

Markov chains - review

(See EE6150 course homepage for detailed notes)

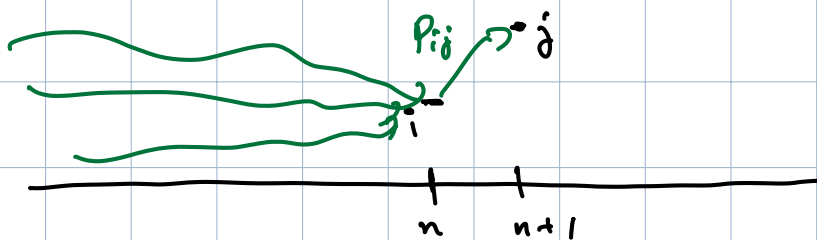
Def: A stochastic process $\{X_n, n \geq 0\}$ with a countable state space S is a DTMC if

(i) $X_n \in S, \forall n \geq 0$

(ii) $\forall n \geq 0, i, j \in S,$

Markov property $\left\{ \begin{aligned} &P(X_{n+1} = j \mid X_n = i, X_{n-1} = i_{n-1}, X_{n-2} = i_{n-2}, \dots, X_0 = i_0) \\ &= P(X_{n+1} = j \mid X_n = i) \end{aligned} \right.$

"The future is conditionally independent of the past, given the present".



Def: A DTMC with countable state space S is time-homogeneous if

$$P(X_{n+1} = j \mid X_n = i) = P_{i,j} \quad \forall n \geq 0, \forall i, j \in S$$

transition probability

If the state space is finite, we can form the "transition probability matrix" P as follows:

Let $|S| = m$

$$P = \begin{matrix} & \begin{matrix} 1 & - & - & - & m \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ \vdots \\ m \end{matrix} & \begin{bmatrix} p_{1,1} & & & p_{1,m} \\ \vdots & & & \vdots \\ p_{m,1} & - & - & - & p_{m,m} \end{bmatrix} \end{matrix}$$

Q: Is the transition probability matrix (t.p.m.), say enough to derive the finite dimensional distribution i.e.,

$$P(X_0 = i_0, X_1 = i_1, \dots, X_n = i_n) ? \text{ "NO"}$$

Simple case:

$$\begin{aligned} P(X_0 = i_0, X_1 = i_1) \\ &= P(X_1 = i_1 | X_0 = i_0) P(X_0 = i_0) \\ &= p_{i_0, i_1} \times P(X_0 = i_0) \end{aligned}$$

Suppose we are given

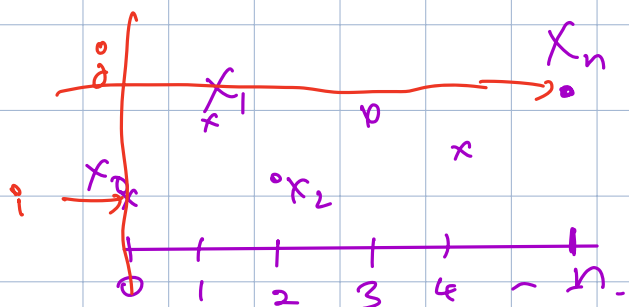
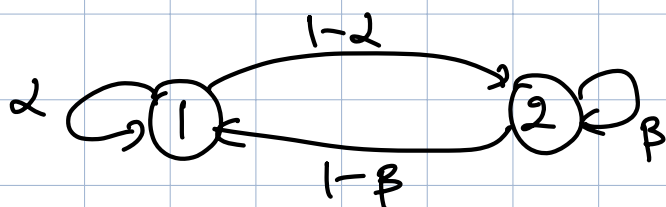
$$a_i = P(X_0 = i), \forall i \in S$$

} Initial distribution

Fact: A DTMC $\{X_n, n \geq 0\}$ is completely specified by the initial distribution " a " & t.p.m. P .

Example: Two-state DTMC
 $S = \{1, 2\}$

$$P = \begin{bmatrix} \alpha & 1-\alpha \\ 1-\beta & \beta \end{bmatrix} \quad 0 \leq \alpha, \beta \leq 1$$



Marginal distributions

Let $\{X_n, n \geq 0\}$ be a DTMC with state space
 $S = \{0, 1, 2, \dots\}$, t.p.m. "P", &
 initial distribution "a"

