Module 2.6: Proof of Convergence

- Now that we have some faith and intuition about why the algorithm works, we will see a more formal proof of convergence ...

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Proof: On the next slide

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- Let w^* be the normalized solution vector (we know one exists as the data is linearly separable)

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$$\begin{aligned} Numerator &= w^* \cdot w_{t+1} = w^* \cdot (w_t + p_i) \\ &= w^* \cdot w_t + w^* \cdot p_i \\ &\geq w^* \cdot w_t + \delta \quad (\delta = min\{w^* \cdot p_i | \forall i\} \\ &\geq w^* \cdot (w_{t-1} + p_j) + \delta \\ &\geq w^* \cdot w_{t-1} + w^* \cdot p_j + \delta \\ &\geq w^* \cdot w_{t-1} + 2\delta \\ &\geq w^* \cdot w_0 + (k)\delta \quad (By\ induction) \end{aligned}$$

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- $cos\beta$ thus grows proportional to $\sqrt{k}$
- As k (number of corrections) increases $cos\beta$ can become arbitrarily large
- But since $cos\beta \leq 1$, k must be bounded by a maximum number
- Thus, there can only be a finite number of corrections (k) to w and the algorithm will converge!

Coming back to our questions ...

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- Do we always need to hand code the threshold?
- Are all inputs equal? What if we want to assign more weight (importance) to some inputs?
- What about functions which are not linearly separable ?

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- What about functions which are not linearly separable ? Not possible with a single perceptron but we will see how to handle this ..