

Module 2.5: Perceptron Learning Algorithm

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- Apart from implementing boolean functions (which does not look very interesting) what can a perceptron be used for ?
- Our interest lies in the use of perceptron as a binary classifier. Let us see what this means...

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$x_1 = isActorDamon$

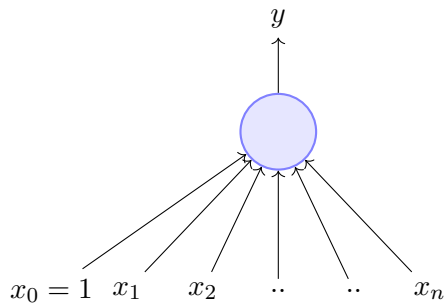
$x_2 = isGenreThriller$

$x_3 = isDirectorNolan$

$x_4 = imdbRating(scaled\ to\ 0\ to\ 1)$

... ...

$x_n = criticsRating(scaled\ to\ 0\ to\ 1)$



$x_1 = isActorDamon$

$x_2 = isGenreThriller$

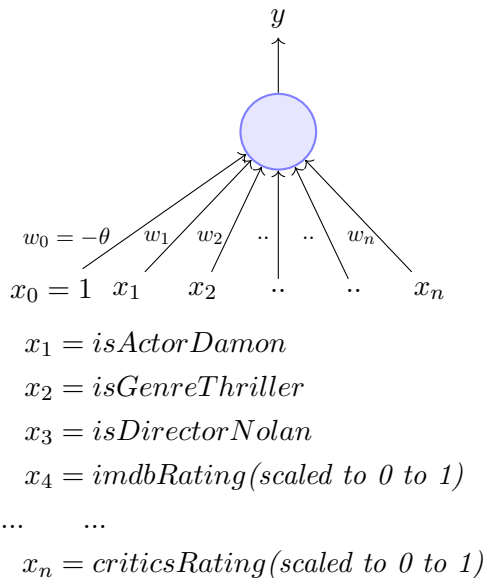
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- We will assume that the data is linearly separable and we want a perceptron to learn how to make this decision
- In other words, we want the perceptron to find the equation of this separating plane (or find the values of $w_0, w_1, w_2, .., w_m$)

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- Why would this work ?
- To understand why this works we will have to get into a bit of Linear Algebra and a bit of geometry...

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$$\mathbf{w} \cdot \mathbf{x} = \mathbf{w}^T \mathbf{x} = \sum_{i=0}^n w_i * x_i$$

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- The angle is 90° ($\because \cos \alpha = \frac{\mathbf{w}^T \mathbf{x}}{\|\mathbf{w}\| \|\mathbf{x}\|} = 0$)

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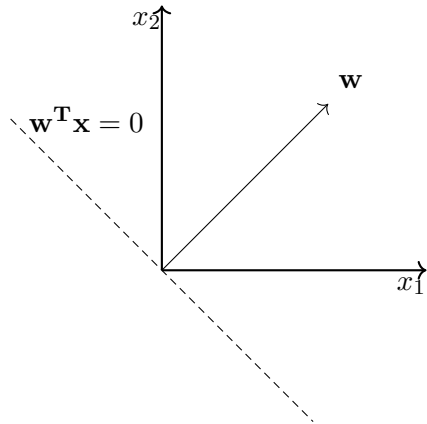
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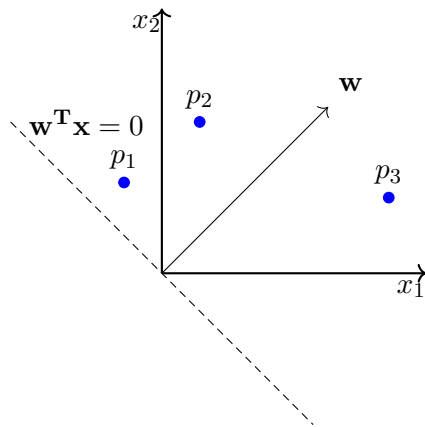
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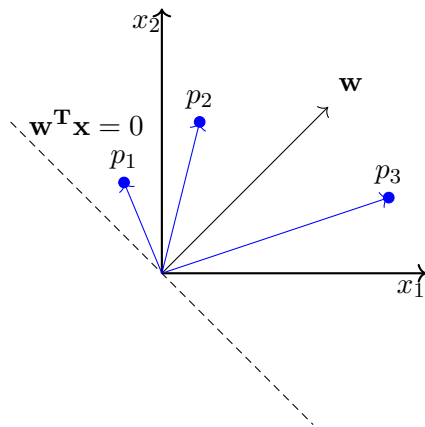
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- Since the vector \mathbf{w} is perpendicular to every point on the line it is actually perpendicular to the line itself



