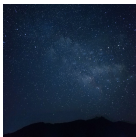


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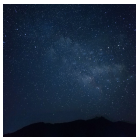


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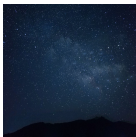


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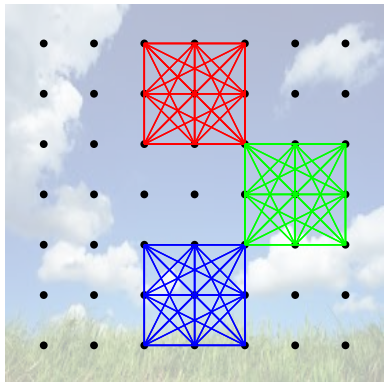
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- The pixels depend on the choice of these latent variables

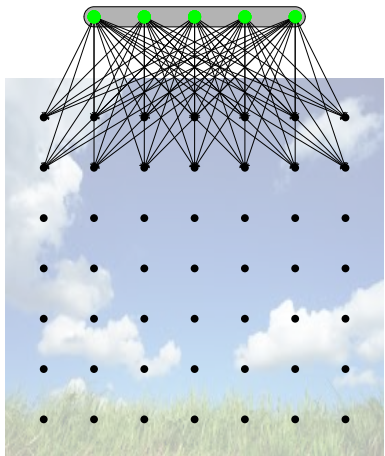
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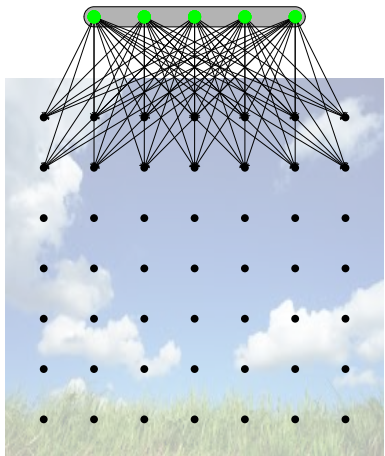




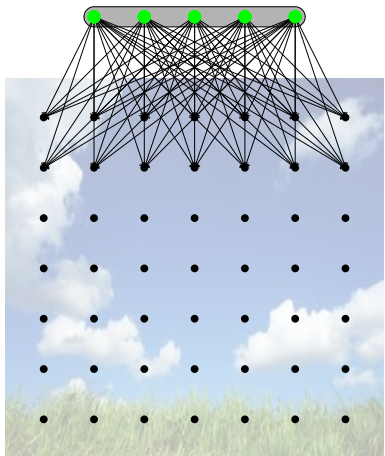
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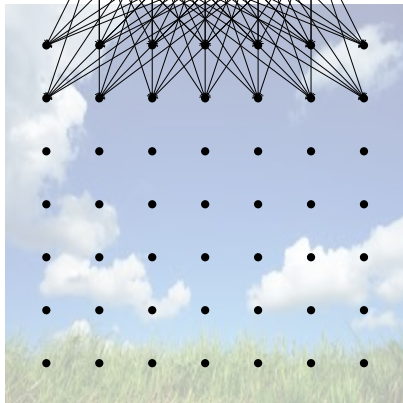


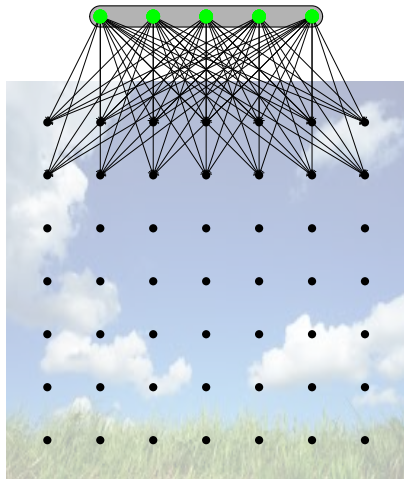
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- But now we could have a better Markov Network involving these latent variables
- This Markov Network suggests that the pixels (observed variables) are dependent on the latent variables (which is exactly the intuition that we were trying to build in the previous slides)
- The interactions between the pixels are captured through the latent variables

