Module 5.5 : Nesterov Accelerated Gradient Descent

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- Yes, let's look at Nesterov accelerated gradient

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Update rule for NAG

$$
\begin{aligned}
w_{look\_ahead} &= w_t - \gamma \cdot update_{t-1} \\
update_t &= \gamma \cdot update_{t-1} + \eta \nabla w_{look\_ahead} \\
w_{t+1} &= w_t - update_t
\end{aligned}
$$

We will have similar update rule for b_t

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def do_nesterov_accelerated_gradient_descent() :

    w, b, eta = init_w, init_b  , 1.0
    prev_v_w, prev_v_b, gamma = 0, 0, 0.9
    for i in range(max_epochs) :
        dw, db = 0, 0
        #do partial updates
        v_w = gamma * prev_v_w
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        for x,y in zip(X, Y) :
            #calculate gradients after partial update
            dw += grad_w(w - v_w, b - v_b, x, y)
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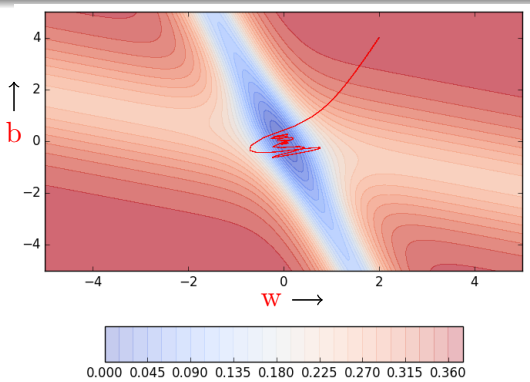

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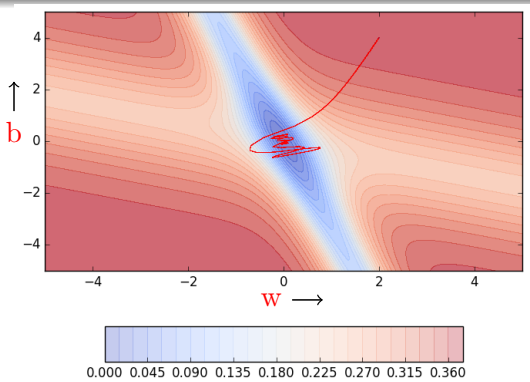

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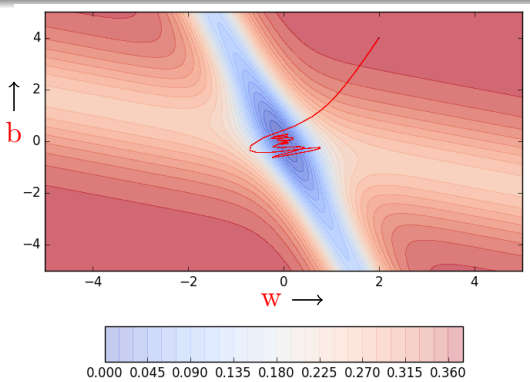

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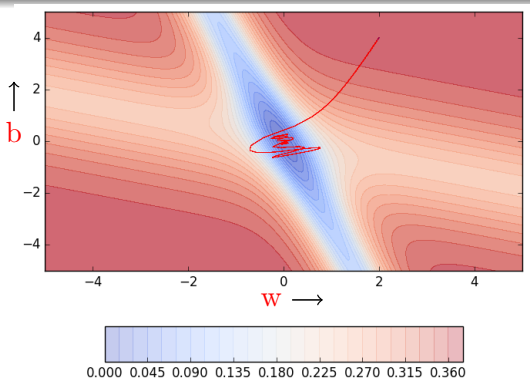

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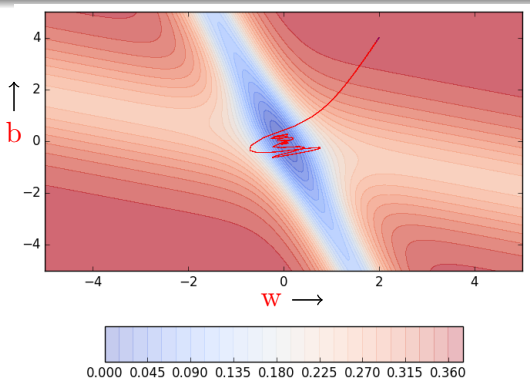