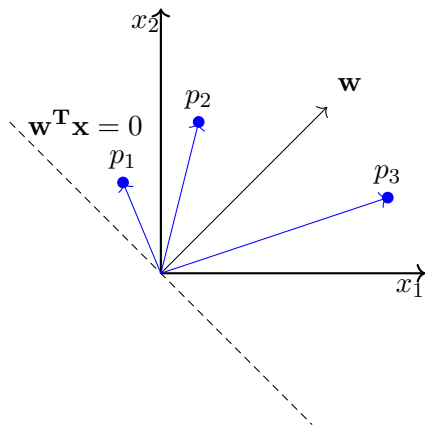
- Consider some points (vectors) which lie in the positive half space of this line (*i.e.*, $\mathbf{w}^T \mathbf{x} \geq 0$)



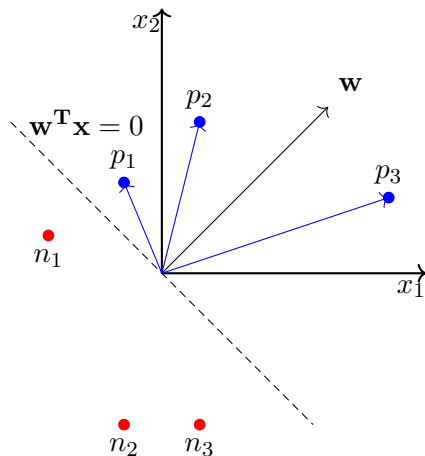
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- What will be the angle between any such vector and \mathbf{w} ?



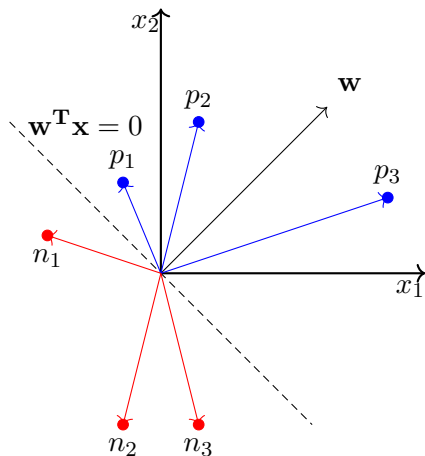
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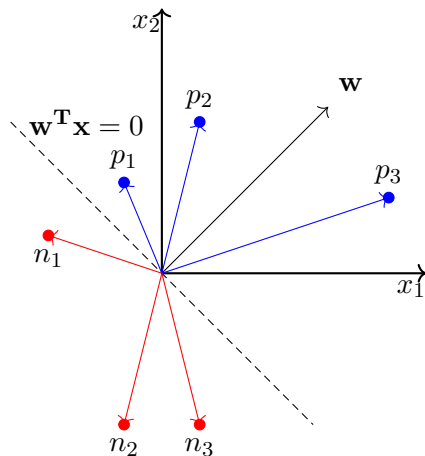
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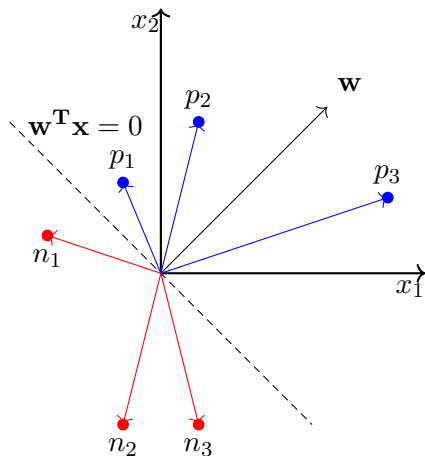
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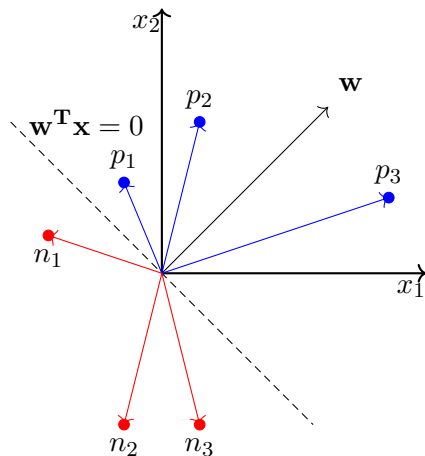
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- Of course, this also follows from the formula ($\cos \alpha = \frac{\mathbf{w}^T \mathbf{x}}{\|\mathbf{w}\| \|\mathbf{x}\|}$)



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- Keeping this picture in mind let us revisit the algorithm



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$P \leftarrow$ inputs with label 1;

$N \leftarrow$ inputs with label 0;

Initialize \mathbf{w} randomly;

while !convergence **do**

 Pick random $\mathbf{x} \in P \cup N$;

if $\mathbf{x} \in P$ and $\mathbf{w} \cdot \mathbf{x} < 0$ **then**

 | $\mathbf{w} = \mathbf{w} + \mathbf{x}$;