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- We will talk about two concepts: *abstraction* and *generation*

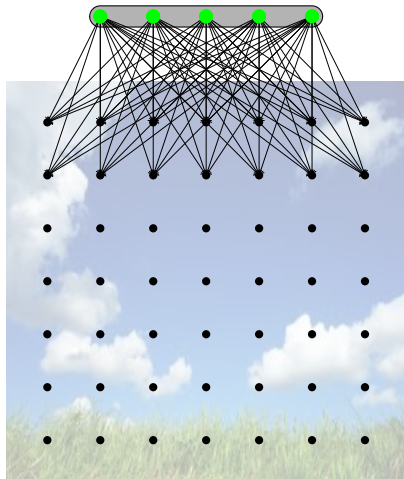
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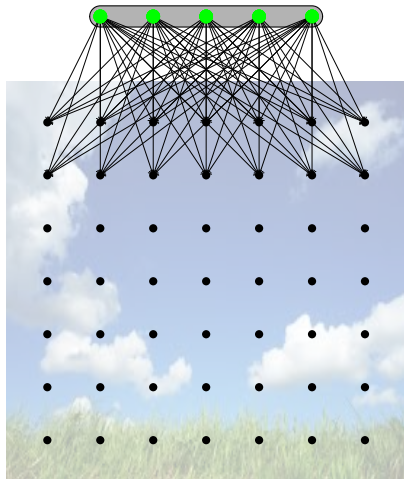
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- Using this distribution we can find

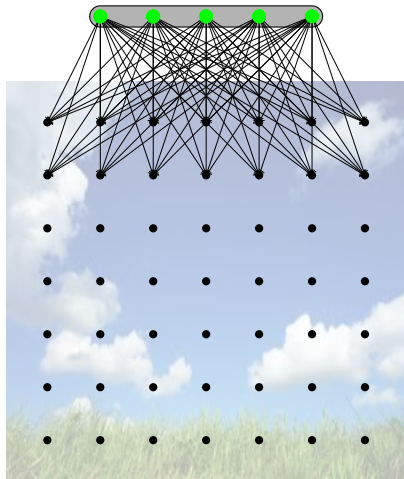
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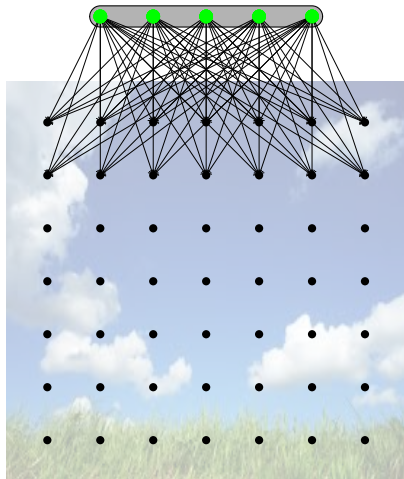
- In other words, given an image, we can find the most likely latent configuration ( $H = h$ ) that generated this image (of course, keeping the computational cost aside for now)



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- What does this  $h$  capture?



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- What does this  $h$  capture? It captures a latent representation or abstraction of the image!



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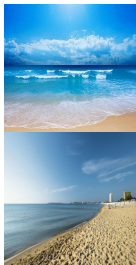
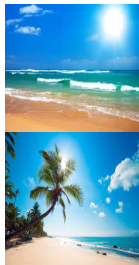


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- This is exactly the abstraction captured by the vector  $h$



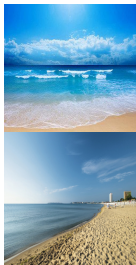
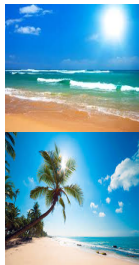


- Under this abstraction all these images would look very similar (i.e., they would have very similar latent configurations  $h$ )



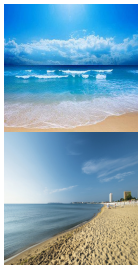
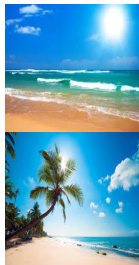