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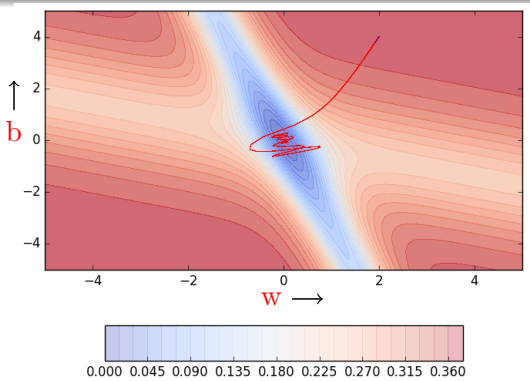

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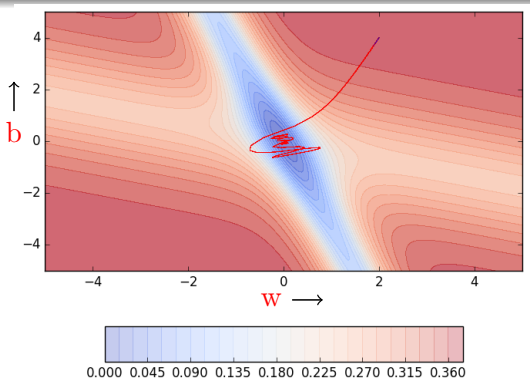

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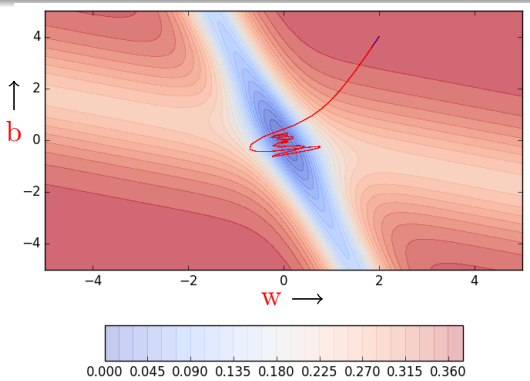

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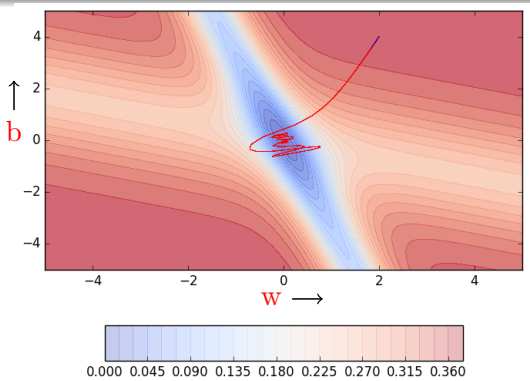

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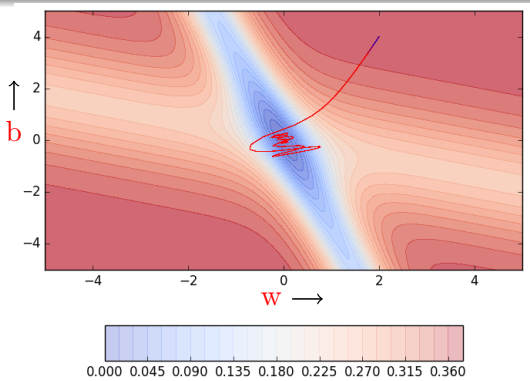

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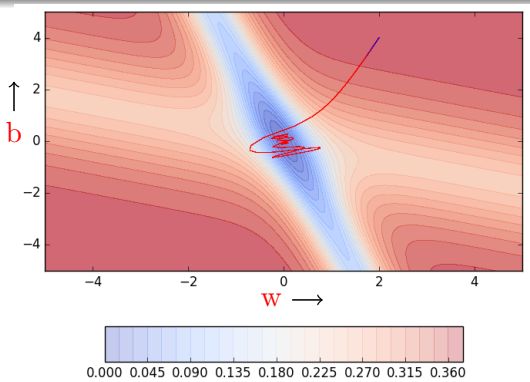

