Module 2.8: Representation Power of a Network of Perceptrons

• We will now see how to implement **any** boolean function using a network of perceptrons ...

• For this discussion, we will assume True = +1 and False = -1

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- ullet We consider 2 inputs and 4 perceptrons



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- Each input is connected to all the 4 perceptrons with specific weights



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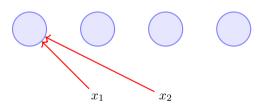
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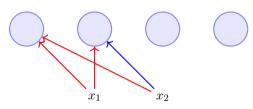
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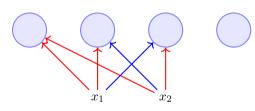
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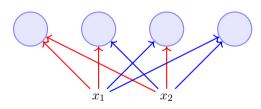
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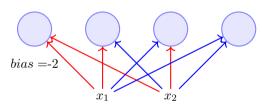
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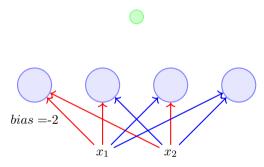


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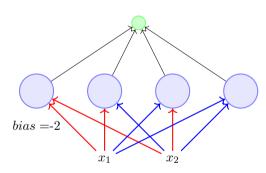
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- We consider 2 inputs and 4 perceptrons
- Each input is connected to all the 4 perceptrons with specific weights
- The bias (w_0) of each perceptron is -2 (i.e., each perceptron will fire only if the weighted sum of its input is ≥ 2)



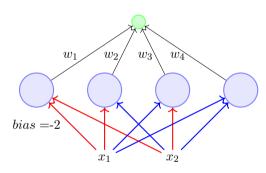
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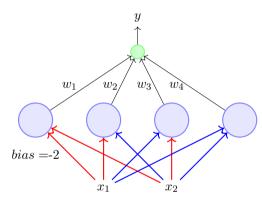
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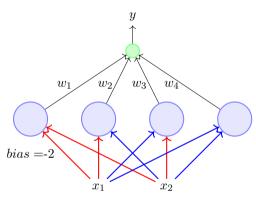
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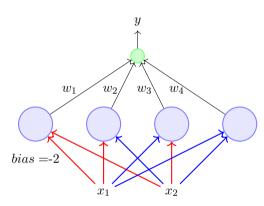
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- The output of this perceptron (y) is the output of this network

• This network contains 3 layers

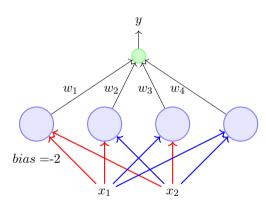


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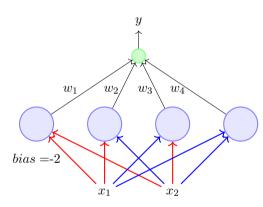
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- The layer containing the inputs (x_1, x_2) is called the **input layer**



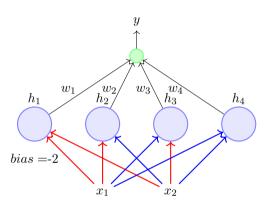
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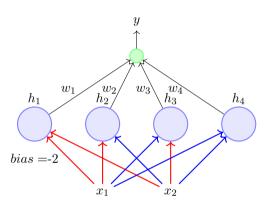
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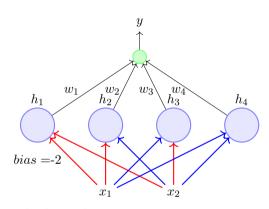
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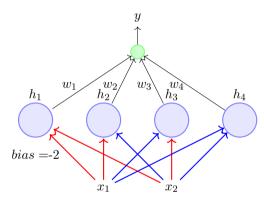
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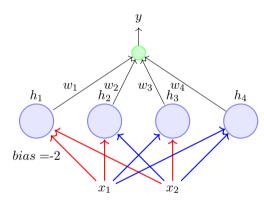
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- w_1, w_2, w_3, w_4 are called layer 2 weights



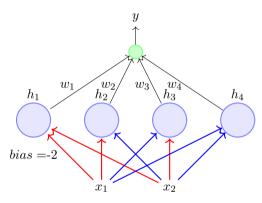
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• We claim that this network can be used to implement **any** boolean function (linearly separable or not)!