Want: $a_j^{(n)} = P(X_n = j)$ ← distribution of X_n

$$\begin{aligned} P(X_n = j) &= \sum_{i \in S} P(X_n = j | X_0 = i) P(X_0 = i) \\ &= \sum_{i \in S} P(X_n = j | X_0 = i) a_i \\ &= \sum_{i \in S} a_i P_{i,j}^{(n)}, \end{aligned}$$

where $\underline{P_{i,j}^{(n)}} = P(X_n = j | X_0 = i), \forall i, j \in S, n \geq 0$

n-step transition probability

In particular,

$$P_{i,j}^{(0)} = P(X_0=j | X_0=i) = \delta_{i,j}, \quad i, j \in S,$$

$$\text{where } \delta_{i,j} = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{else} \end{cases}$$

$$P_{i,j}^{(1)} = P(X_1=j | X_0=i) = P_{i,j}, \quad i, j \in S$$

Q: How to calculate $P_{i,j}^{(n)}$, $n \geq 2$?

Chapman-Kolmogorov equations

$$P_{i,j}^{(n)} = \sum_{r \in S} P_{i,r}^{(k)} P_{r,j}^{(n-k)}, \quad i, j \in S$$

$$\text{where } 0 \leq k \leq n$$



Suppose $|S| = m < \infty$ (finite state space)

$$P^{(n)} = \begin{bmatrix} P_{1,1}^{(n)} & \cdots & P_{1,m}^{(n)} \\ \vdots & & \vdots \\ P_{m,1}^{(n)} & \cdots & P_{m,m}^{(n)} \end{bmatrix}$$

n-step t.p.m.

$$P^{(n)} = [p_{i,j}^{(n)}]_{i,j=1,\dots,m}$$

Lecture 29*

Chapman-Kolmogorov equation:

$$P^{(n)} = P^{(k)} P^{(n-k)}, \quad 0 \leq k \leq n$$

Fact: $P^{(n)} = \underbrace{P^n}_{n\text{th power of t.p.m. } P}$

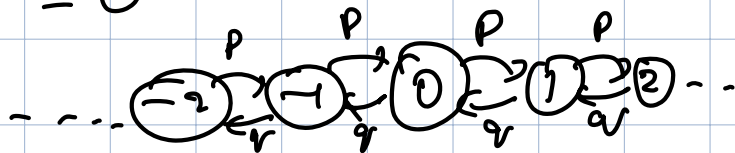
EXAMPLE: Random walk

$$p_{i,i+1} = p, \quad p_{i,i-1} = q (=1-p), \quad -\infty < i < \infty$$

$$0 < p < 1$$

Find $P_{0,0}^{(n)} = P(X_n = 0 \mid X_0 = 0)$

If n is odd, $P_{0,0}^{(n)} = 0$



If n is even, say $n = 2k$, then one has to take k steps to right & k steps to left, in any order.

$$P_{0,0}^{(2k)} = \frac{(2k)!}{k! k!} \underbrace{p^k q^k}_{\substack{\text{prob of } k \text{ left} \times \text{prob } k \text{ right steps}}}$$

\downarrow
ways (distinct)
of k right &

k left steps

EXAMPLE:

DTMC with $S = \{1, 2, 3, 4\}$

$$a = \left\{ \frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4} \right\}$$

$$P = \begin{bmatrix} 0.1 & 0.2 & 0.3 & 0.4 \\ 0.25 & 0.25 & 0.5 & 0 \\ 0.5 & 0 & 0.1 & 0.4 \\ 0 & 0 & 0.4 & 0.6 \end{bmatrix}$$

$$a^{(4)} = a P^4 = \text{H.W.},$$

$$\text{where } a^{(4)} = \left[P(X_4=1) \quad P(X_4=2) \quad \dots \quad P(X_4=4) \right]$$

DTMCs: First passage times

Let $\{X_n, n \geq 0\}$ be a DTMC on $S = \{0, 1, 2, \dots\}$

$$T = \min \{n \geq 0 \mid X_n = 0\}$$

First passage time into "0".

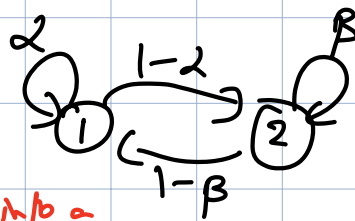
Quantities related to T :

① Complementary cdf $P(T > n), n \geq 0$

② Probability of eventually hitting "0" $P(T < \infty)$

EXAMPLE:

Two-state DTMC



to obtain the first passage into a certain state

$$T = \min \{ n \geq 0 \mid X_n = 1 \}$$

$$P = \begin{bmatrix} 2 & 1-2 \\ 1-\beta & \beta \end{bmatrix}$$

$$V_2(n) = P(T > n \mid X_0 = 2) = \beta^n$$

$$\begin{aligned} P(T = n \mid X_0 = 2) &= V_2(n-1) - V_2(n) \\ &= \beta^{n-1}(1-\beta) \end{aligned}$$