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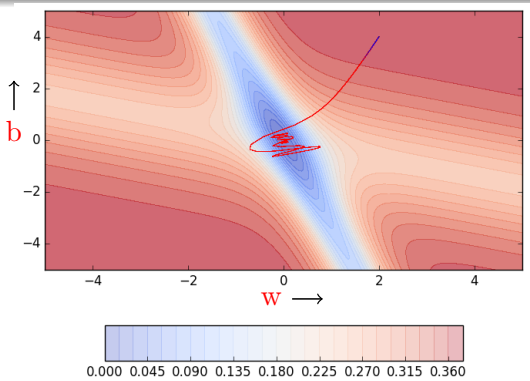

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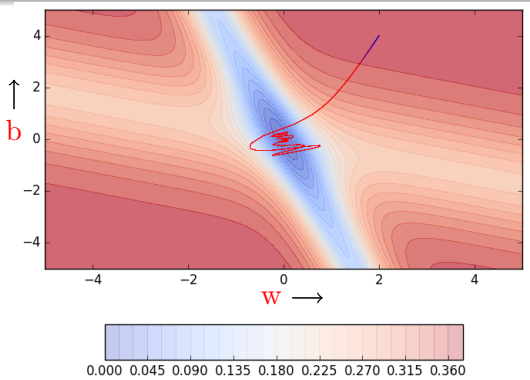

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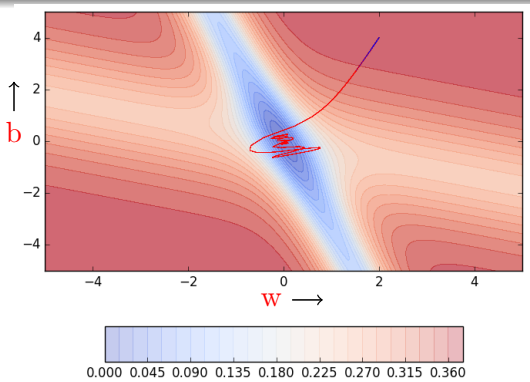

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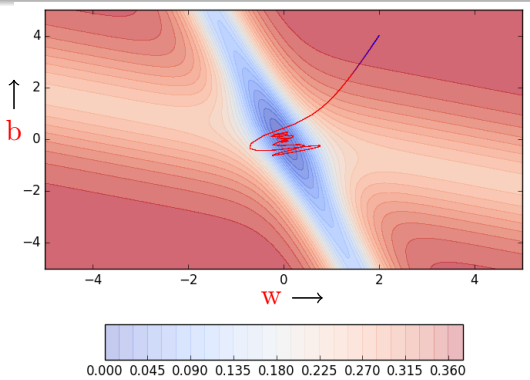

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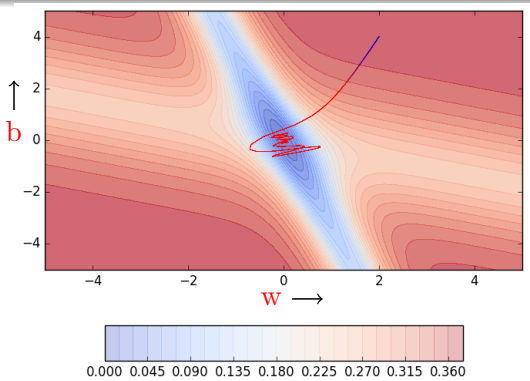

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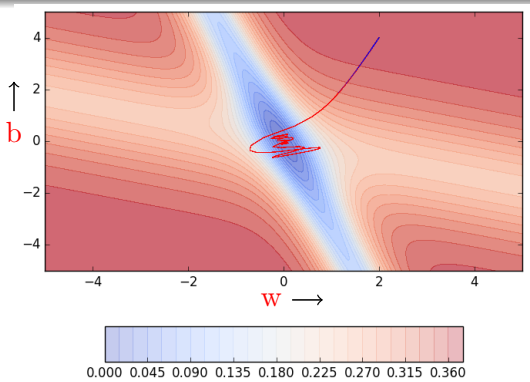

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        for x,y in zip(X, Y) :
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            dw += grad_w(w - v_w, b - v_b, x, y)
            db += grad_b(w - v_w, b - v_b, x, y)