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$$\cos(\alpha_{new}) \propto \mathbf{w}_{new}^T \mathbf{x}$$

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$$\begin{aligned} \cos(\alpha_{new}) &\propto \mathbf{w}_{new}^T \mathbf{x} \\ &\propto (\mathbf{w} + \mathbf{x})^T \mathbf{x} \end{aligned}$$

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$$\begin{aligned} \cos(\alpha_{new}) &\propto \mathbf{w}_{new}^T \mathbf{x} \\ &\propto (\mathbf{w} + \mathbf{x})^T \mathbf{x} \\ &\propto \mathbf{w}^T \mathbf{x} + \mathbf{x}^T \mathbf{x} \end{aligned}$$

Algorithm: Perceptron Learning Algorithm

$P \leftarrow$ inputs with label 1;

$N \leftarrow$ inputs with label 0;

Initialize \mathbf{w} randomly;

while !convergence **do**

 Pick random $\mathbf{x} \in P \cup N$;

if $\mathbf{x} \in P$ and $\mathbf{w} \cdot \mathbf{x} < 0$ **then**

$\mathbf{w} = \mathbf{w} + \mathbf{x}$;

end

if $\mathbf{x} \in N$ and $\mathbf{w} \cdot \mathbf{x} \geq 0$ **then**

$\mathbf{w} = \mathbf{w} - \mathbf{x}$;

end

end

//the algorithm converges when all the
inputs are classified correctly

$$\cos \alpha = \frac{\mathbf{w}^T \mathbf{x}}{\|\mathbf{w}\| \|\mathbf{x}\|}$$

- For $\mathbf{x} \in P$ if $\mathbf{w} \cdot \mathbf{x} < 0$ then it means that the angle (α) between this \mathbf{x} and the current \mathbf{w} is greater than 90° (but we want α to be less than 90°)
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Algorithm: Perceptron Learning Algorithm

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 Pick random $\mathbf{x} \in P \cup N$;

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$$\begin{aligned} \cos(\alpha_{new}) &\propto \mathbf{w}_{new}^T \mathbf{x} \\ &\propto (\mathbf{w} + \mathbf{x})^T \mathbf{x} \\ &\propto \mathbf{w}^T \mathbf{x} + \mathbf{x}^T \mathbf{x} \\ &\propto \cos \alpha + \mathbf{x}^T \mathbf{x} \\ \cos(\alpha_{new}) &> \cos \alpha \end{aligned}$$

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$$\cos \alpha = \frac{\mathbf{w}^T \mathbf{x}}{\|\mathbf{w}\| \|\mathbf{x}\|}$$

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$$\begin{aligned} \cos(\alpha_{new}) &\propto \mathbf{w}_{new}^T \mathbf{x} \\ &\propto (\mathbf{w} + \mathbf{x})^T \mathbf{x} \\ &\propto \mathbf{w}^T \mathbf{x} + \mathbf{x}^T \mathbf{x} \\ &\propto \cos \alpha + \mathbf{x}^T \mathbf{x} \end{aligned}$$

$$\cos(\alpha_{new}) > \cos \alpha$$

- Thus α_{new} will be less than α and this is exactly what we want

Algorithm: Perceptron Learning Algorithm

$P \leftarrow$ inputs with label 1;

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Initialize \mathbf{w} randomly;

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 Pick random $\mathbf{x} \in P \cup N$;

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$$\cos \alpha = \frac{\mathbf{w}^T \mathbf{x}}{\|\mathbf{w}\| \|\mathbf{x}\|}$$

- For $\mathbf{x} \in N$ if $\mathbf{w} \cdot \mathbf{x} \geq 0$ then it means that the angle (α) between this \mathbf{x} and the current \mathbf{w} is less than 90°

Algorithm: Perceptron Learning Algorithm

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$$\cos \alpha = \frac{\mathbf{w}^T \mathbf{x}}{\|\mathbf{w}\| \|\mathbf{x}\|}$$

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- What happens to the new angle (α_{new}) when $\mathbf{w}_{new} = \mathbf{w} - \mathbf{x}$

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- What happens to the new angle (α_{new}) when $\mathbf{w}_{new} = \mathbf{w} - \mathbf{x}$

$$\cos(\alpha_{new}) \propto \mathbf{w}_{new}^T \mathbf{x}$$

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- What happens to the new angle (α_{new}) when $\mathbf{w}_{new} = \mathbf{w} - \mathbf{x}$

$$\begin{aligned} \cos(\alpha_{new}) &\propto \mathbf{w}_{new}^T \mathbf{x} \\ &\propto (\mathbf{w} - \mathbf{x})^T \mathbf{x} \end{aligned}$$