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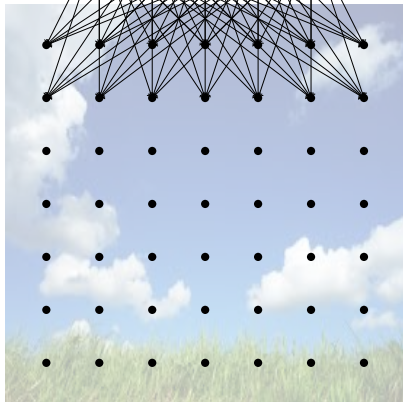


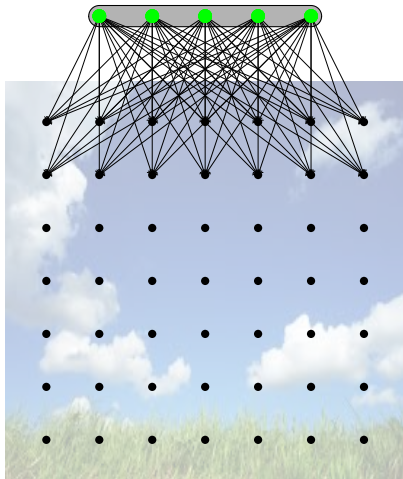


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- This is very similar to the idea behind PCA and autoencoders

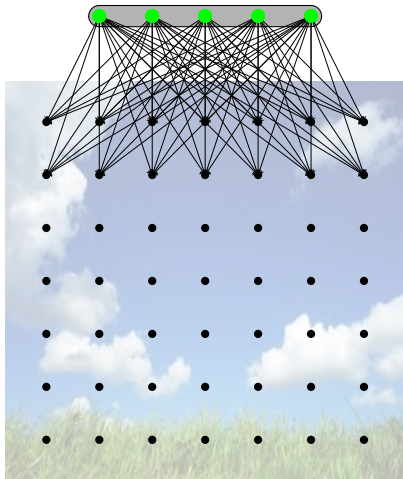


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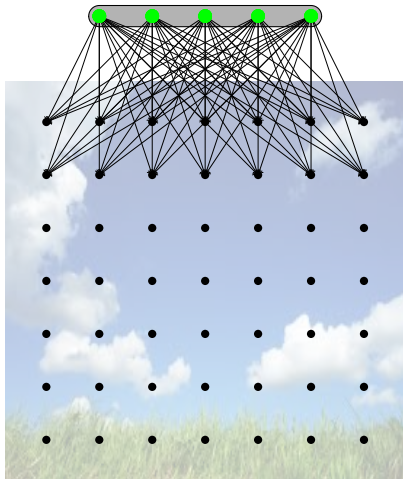




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- In the case of PCA, learning such latent representations boiled down to learning the eigen vectors of  $X^T X$  (using linear algebra)

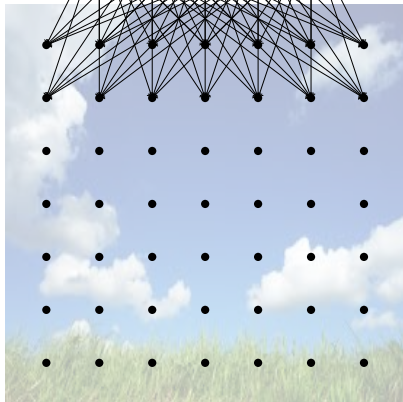


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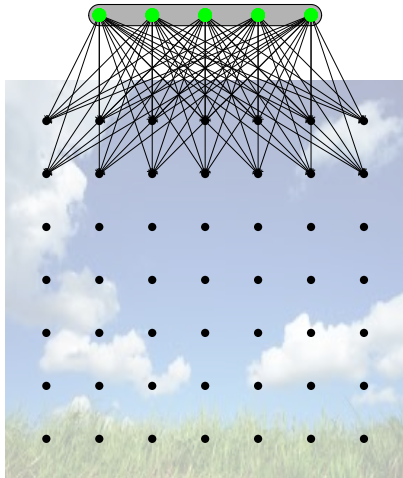


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- We still haven't seen how to learn the parameters of  $P(H, V)$  (we are far from it but we will get there soon!)