        #now do the full update
        v_w = gamma * prev_v_w + eta * dw
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        w = w - v_w
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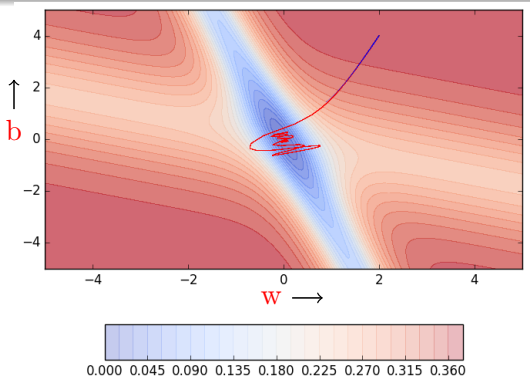

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def do_nesterov_accelerated_gradient_descent() :

    w, b, eta = init_w, init_b  , 1.0
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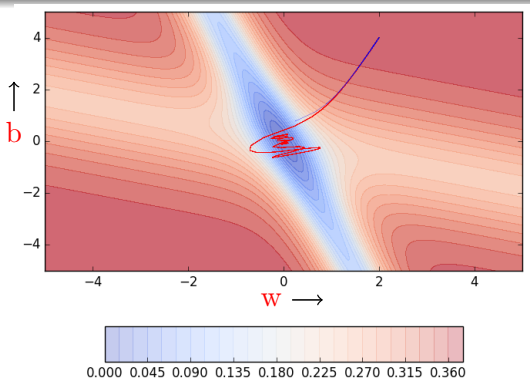

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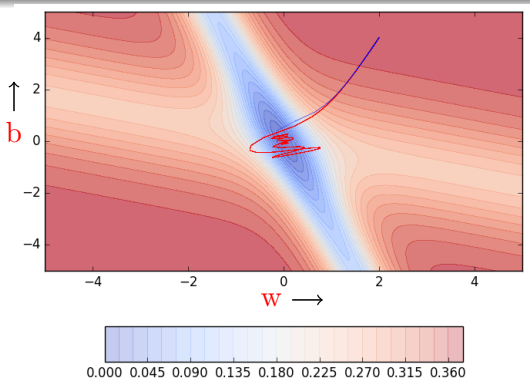

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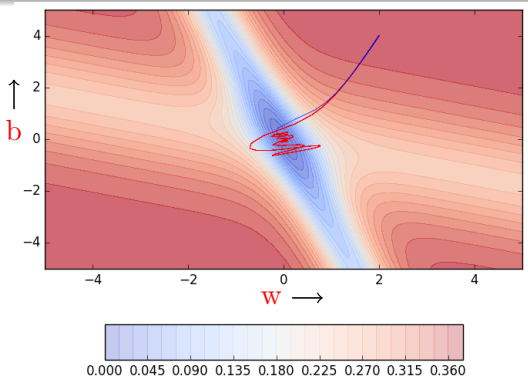

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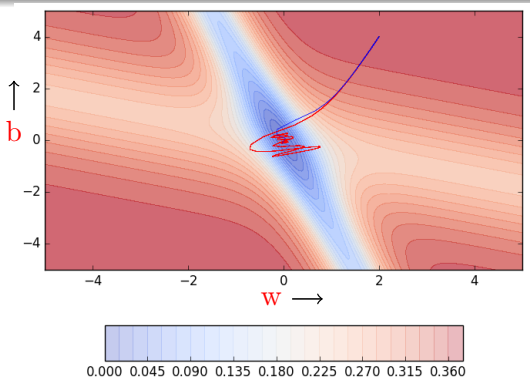

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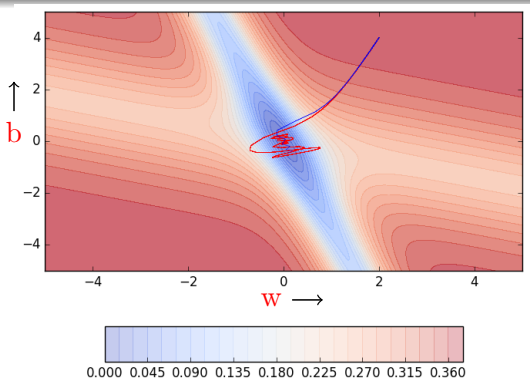