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- What happens to the new angle (α_{new}) when $\mathbf{w}_{new} = \mathbf{w} - \mathbf{x}$

$$\begin{aligned} \cos(\alpha_{new}) &\propto \mathbf{w}_{new}^T \mathbf{x} \\ &\propto (\mathbf{w} - \mathbf{x})^T \mathbf{x} \\ &\propto \mathbf{w}^T \mathbf{x} - \mathbf{x}^T \mathbf{x} \end{aligned}$$

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- What happens to the new angle (α_{new}) when $\mathbf{w}_{new} = \mathbf{w} - \mathbf{x}$

$$\begin{aligned} \cos(\alpha_{new}) &\propto \mathbf{w}_{new}^T \mathbf{x} \\ &\propto (\mathbf{w} - \mathbf{x})^T \mathbf{x} \\ &\propto \mathbf{w}^T \mathbf{x} - \mathbf{x}^T \mathbf{x} \\ &\propto \cos \alpha - \mathbf{x}^T \mathbf{x} \end{aligned}$$

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$$\begin{aligned} \cos(\alpha_{new}) &\propto \mathbf{w}_{new}^T \mathbf{x} \\ &\propto (\mathbf{w} - \mathbf{x})^T \mathbf{x} \\ &\propto \mathbf{w}^T \mathbf{x} - \mathbf{x}^T \mathbf{x} \\ &\propto \cos \alpha - \mathbf{x}^T \mathbf{x} \\ \cos(\alpha_{new}) &< \cos \alpha \end{aligned}$$

Algorithm: Perceptron Learning Algorithm

$P \leftarrow$ inputs with label 1;

$N \leftarrow$ inputs with label 0;

Initialize \mathbf{w} randomly;

while !convergence **do**

 Pick random $\mathbf{x} \in P \cup N$;

if $\mathbf{x} \in P$ and $\mathbf{w} \cdot \mathbf{x} < 0$ **then**

$\mathbf{w} = \mathbf{w} + \mathbf{x}$;

end

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- What happens to the new angle (α_{new}) when $\mathbf{w}_{new} = \mathbf{w} - \mathbf{x}$

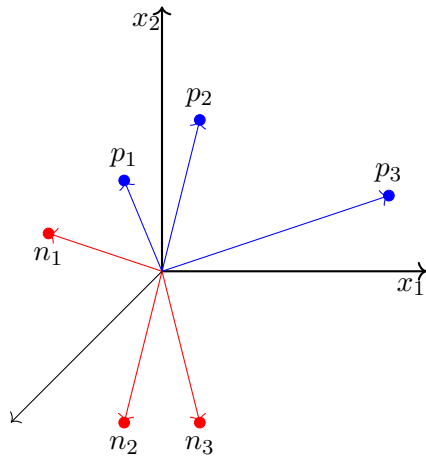
$$\begin{aligned}\cos(\alpha_{new}) &\propto \mathbf{w}_{new}^T \mathbf{x} \\ &\propto (\mathbf{w} - \mathbf{x})^T \mathbf{x} \\ &\propto \mathbf{w}^T \mathbf{x} - \mathbf{x}^T \mathbf{x} \\ &\propto \cos \alpha - \mathbf{x}^T \mathbf{x}\end{aligned}$$

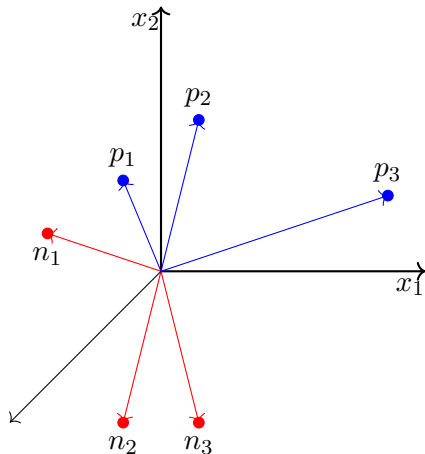
$$\cos(\alpha_{new}) < \cos \alpha$$

- Thus α_{new} will be greater than α and this is exactly what we want

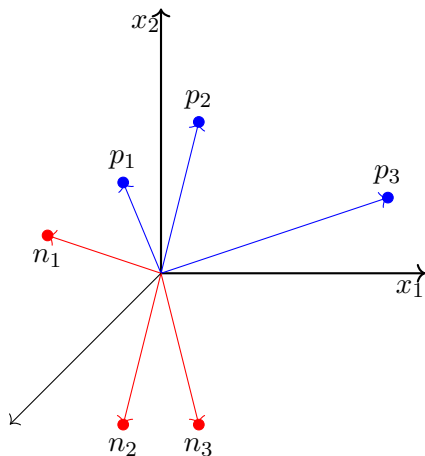
- We will now see this algorithm in action for a toy dataset