Geometric distribution

Occupancy times

$\{X_n, n \geq 0\}$ DTMC with state space S ,
t.p.m. P

$$V_j^{(n)} = \# \text{ visits to "j" up to time } n \text{ (including 0)}$$

Note: $V_j^{(0)} = 1$ if $X_0 = j$

Define $M_{i,j}^{(n)} = E \left(V_j^{(n)} \mid X_0 = i \right), i, j \in S, n \geq 0$

Occupancy time of "j" up to "n", starting in "i"

Occupancy matrix $\rightarrow M^{(n)} = [M_{i,j}^{(n)}]_{i,j \in S}, |S| < \infty$

Fact :

$$M^{(n)} = \sum_{r=0}^n P^r, \quad n \geq 0$$

$$P^0 = I$$

$$P^1 = P$$

EXAMPLE:

3-state DTMC, $S = \{A, B, C\}$

t.p.m. $P =$

	A	B	C
A	0.1	0.2	0.7
B	0.2	0.4	0.4
C	0.1	0.3	0.6

$$M^{(9)} = \sum_{r=0}^9 P^r = \begin{bmatrix} 2.14 & 2.74 & 5.12 \\ 1.26 & 3.95 & 4.78 \\ 1.15 & 2.85 & 6 \end{bmatrix}$$

$$M_{(A,A)}^{(9)} = 2.14 = \text{if customer buys A on day 0 (initial distribution),}$$

then the expected # of purchases of A = 2.14 over 10 days

$$M_{(A,C)}^{(9)} = 5.12$$

Remark: Marginal distributions & passage times \rightarrow may characterize the transient behaviour of Markov chains.

Markov chains - Limiting behaviour

(I) Recall $P^{(n)} \rightarrow n$ -step t.p.m.
 $P^{(n)}_{i,j} \rightarrow$ prob of going from i to j in ' n ' steps

$$P^{(n)} = P^n$$

Q: Does $P^{(n)}$ converge as $n \rightarrow \infty$?

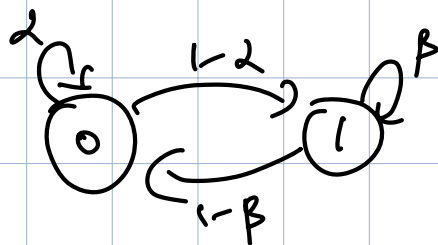
(II) Occupancy matrix $M^{(n)} = \sum_{r=0}^n P^r$
 $M^{(n)}_{i,j} \rightarrow$ # visits to j starting in i up to time n
 $M^{(n)} \rightarrow$ row sums are ' $n+1$ '

Q: Does $\frac{M^{(n)}}{n+1}$ converge as $n \rightarrow \infty$?

EXAMPLE

① Two-state DTMC:

$$\alpha + \beta < 2$$



By an induction argument, it can be shown that

$$P^n = \frac{1}{2-\alpha-\beta} \begin{bmatrix} 1-\beta & 1-\alpha \\ 1-\beta & 1-\alpha \end{bmatrix} + \frac{(\alpha+\beta-1)^n}{2-\alpha-\beta} \begin{bmatrix} 1-\alpha & \alpha-1 \\ \beta-1 & 1-\beta \end{bmatrix}, \forall n$$

M.W.

Check case $n=1$

$$P^1 = P = \begin{bmatrix} \alpha & 1-\alpha \\ 1-\beta & \beta \end{bmatrix}$$

induction hypothesis for $k=1 \dots n$ & prove for $n+1$ using $P^{n+1} = P^n P$

$$\lim_{n \rightarrow \infty} P^n = \frac{1}{2-\alpha-\beta} \begin{bmatrix} 1-\beta & 1-\alpha \\ 1-\beta & 1-\alpha \end{bmatrix}$$

Another induction argument gives

$$M^{(n)} = \frac{n+1}{2-\alpha-\beta} \begin{bmatrix} 1-\beta & 1-\alpha \\ 1-\beta & 1-\alpha \end{bmatrix} + \frac{1-(\alpha+\beta-1)^{n+1}}{(2-\alpha-\beta)^2} \begin{bmatrix} 1-\alpha & \alpha-1 \\ \beta-1 & 1-\beta \end{bmatrix}$$

$$\lim_{n \rightarrow \infty} \frac{M^{(n)}}{n+1} = \frac{1}{2-\alpha-\beta} \begin{bmatrix} 1-\beta & 1-\alpha \\ 1-\beta & 1-\alpha \end{bmatrix}$$

P^n & $\frac{M^{(n)}}{n+1}$ converged to the same limit.