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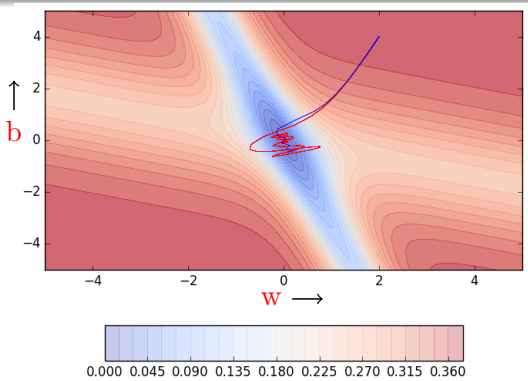

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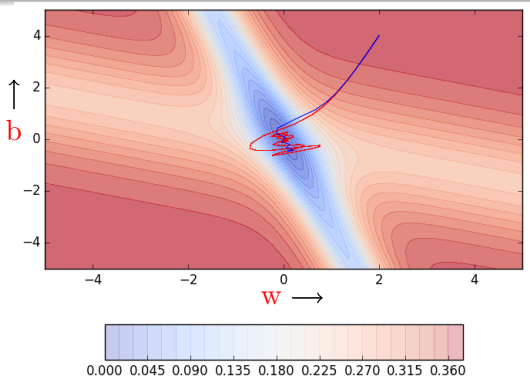

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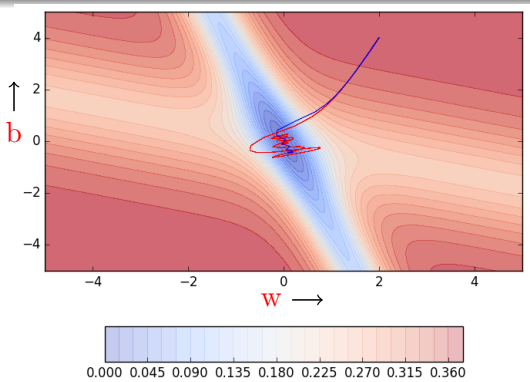

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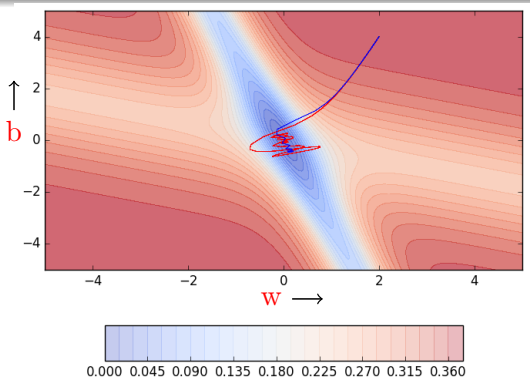

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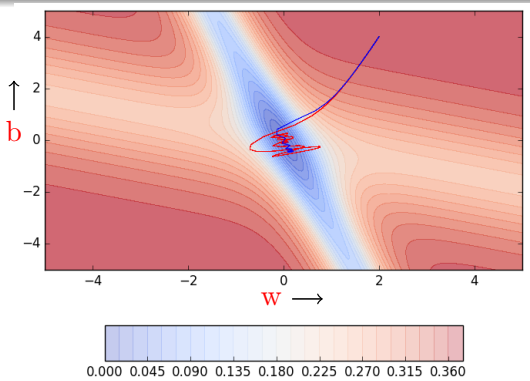

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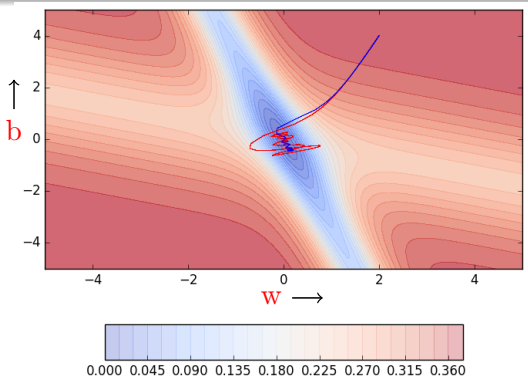

