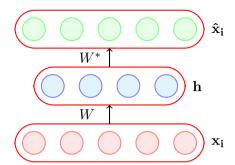
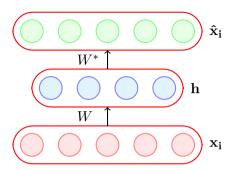
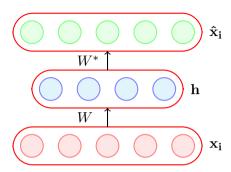
Module 7.1: Introduction to Autoencoders

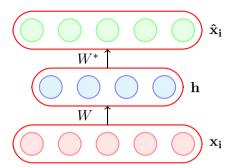




• An autoencoder is a special type of feed forward neural network which does the following

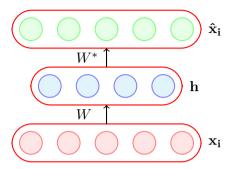


- An autoencoder is a special type of feed forward neural network which does the following
- \bullet Encodes its input $\mathbf{x_i}$ into a hidden representation \mathbf{h}



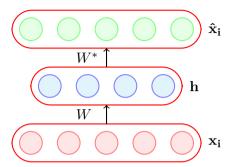
$$\mathbf{h} = g(W\mathbf{x_i} + \mathbf{b})$$

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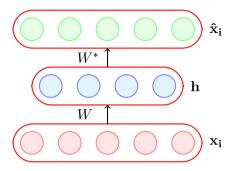
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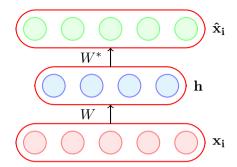
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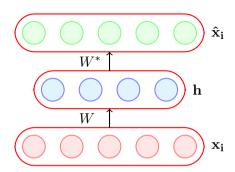
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- Encodes its input $\mathbf{x_i}$ into a hidden representation \mathbf{h}
- <u>Decodes</u> the input again from this hidden representation
- The model is trained to minimize a certain loss function which will ensure that $\hat{\mathbf{x}}_i$ is close to \mathbf{x}_i (we will see some such loss functions soon)



$$\mathbf{h} = g(W\mathbf{x_i} + \mathbf{b})$$

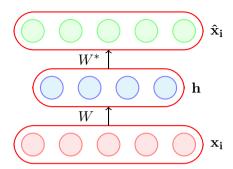
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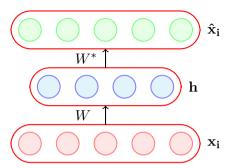
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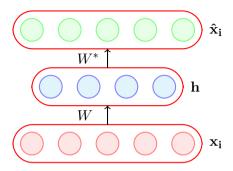
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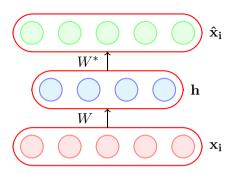
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- Do you see an analogy with PCA?

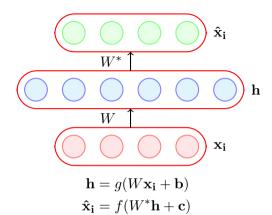


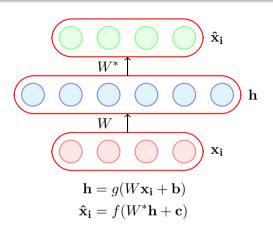
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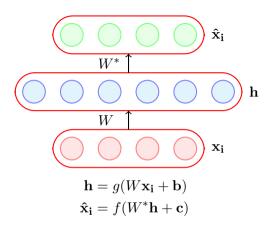
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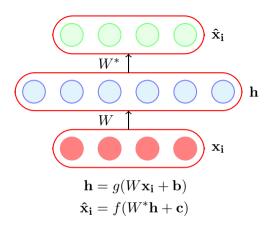