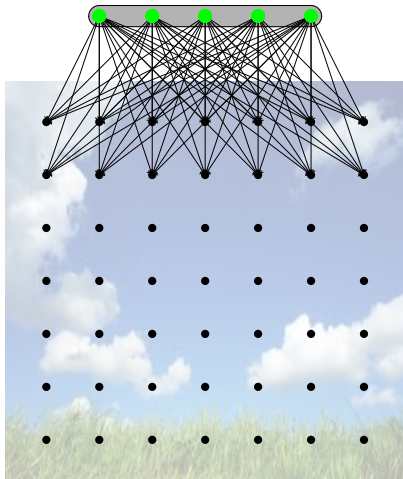
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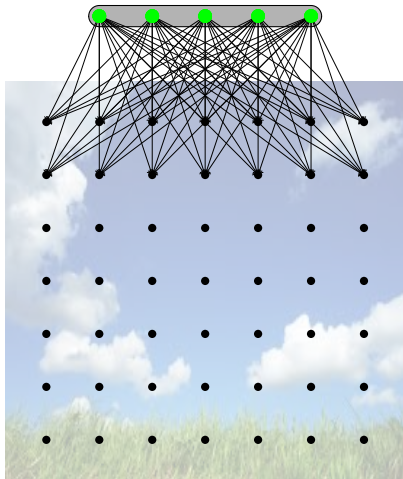




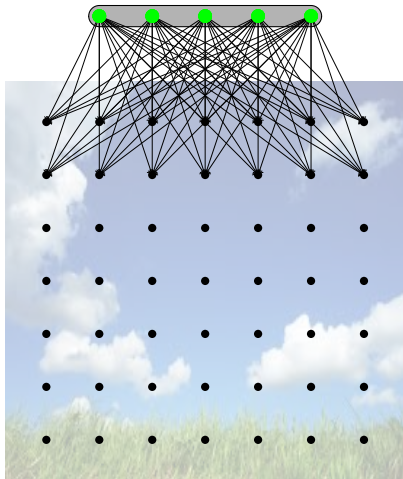
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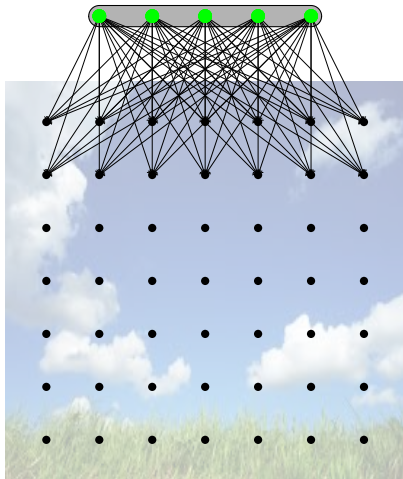
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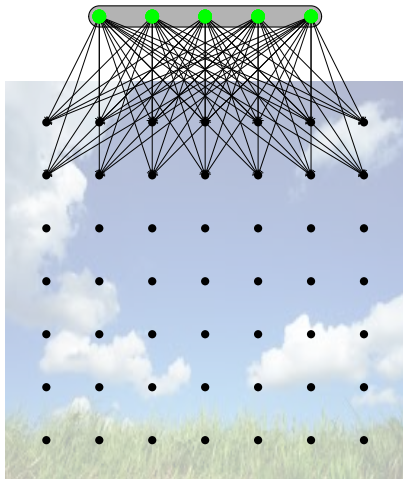
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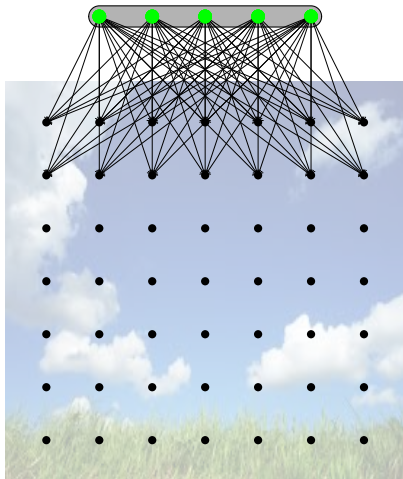
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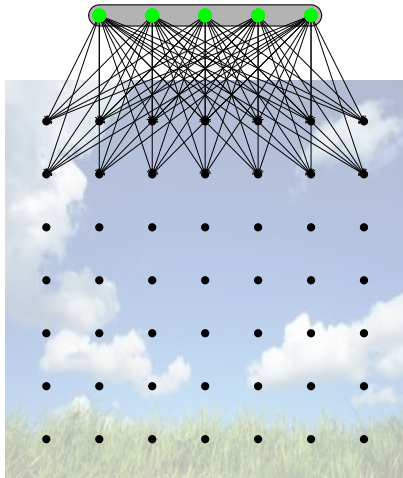
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- Only for illustration purpose we assumed that  $h_1$  corresponds to sunny/cloudy,  $h_2$  corresponds to beach and so on