- We initialized \mathbf{w} to a random value

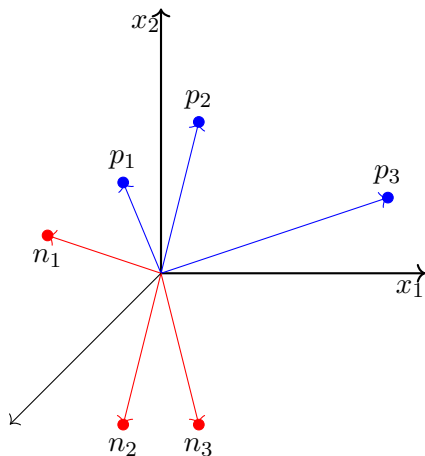




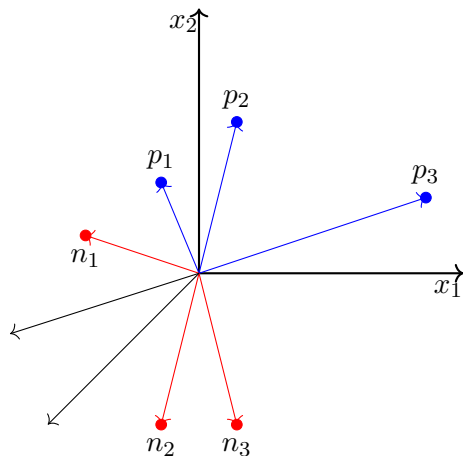
- We initialized \mathbf{w} to a random value
- We observe that currently, $\mathbf{w} \cdot \mathbf{x} < 0$ (\because angle $> 90^\circ$) for all the positive points and $\mathbf{w} \cdot \mathbf{x} \geq 0$ (\because angle $< 90^\circ$) for all the negative points (the situation is exactly opposite of what we actually want it to be)



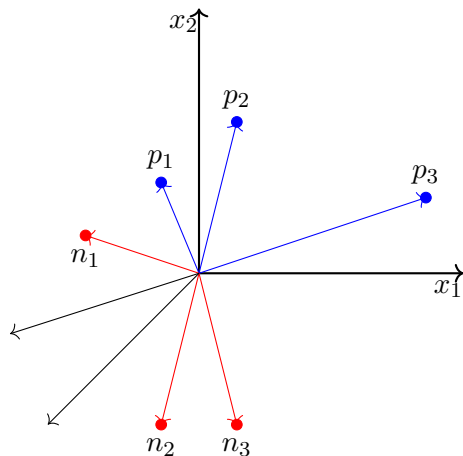
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- We now run the algorithm by randomly going over the points



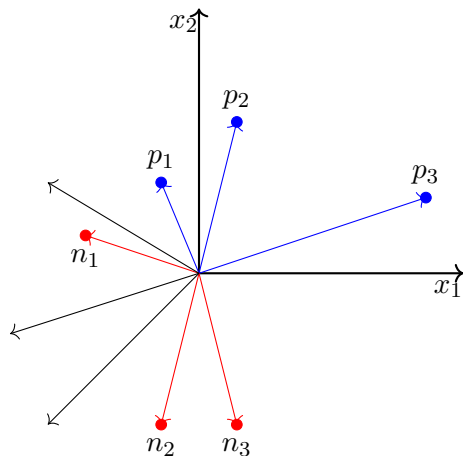
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- We now run the algorithm by randomly going over the points
- Randomly pick a point (say, p_1), apply correction $\mathbf{w} = \mathbf{w} + \mathbf{x} \because \mathbf{w} \cdot \mathbf{x} < 0$ (you can check the angle visually)



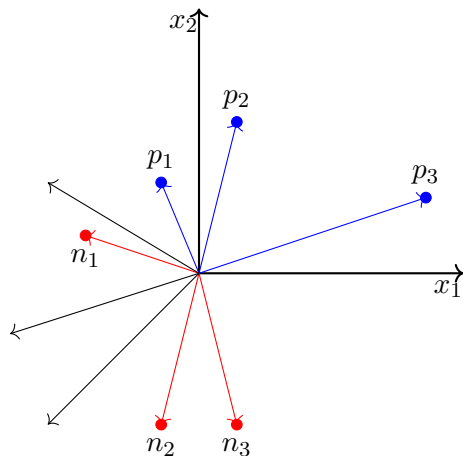
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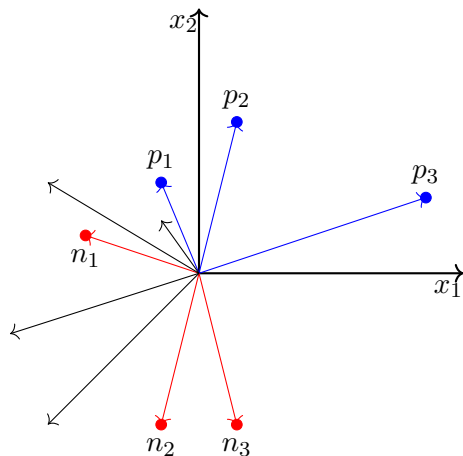
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- We now run the algorithm by randomly going over the points
- Randomly pick a point (say, p_2), apply correction $\mathbf{w} = \mathbf{w} + \mathbf{x} \because \mathbf{w} \cdot \mathbf{x} < 0$ (you can check the angle visually)



