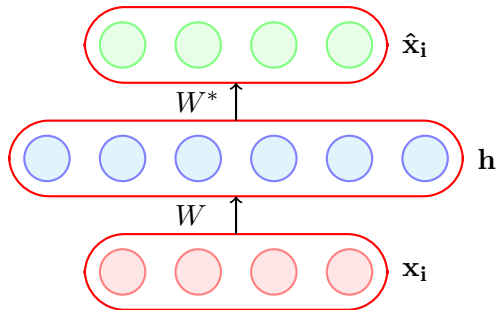
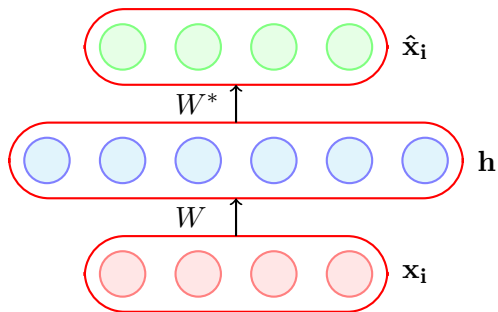
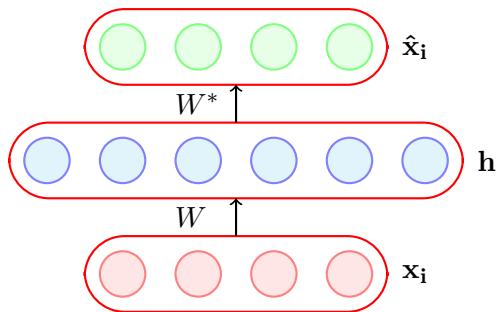


## Module 7.3: Regularization in autoencoders (Motivation)

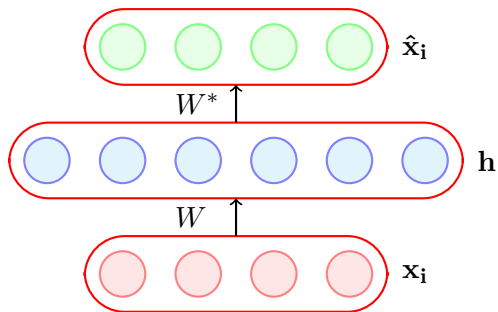




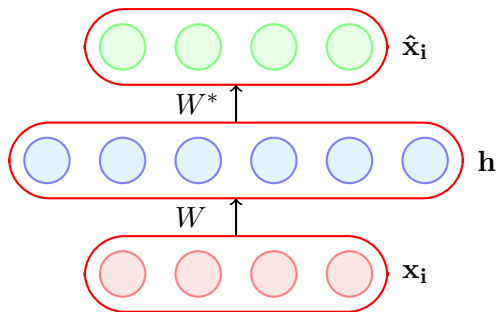
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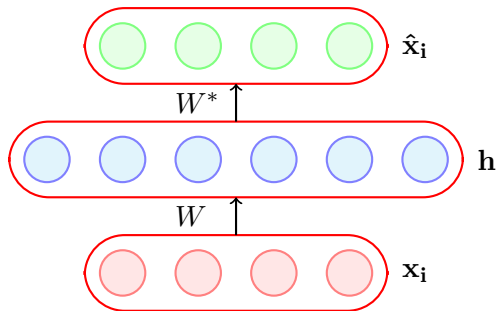


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- Here, (as stated earlier) the model can simply learn to copy  $\mathbf{x}_i$  to  $\mathbf{h}$  and then  $\mathbf{h}$  to  $\hat{\mathbf{x}}_i$
- To avoid poor generalization, we need to introduce regularization



- The simplest solution is to add a  $L_2$ -regularization term to the objective function

$$\min_{\theta, w, w^*, \mathbf{b}, \mathbf{c}} \frac{1}{m} \sum_{i=1}^m \sum_{j=1}^n (\hat{x}_{ij} - x_{ij})^2 + \lambda \|\theta\|^2$$

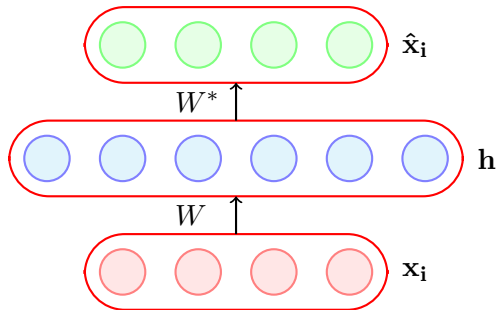


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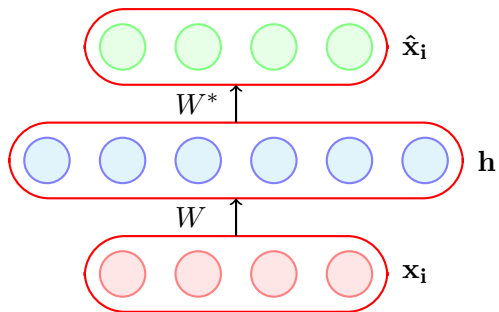
$$\min_{\theta, w, w^*, \mathbf{b}, \mathbf{c}} \frac{1}{m} \sum_{i=1}^m \sum_{j=1}^n (\hat{x}_{ij} - x_{ij})^2 + \lambda \|\theta\|^2$$

- This is very easy to implement and just adds a term  $\lambda W$  to the gradient  $\frac{\partial \mathcal{L}(\theta)}{\partial W}$  (and similarly for other parameters)

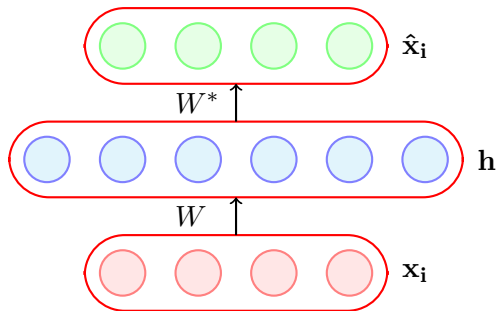
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- This effectively reduces the capacity of Autoencoder and acts as a regularizer