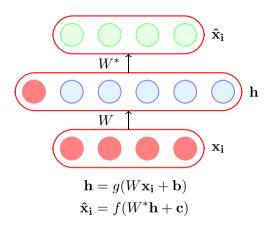
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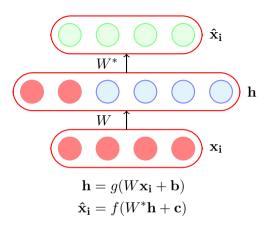
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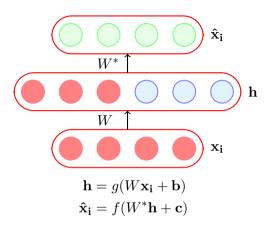
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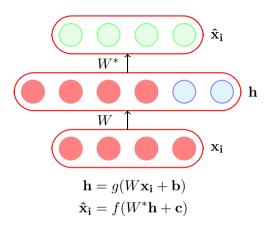
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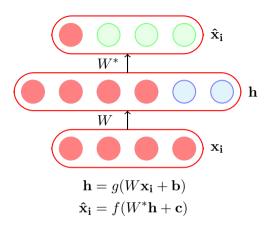
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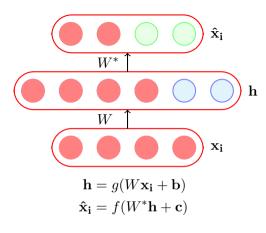
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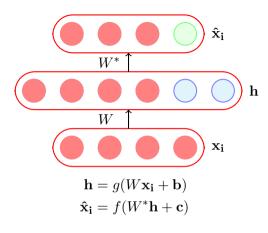
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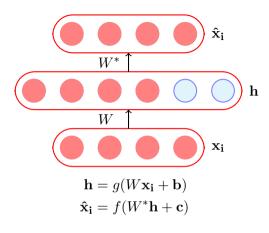
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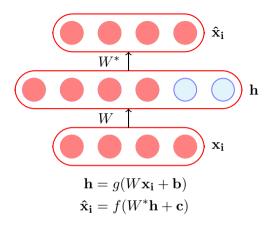
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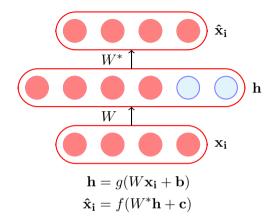
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- Such an identity encoding is useless in practice as it does not really tell us anything about the important characteristics of the data



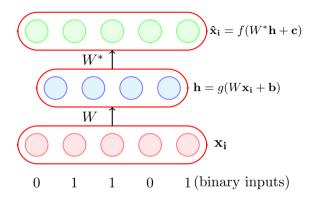
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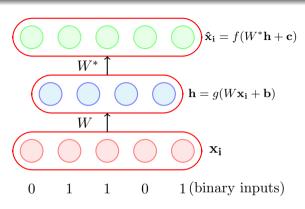
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 \bullet Choice of $f(\mathbf{x_i})$ and $g(\mathbf{x_i})$

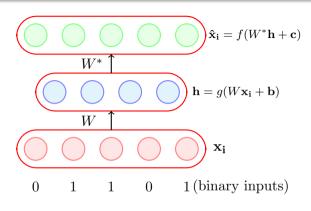
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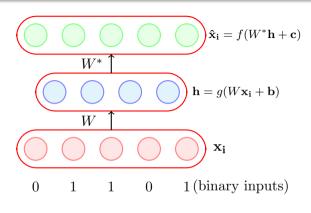




• Suppose all our inputs are binary (each $x_{ij} \in \{0,1\}$)

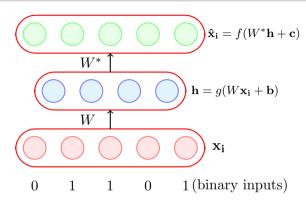


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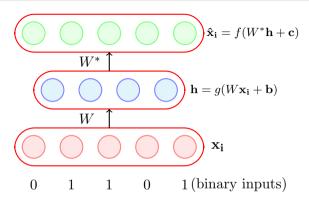
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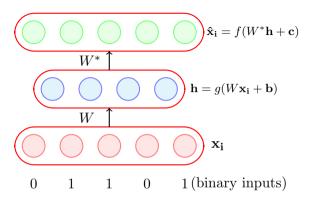
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$$\begin{aligned} \hat{\mathbf{x}}_{i} &= \tanh(W^*\mathbf{h} + \mathbf{c}) \\ \hat{\mathbf{x}}_{i} &= W^*\mathbf{h} + \mathbf{c} \\ \hat{\mathbf{x}}_{i} &= logistic(W^*\mathbf{h} + \mathbf{c}) \end{aligned}$$