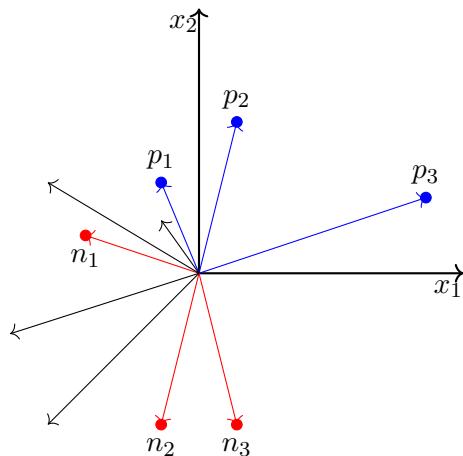
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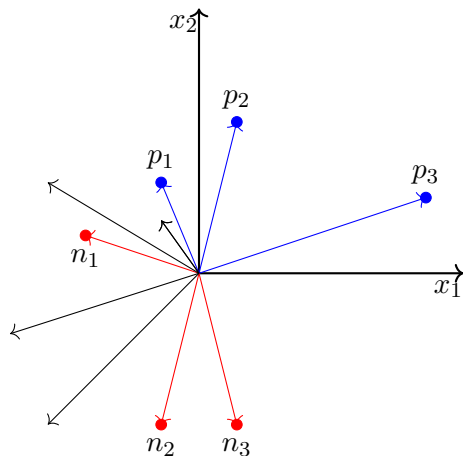
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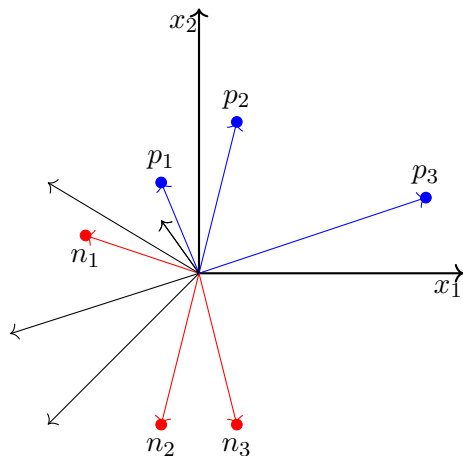
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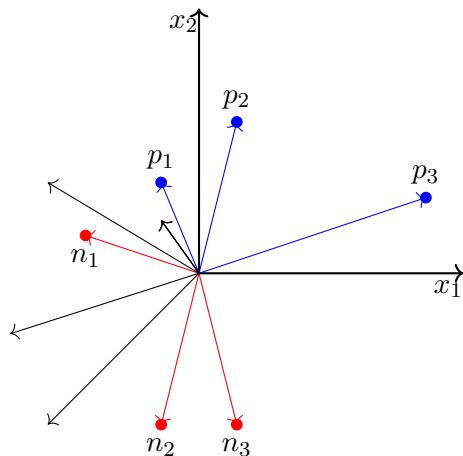
- We initialized \mathbf{w} to a random value
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- We now run the algorithm by randomly going over the points
- Randomly pick a point (say, n_3), no correction needed $\because \mathbf{w} \cdot \mathbf{x} < 0$ (you can check the angle visually)



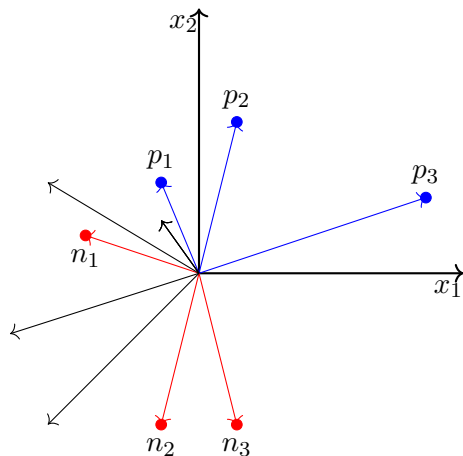
- We initialized \mathbf{w} to a random value
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- We now run the algorithm by randomly going over the points
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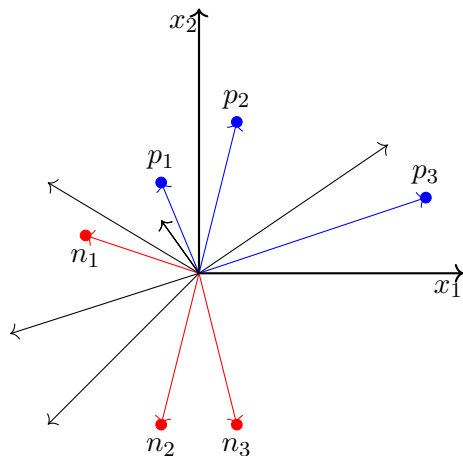
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- We now run the algorithm by randomly going over the points
- Randomly pick a point (say, n_2), no correction needed $\because \mathbf{w} \cdot \mathbf{x} < 0$ (you can check the angle visually)