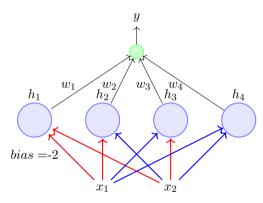
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- In other words, we can find w_1, w_2, w_3, w_4 such that the truth table of any boolean function can be represented by this network



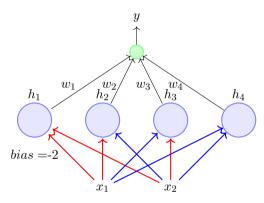
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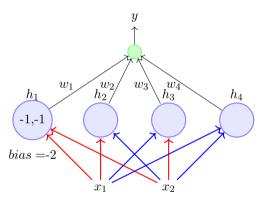
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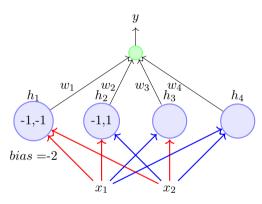
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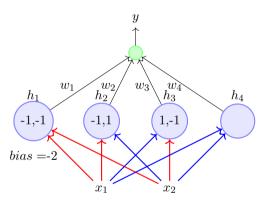
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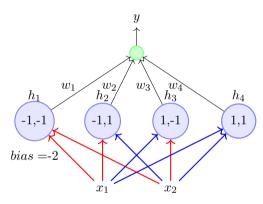
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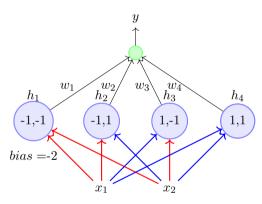
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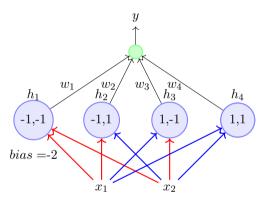
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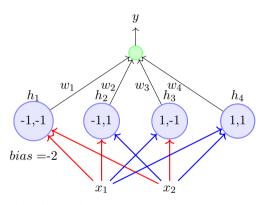
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- Let us see why this network works by taking an example of the XOR function



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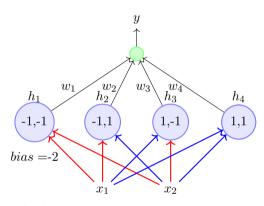
• Let w_0 be the bias output of the neuron (i.e., it will fire if $\sum_{i=1}^4 w_i h_i \geq w_0$)



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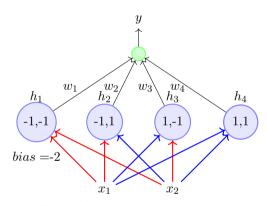
x_1	x_2	XOR	h_1	h_2	h_3	h_4	$\sum_{i=1}^4 w_i h_i$
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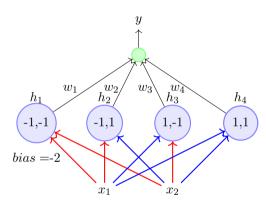
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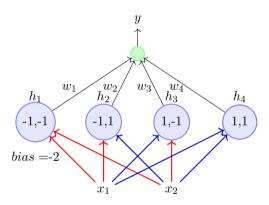
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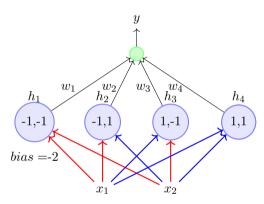


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• This results in the following four conditions to implement XOR: $w_1 < w_0, w_2 \ge w_0, w_3 \ge w_0, w_4 < w_0$