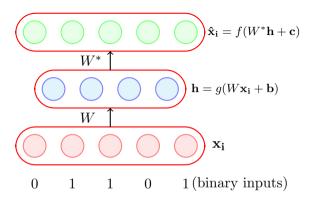
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• Logistic as it naturally restricts all outputs to be between 0 and 1



g is typically chosen as the sigmoid function

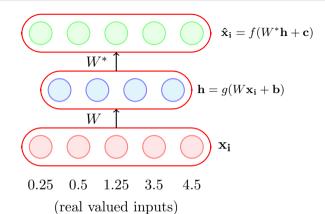
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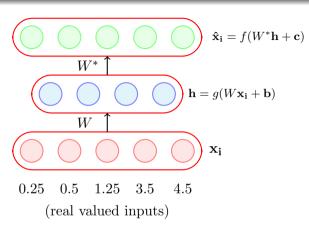
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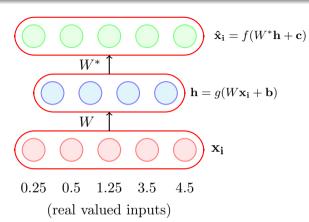
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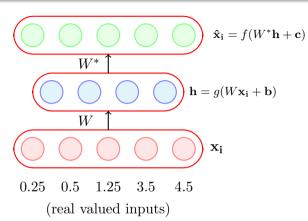




• Suppose all our inputs are real (each $x_{ij} \in \mathbb{R}$)

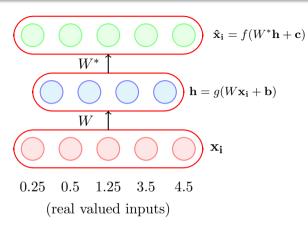


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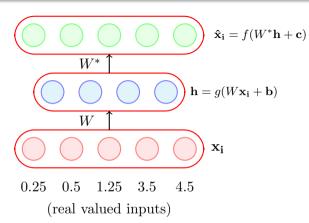
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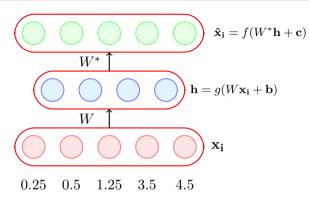


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(real valued inputs)

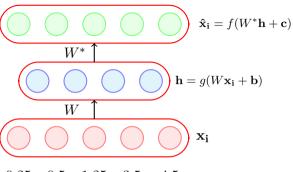
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• What will logistic and tanh do?



0.25 0.5 1.25 3.5 4.5 (real valued inputs)

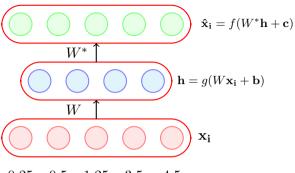
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- What will logistic and tanh do?
- They will restrict the reconstructed $\hat{\mathbf{x}}_i$ to lie between [0,1] or [-1,1] whereas we want $\hat{\mathbf{x}}_i \in \mathbb{R}^n$



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Again, g is typically chosen as the sigmoid function

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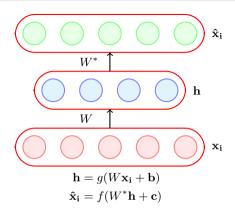
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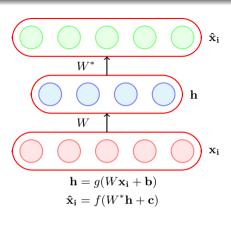
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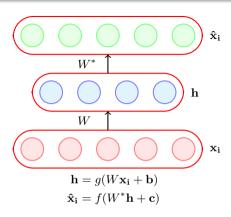
The Road Ahead

- Choice of $f(\mathbf{x_i})$ and $g(\mathbf{x_i})$
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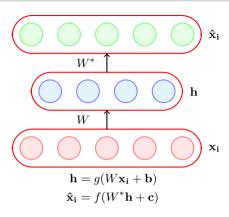




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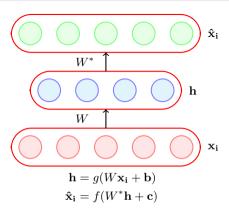