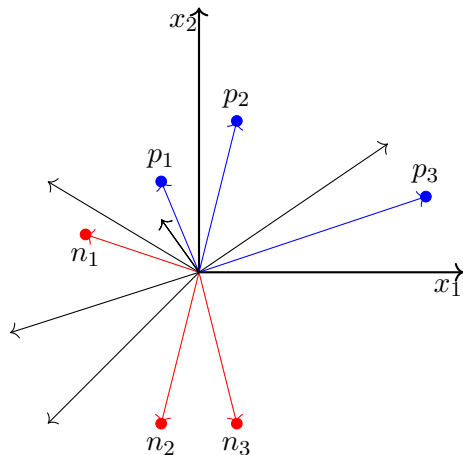
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- We now run the algorithm by randomly going over the points
- Randomly pick a point (say, n_2), no correction needed $\because \mathbf{w} \cdot \mathbf{x} < 0$ (you can check the angle visually)



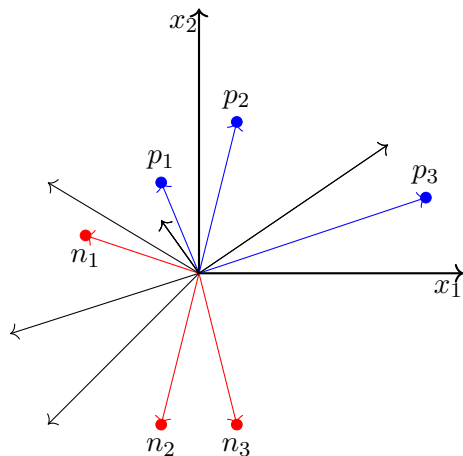
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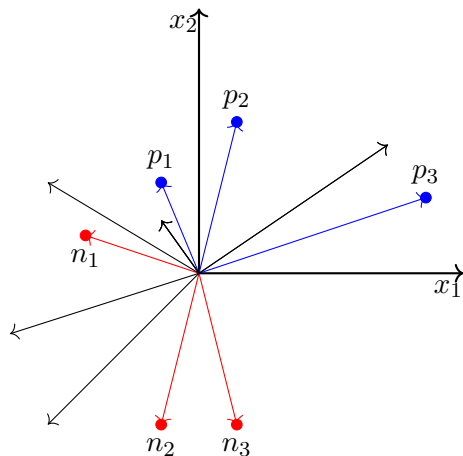
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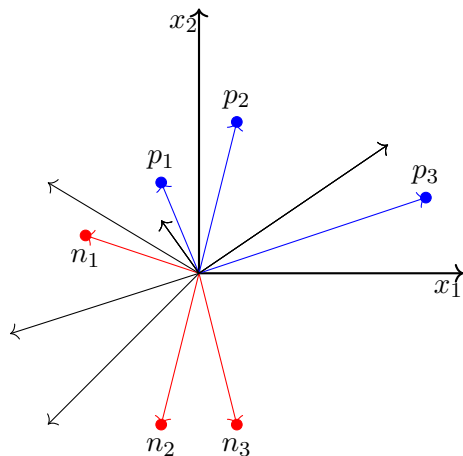
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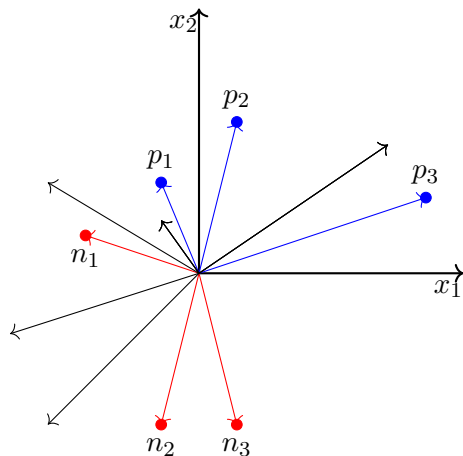
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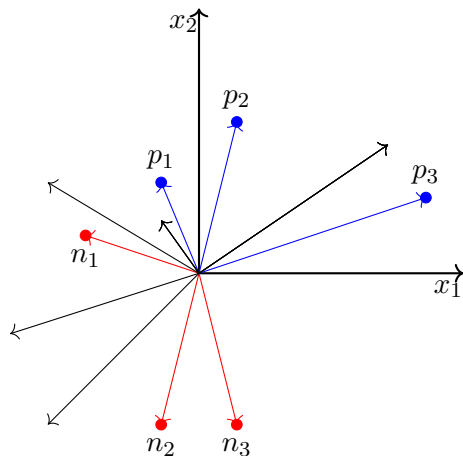