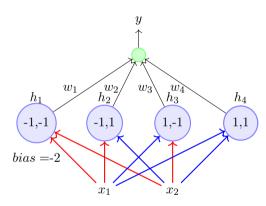


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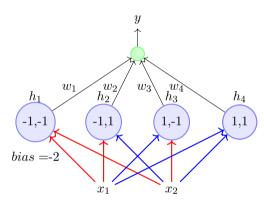


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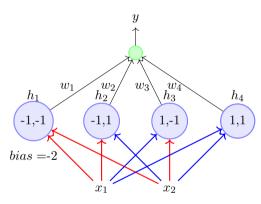
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- Unlike before, there are no contradictions now and the system of inequalities can be satisfied
- Essentially each w_i is now responsible for one of the 4 possible inputs and can be adjusted to get the desired output for that input



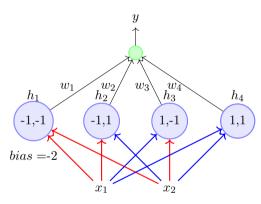
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- Each boolean function will result in a different set of non-contradicting inequalities which can be satisfied by appropriately setting w_1, w_2, w_3, w_4

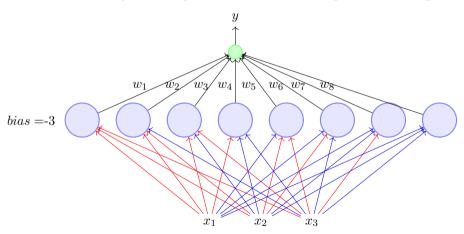


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- It should be clear that the same network can be used to represent the remaining 15 boolean functions also
- Each boolean function will result in a different set of non-contradicting inequalities which can be satisfied by appropriately setting w_1, w_2, w_3, w_4
- Try it!

• What if we have more than 3 inputs?

- Again each of the 8 perceptorns will fire only for one of the 8 inputs
- Each of the 8 weights in the second layer is responsible for one of the 8 inputs and can be adjusted to produce the desired output for that input



ullet What if we have n inputs ?

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Any boolean function of n inputs can be represented exactly by a network of perceptrons containing 1 hidden layer with 2^n perceptrons and one output layer containing 1 perceptron

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Proof (informal:) We just saw how to construct such a network

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Catch: As n increases the number of perceptrons in the hidden layers obviously increases exponentially

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- How does this help us with our original problem: which was to predict whether we like a movie or not? Let us see!

• We are given this data about our past movie experience

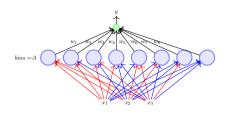
- We are given this data about our past movie experience
- For each movie, we are given the values of the various factors $(x_1, x_2, ..., x_n)$ that we base our decision on and we are also also given the value of y (like/dislike)

$$p_1 \quad \begin{bmatrix} x_{11} & x_{12} & \dots & x_{1n} & y_1 = 1 \\ x_{21} & x_{22} & \dots & x_{2n} & y_2 = 1 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_{k1} & x_{k2} & \dots & x_{kn} & y_i = 0 \\ n_2 & \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots \end{bmatrix}$$

- We are given this data about our past movie experience
- For each movie, we are given the values of the various factors $(x_1, x_2, ..., x_n)$ that we base our decision on and we are also also given the value of y (like/dislike)
- p_i 's are the points for which the output was 1 and n_i 's are the points for which it was 0

$$p_1 \\ p_2 \\ \vdots \\ n_1 \\ n_2 \\ x_{21} \\ x_{22} \\ \vdots \\ x_{k1} \\ x_{k2} \\ \vdots \\ x_{k2} \\ \vdots \\ x_{jn} \\ x_{j2} \\ \vdots \\ x_{jn} \\ x_{j2} \\ \vdots \\ x_{jn} \\ x_{jn}$$

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- The proof that we just saw tells us that it is possible to have a network of perceptrons and learn the weights in this network such that for any given p_i or n_j the output of the network will be the same as y_i or y_j (i.e., we can separate the positive and the negative points)

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- Specifically, it tells us that a MLP with a single hidden layer can represent **any** boolean function