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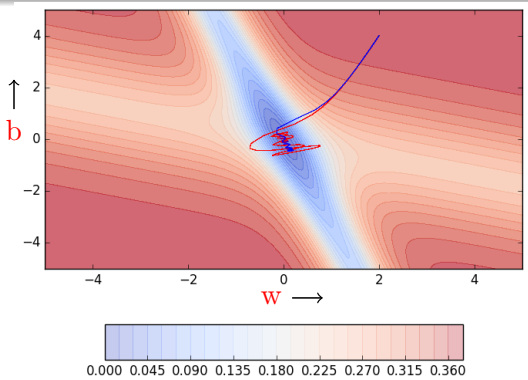

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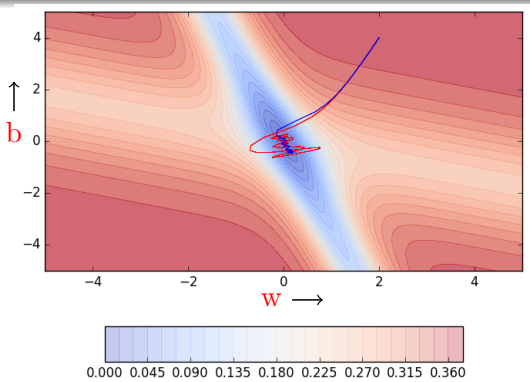

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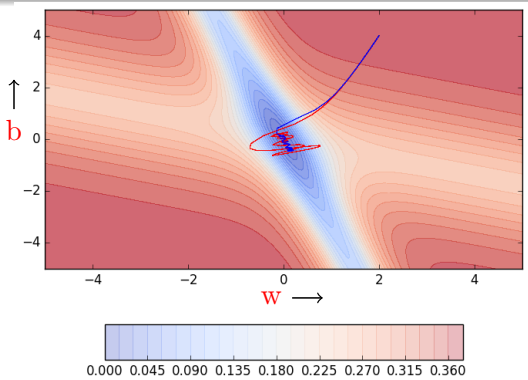

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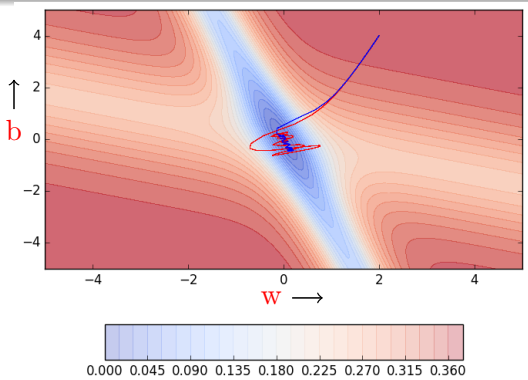

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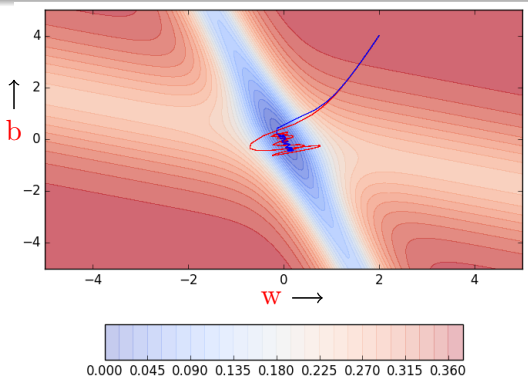

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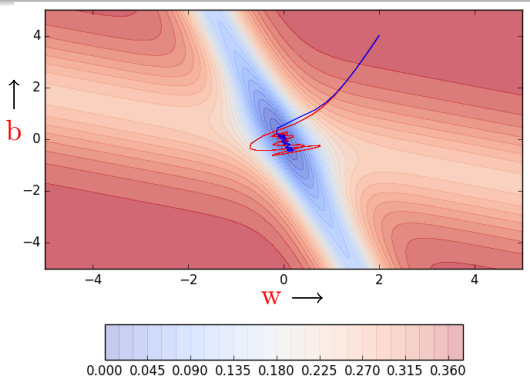