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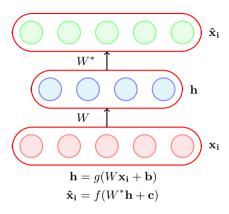
$$\min_{W,W^*,\mathbf{c},\mathbf{b}} \frac{1}{m} \sum_{i=1}^m \sum_{j=1}^n (\hat{x}_{ij} - x_{ij})^2$$



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$$i.e., \min_{W,W^*,\mathbf{c},\mathbf{b}} \frac{1}{m} \sum_{i=1}^m (\hat{\mathbf{x}}_i - \mathbf{x}_i)^T (\hat{\mathbf{x}}_i - \mathbf{x}_i)$$

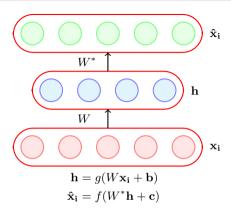


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i.e.,
$$\min_{W,W^*,\mathbf{c},\mathbf{b}} \frac{1}{m} \sum_{i=1}^m (\hat{\mathbf{x}}_i - \mathbf{x}_i)^T (\hat{\mathbf{x}}_i - \mathbf{x}_i)$$

 We can then train the autoencoder just like a regular feedforward network using backpropagation



- Consider the case when the inputs are real valued
- The objective of the autoencoder is to reconstruct $\hat{\mathbf{x}}_i$ to be as close to \mathbf{x}_i as possible
- This can be formalized using the following objective function:

$$\min_{W,W^*,\mathbf{c},\mathbf{b}} \frac{1}{m} \sum_{i=1}^m \sum_{j=1}^n (\hat{x}_{ij} - x_{ij})^2$$

i.e.,
$$\min_{W,W^*,\mathbf{c},\mathbf{b}} \frac{1}{m} \sum_{i=1}^m (\hat{\mathbf{x}}_i - \mathbf{x}_i)^T (\hat{\mathbf{x}}_i - \mathbf{x}_i)$$

- We can then train the autoencoder just like a regular feedforward network using backpropagation
- All we need is a formula for $\frac{\partial \mathcal{L}(\theta)}{\partial W^*}$ and $\frac{\partial \mathcal{L}(\theta)}{\partial W}$ which we will see now

$$\mathcal{L}(\theta) = (\hat{\mathbf{x}}_i - \mathbf{x}_i)^T (\hat{\mathbf{x}}_i - \mathbf{x}_i)$$

$$\mathbf{h}_2 = \hat{\mathbf{x}}_i$$

$$\mathbf{h}_1$$

$$\mathbf{h}_1$$

$$\mathbf{h}_0 = \mathbf{x}_i$$

$$\mathcal{L}(\theta) = (\hat{\mathbf{x}}_i - \mathbf{x}_i)^T (\hat{\mathbf{x}}_i - \mathbf{x}_i)$$

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$$W^*$$

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$$\mathbf{h}_1$$

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$$\bullet \quad \frac{\partial \mathcal{L}(\theta)}{\partial W^*} = \frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{h_2}} \boxed{\frac{\partial \mathbf{h_2}}{\partial \mathbf{a_2}} \frac{\partial \mathbf{a_2}}{\partial W^*}}$$

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$$\mathbf{h}_2 = \hat{\mathbf{x}}_i$$

$$\mathbf{h}_1$$

$$\mathbf{a}_1$$

$$W^*$$

$$\mathbf{h}_0 = \mathbf{x}_i$$

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$$\bullet \quad \frac{\partial \mathcal{L}(\theta)}{\partial W} = \frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{h_2}} \left[\frac{\partial \mathbf{h_2}}{\partial \mathbf{a_2}} \frac{\partial \mathbf{a_2}}{\partial \mathbf{h_1}} \frac{\partial \mathbf{h_1}}{\partial \mathbf{a_1}} \frac{\partial \mathbf{a_1}}{\partial W} \right]$$

$$\mathcal{L}(\theta) = (\hat{\mathbf{x}}_i - \mathbf{x}_i)^T (\hat{\mathbf{x}}_i - \mathbf{x}_i)$$