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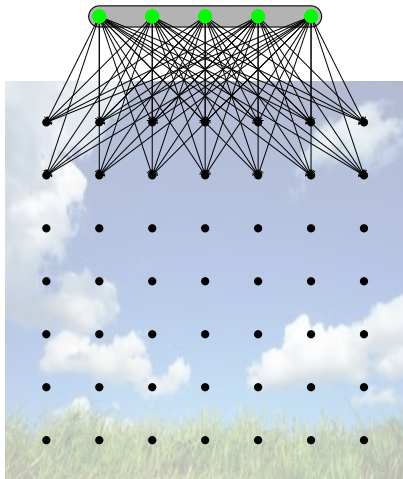


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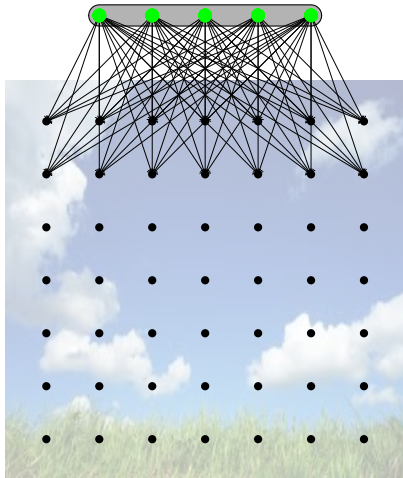


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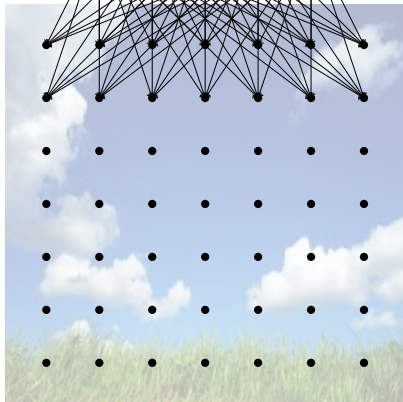


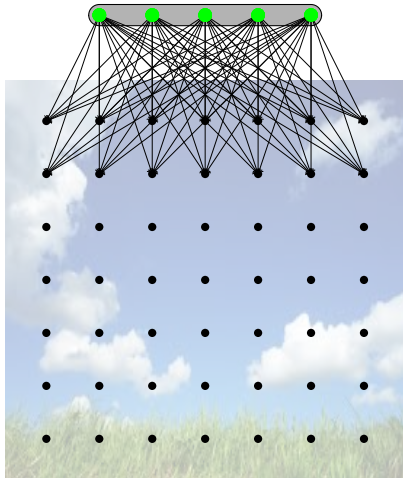
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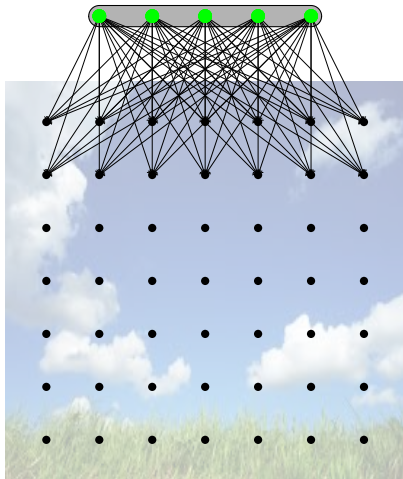
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- How? (we will get there eventually)