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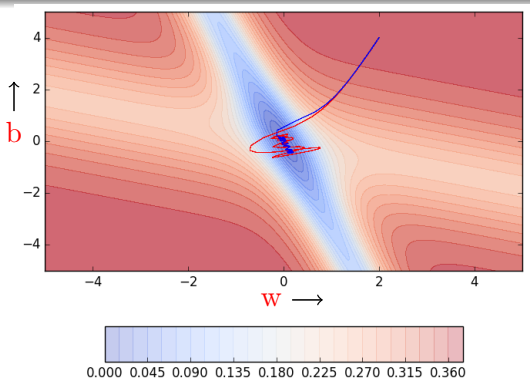

```python
def do_nesterov_accelerated_gradient_descent() :

    w, b, eta = init_w, init_b  , 1.0
    prev_v_w, prev_v_b, gamma = 0, 0, 0.9
    for i in range(max_epochs) :
        dw, db = 0, 0
        #do partial updates
        v_w = gamma * prev_v_w
        v_b = gamma * prev_v_b
        for x,y in zip(X, Y) :
            #calculate gradients after partial update
            dw += grad_w(w - v_w, b - v_b, x, y)
            db += grad_b(w - v_w, b - v_b, x, y)

        #now do the full update
        v_w = gamma * prev_v_w + eta * dw
        v_b = gamma * prev_v_b + eta * db
        w = w - v_w
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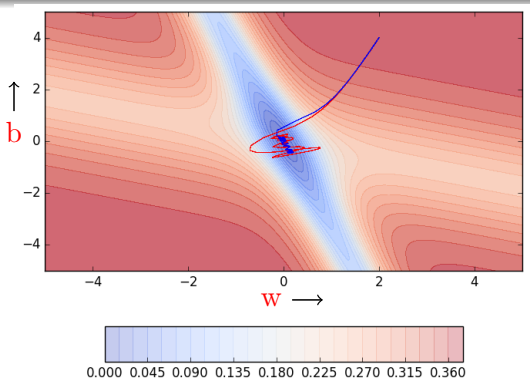

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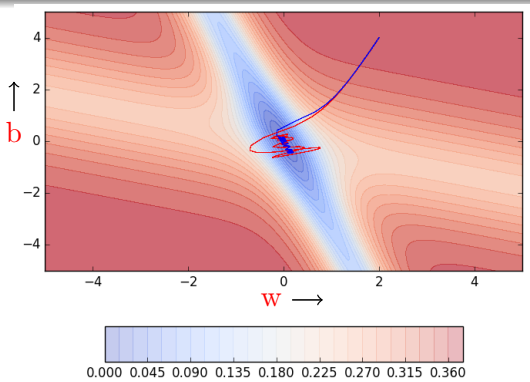

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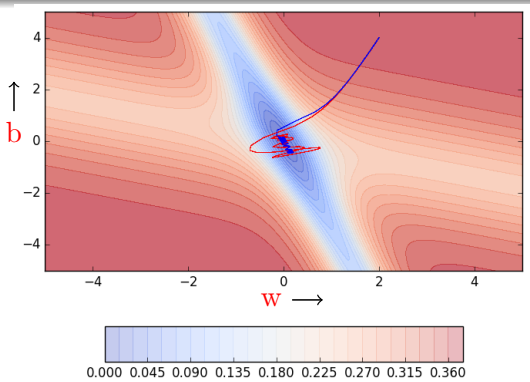

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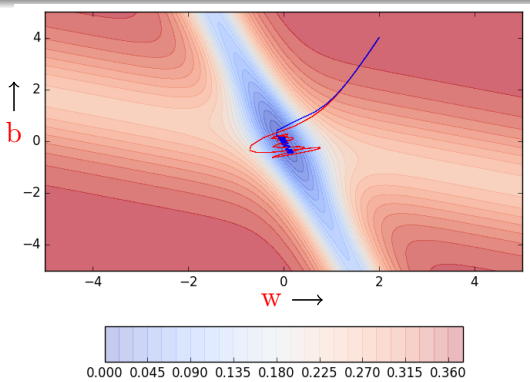

Observations about NAG

- Looking ahead helps NAG in correcting its course quicker than momentum based gradient descent

Observations about NAG

- Looking ahead helps NAG in correcting its course quicker than momentum based gradient descent
- Hence the oscillations are smaller and the chances of escaping the minima valley also smaller