$$\mathbf{h}_2 = \hat{\mathbf{x}}_i$$

$$\mathbf{h}_1$$

$$\mathbf{h}_1$$

$$\mathbf{h}_0 = \mathbf{x}_i$$

•
$$\frac{\partial \mathcal{L}(\theta)}{\partial W^*} = \frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{h_2}} \boxed{\frac{\partial \mathbf{h_2}}{\partial \mathbf{a_2}} \frac{\partial \mathbf{a_2}}{\partial W^*}}$$

$$\frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{h_2}} = \frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{\hat{x}_i}}$$

$$\mathcal{L}(\theta) = (\hat{\mathbf{x}}_i - \mathbf{x}_i)^T (\hat{\mathbf{x}}_i - \mathbf{x}_i)$$

$$\mathbf{h}_2 = \hat{\mathbf{x}}_i$$

$$\mathbf{h}_1$$

$$\mathbf{a}_1$$

$$W^*$$

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$$\bullet \ \frac{\partial \mathcal{L}(\theta)}{\partial W^*} = \frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{h_2}} \boxed{\frac{\partial \mathbf{h_2}}{\partial \mathbf{a_2}} \frac{\partial \mathbf{a_2}}{\partial W^*}}$$

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$$\begin{split} \frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{h_2}} &= \frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{\hat{x}_i}} \\ &= \nabla_{\mathbf{\hat{x}_i}} \{ (\mathbf{\hat{x}_i} - \mathbf{x_i})^T (\mathbf{\hat{x}_i} - \mathbf{x_i}) \} \end{split}$$

$$\mathcal{L}(\theta) = (\hat{\mathbf{x}}_i - \mathbf{x}_i)^T (\hat{\mathbf{x}}_i - \mathbf{x}_i)$$

$$\mathbf{h}_2 = \hat{\mathbf{x}}_i$$

$$\mathbf{h}_1$$

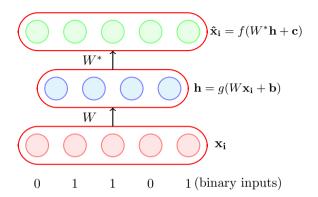
$$\mathbf{h}_1$$

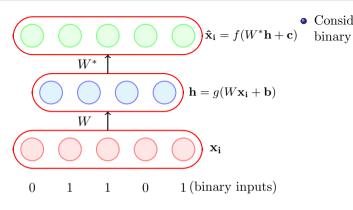
$$\mathbf{h}_0 = \mathbf{x}_i$$

$$\bullet \quad \frac{\partial \mathcal{L}(\theta)}{\partial W^*} = \frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{h_2}} \boxed{\frac{\partial \mathbf{h_2}}{\partial \mathbf{a_2}} \frac{\partial \mathbf{a_2}}{\partial W^*}}$$

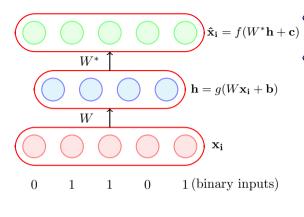
$$\bullet \quad \frac{\partial \mathcal{L}(\theta)}{\partial W} = \frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{h_2}} \left[\frac{\partial \mathbf{h_2}}{\partial \mathbf{a_2}} \frac{\partial \mathbf{a_2}}{\partial \mathbf{h_1}} \frac{\partial \mathbf{h_1}}{\partial \mathbf{a_1}} \frac{\partial \mathbf{a_1}}{\partial W} \right]$$

$$\frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{h_2}} = \frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{\hat{x}_i}}
= \nabla_{\mathbf{\hat{x}_i}} \{ (\mathbf{\hat{x}_i} - \mathbf{x_i})^T (\mathbf{\hat{x}_i} - \mathbf{x_i}) \}
= 2(\mathbf{\hat{x}_i} - \mathbf{x_i})$$

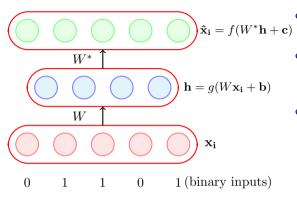




• Consider the case when the inputs are binary

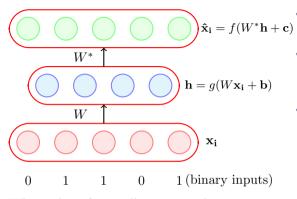


- Consider the case when the inputs are binary
- We use a sigmoid decoder which will produce outputs between 0 and 1, and can be interpreted as probabilities.