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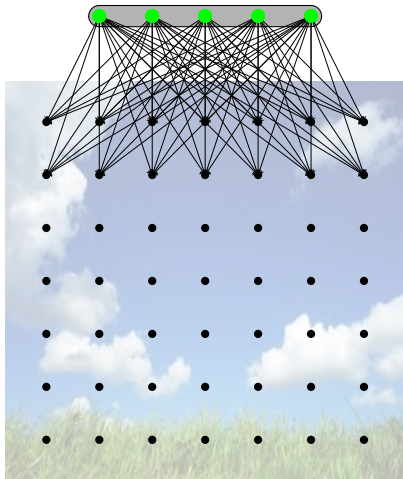


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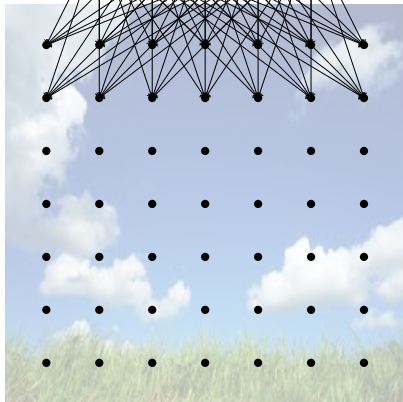


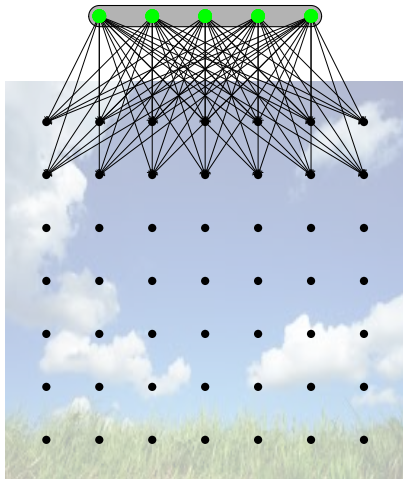
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- Why is this interesting?

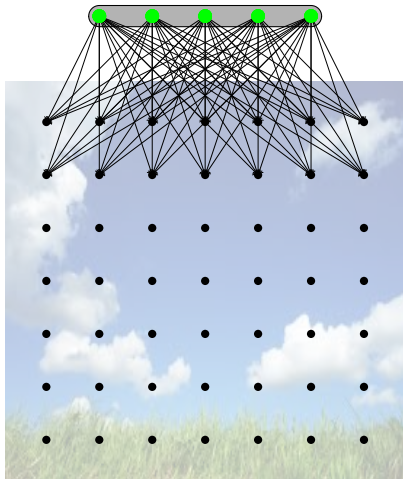
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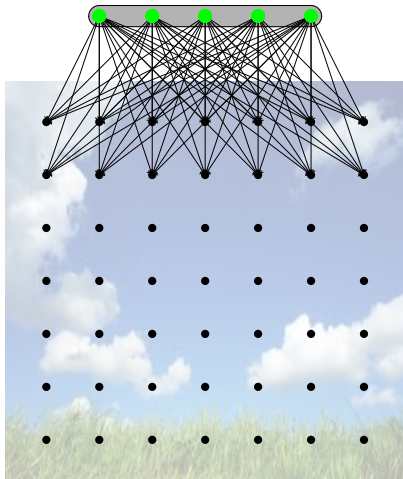


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- The hope is that I should be able to ask the model to generate very creative images given some latent configuration (we will come back to this later)

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- We will now concretize these intuitions by developing equations (models) and learning algorithms
- And of course, we will tie all this back to neural networks!

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- Thus, the vector  $V$  will be a boolean vector  $\in \{0, 1\}^m$  (there are a total of  $2^m$  values that  $V$  can take)
- And the vector  $H$  will be a boolean vector  $\in \{0, 1\}^n$  (there are a total of  $2^n$  values that  $H$  can take)