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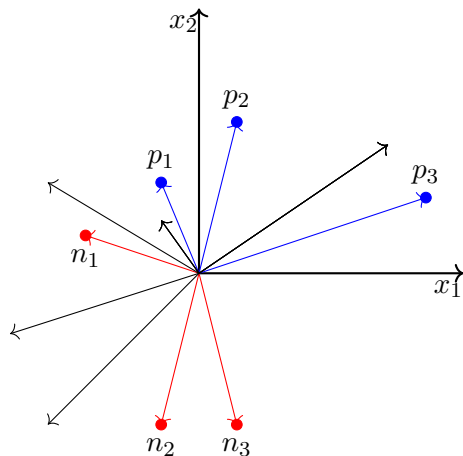
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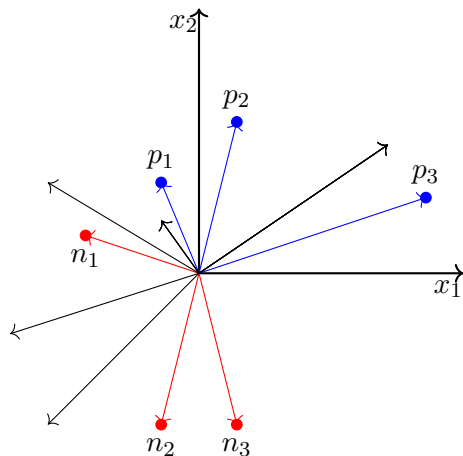
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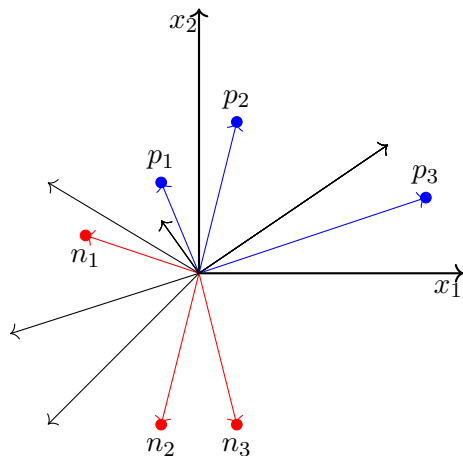
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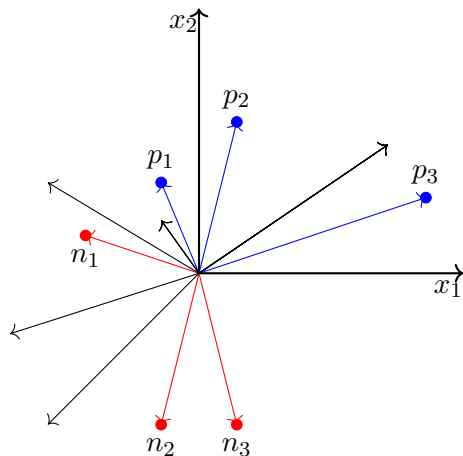
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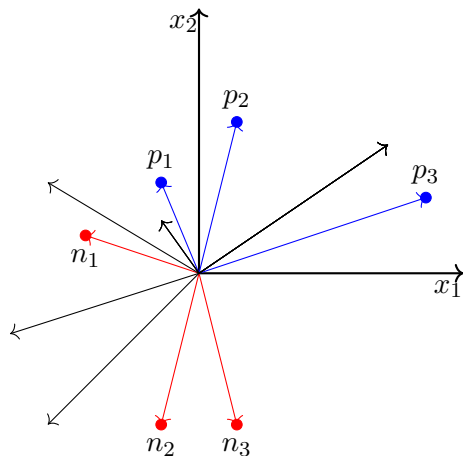
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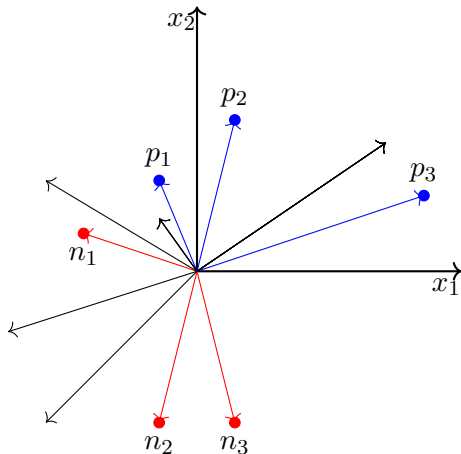
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- We now run the algorithm by randomly going over the points
- The algorithm has converged