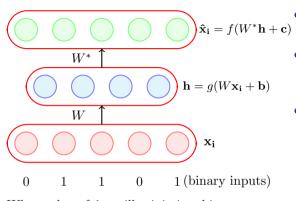
- Consider the case when the inputs are binary
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- ullet For a single n-dimensional i^{th} input we can use the following loss function

$$\min\{-\sum_{j=1}^{n} (x_{ij} \log \hat{x}_{ij} + (1 - x_{ij}) \log(1 - \hat{x}_{ij}))\}$$



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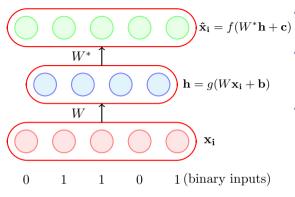
$$\min\{-\sum_{j=1}^{n} (x_{ij} \log \hat{x}_{ij} + (1 - x_{ij}) \log(1 - \hat{x}_{ij}))\}$$



• If $x_{ij} = 1$?

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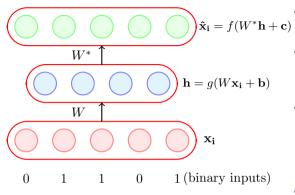
$$\min\{-\sum_{j=1}^{n}(x_{ij}\log\hat{x}_{ij}+(1-x_{ij})\log(1-\hat{x}_{ij}))\}$$



- If $x_{ij} = 1$?
- If $x_{ij} = 0$?

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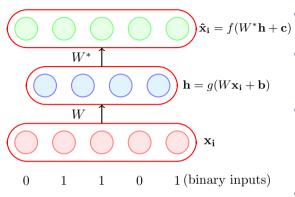


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• Again we need is a formula for $\frac{\partial \mathcal{L}(\theta)}{\partial W^*}$ and $\frac{\partial \mathcal{L}(\theta)}{\partial W}$ to use backpropagation



- If $x_{ij} = 1$?
- If $x_{ij} = 0$?

Indeed the above function will be minimized when $\hat{x}_{ij} = x_{ij}$!

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$$\min\{-\sum_{j=1}^{n} (x_{ij} \log \hat{x}_{ij} + (1 - x_{ij}) \log(1 - \hat{x}_{ij}))\}$$

• Again we need is a formula for $\frac{\partial \mathcal{L}(\theta)}{\partial W^*}$ and $\frac{\partial \mathcal{L}(\theta)}{\partial W}$ to use backpropagation

$$\mathcal{L}(\theta) = -\sum_{j=1}^{n} (x_{ij} \log \hat{x}_{ij} + (1 - x_{ij}) \log(1 - \hat{x}_{ij}))$$

$$\mathbf{h_2} = \hat{\mathbf{x}_i}$$

$$\mathbf{a_2}$$

$$\mathbf{h_1}$$

$$\mathbf{a_1}$$

$$\mathbf{h_0} = \mathbf{x_i}$$

L20pt

$$\mathcal{L}(\theta) = -\sum_{j=1}^{n} (x_{ij} \log \hat{x}_{ij} + (1 - x_{ij}) \log(1 - \hat{x}_{ij}))$$

$$\mathbf{h_2} = \hat{\mathbf{x}}_{\mathbf{i}}$$

$$\mathbf{h_2}$$

$$\mathbf{h_1}$$

$$\mathbf{h_0} = \mathbf{x_i}$$

•
$$\frac{\partial \mathcal{L}(\theta)}{\partial W^*} = \frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{h_2}} \frac{\partial \mathbf{h_2}}{\partial \mathbf{a_2}} \frac{\partial \mathbf{a_2}}{\partial W^*}$$

L20pt

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$$\bullet \ \, \frac{\partial \mathcal{L}(\theta)}{\partial W^*} = \frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{h_2}} \frac{\partial \mathbf{h_2}}{\partial \mathbf{a_2}} \boxed{\frac{\partial \mathbf{a_2}}{\partial W^*}}$$

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L20pt

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$$\bullet \ \frac{\partial \mathcal{L}(\theta)}{\partial W^*} = \frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{h_2}} \frac{\partial \mathbf{h_2}}{\partial \mathbf{a_2}} \left[\frac{\partial \mathbf{a_2}}{\partial W^*} \right]$$

$$\bullet \ \, \frac{\partial \mathcal{L}(\theta)}{\partial W} = \frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{h_2}} \frac{\partial \mathbf{h_2}}{\partial \mathbf{a_2}} \boxed{\frac{\partial \mathbf{a_2}}{\partial \mathbf{h_1}} \frac{\partial \mathbf{h_1}}{\partial \mathbf{a_1}} \frac{\partial \mathbf{a_1}}{\partial W}}$$

• We have already seen how to calculate the expressions in the square boxes when we learnt BP

$$\mathcal{L}(\theta) = -\sum_{j=1}^{n} (x_{ij} \log \hat{x}_{ij} + (1 - x_{ij}) \log(1 - \hat{x}_{ij}))$$

$$\mathbf{h_2} = \hat{\mathbf{x}}_{i}$$

$$\mathbf{h_1}$$

$$\mathbf{h_1}$$

$$\mathbf{h_0} = \mathbf{x}_{i}$$

$$W^*$$

L20pt

$$\bullet \ \frac{\partial \mathcal{L}(\theta)}{\partial W^*} = \frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{h_2}} \frac{\partial \mathbf{h_2}}{\partial \mathbf{a_2}} \boxed{\frac{\partial \mathbf{a_2}}{\partial W^*}}$$

$$\bullet \ \, \frac{\partial \mathscr{L}(\theta)}{\partial W} = \frac{\partial \mathscr{L}(\theta)}{\partial \mathbf{h_2}} \frac{\partial \mathbf{h_2}}{\partial \mathbf{a_2}} \boxed{\frac{\partial \mathbf{a_2}}{\partial \mathbf{h_1}} \frac{\partial \mathbf{h_1}}{\partial \mathbf{a_1}} \frac{\partial \mathbf{a_1}}{\partial W}}$$

- We have already seen how to calculate the expressions in the square boxes when we learnt BP
- The first two terms on RHS can be computed as:

$$\frac{\partial \hat{\mathcal{L}}(\theta)}{\partial h_{2j}} = -\frac{x_{ij}}{\hat{x}_{ij}} + \frac{1 - x_{ij}}{1 - \hat{x}_{ij}}$$
$$\frac{\partial h_{2j}}{\partial a_{2j}} = \sigma(a_{2j})(1 - \sigma(a_{2j}))$$

$$\mathcal{L}(\theta) = -\sum_{j=1}^{n} (x_{ij} \log \hat{x}_{ij} + (1 - x_{ij}) \log(1 - \hat{x}_{ij}))$$

$$\mathbf{h_2} = \hat{\mathbf{x}_i}$$

$$\mathbf{h_1}$$

$$\mathbf{a_1}$$

$$W^*$$

$$L20pt\frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{h_2}} = \frac{\partial \mathcal{L}(\theta)}{\partial h_{21}} \frac{\partial \mathcal{L}(\theta)}{\partial h_{22}} : \frac{\partial \mathcal{L}(\theta)}{\partial h_{2n}}$$

 $h_0 = x_i$

$$\bullet \ \, \frac{\partial \mathcal{L}(\theta)}{\partial W^*} = \frac{\partial \mathcal{L}(\theta)}{\partial \mathbf{h_2}} \frac{\partial \mathbf{h_2}}{\partial \mathbf{a_2}} \boxed{\frac{\partial \mathbf{a_2}}{\partial W^*}}$$

$$\bullet \ \, \frac{\partial \mathscr{L}(\theta)}{\partial W} = \frac{\partial \mathscr{L}(\theta)}{\partial \mathbf{h_2}} \frac{\partial \mathbf{h_2}}{\partial \mathbf{a_2}} \boxed{\frac{\partial \mathbf{a_2}}{\partial \mathbf{h_1}} \frac{\partial \mathbf{h_1}}{\partial \mathbf{a_1}} \frac{\partial \mathbf{a_1}}{\partial W}}$$

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