Classification of states

"Accessibility"

A state j is said to be accessible from a state i if $\exists n \geq 0$ s.t. $P_{i,j}^{(n)} > 0$.

If j is accessible from i , we write $i \rightarrow j$

$i \rightarrow j \Rightarrow \exists$ a directed path from i to j in the transition diagram

Communication: States i and j communicate if

$$i \rightarrow j \text{ and } j \rightarrow i$$

Denote communication by " \leftrightarrow "

Claim:

(i) $i \leftrightarrow i$ (reflexive)

(ii) If $i \leftrightarrow j$ then $j \leftrightarrow i$ (symmetric)

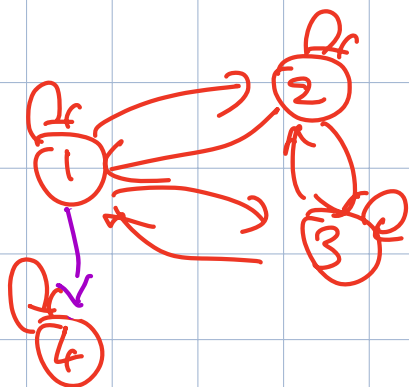
(iii) If $i \leftrightarrow j$, $j \leftrightarrow k$, then $i \leftrightarrow k$ (transitive)

Communicating class:

A set $C \subset S$ is a communicating class if

(i) $i \in C, j \in C \Rightarrow i \leftrightarrow j$

(ii) $i \in C, i \leftrightarrow j \Rightarrow j \in C$ \leftarrow makes C maximal



$$1 \leftrightarrow 2 \quad 2 \leftrightarrow 3$$

$\{1, 2\}$ is not a communicating class

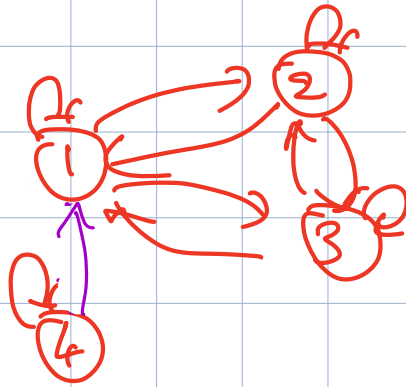
but $\{1, 2, 3\}$ is.

$$S = \{1, 2, 3\} \cup \{4\}$$

closed communicating class

A communicating class C is closed if for any $i \in C$ & $j \notin C$, we have $i \not\rightarrow j$

j is not accessible from i



$\{1, 2, 3\}$ is a closed communicating class

If $X_n \in C$ for some n , & C is closed, then $X_m \in C \quad \forall m \geq n$.

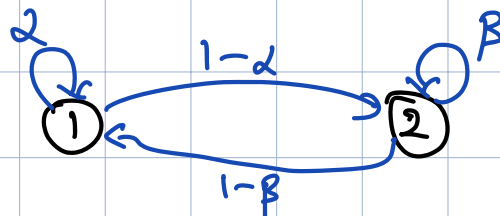
We can partition the state space as

$$S = \underbrace{C_1 \cup C_2 \cup \dots \cup C_k}_{\substack{\text{disjoint closed} \\ \text{communicating} \\ \text{classes}}} \cup \underbrace{T}_{\substack{\text{left-over states} \\ \text{could include} \\ \text{communicating} \\ \text{classes that} \\ \text{aren't closed}}}$$

Irreducibility: If the state space S is a single closed communicating class, then the DTMC is said to be irreducible.

Else it is reducible.

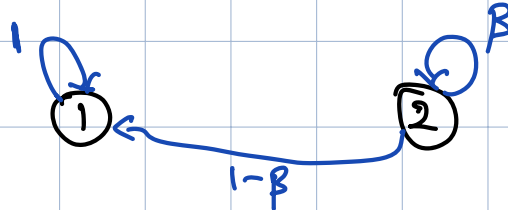
Example:



If $0 \leq \alpha, \beta < 1$, then $\{1, 2\}$ is a

closed communicating class & the DTMC is irreducible,

Suppose $\alpha = 1$ & $0 < \beta < 1$



$\{1\}$ is a closed communicating class

$\{2\}$ is not closed

Partition of state space = $\underbrace{\{1\}}_{C_1} \cup \underbrace{\{2\}}_T$

Case $\alpha = \beta = 1$: Partition: $\underbrace{\{1\}}_{C_1} \cup \underbrace{\{2\}}_{C_2}$ $T = \emptyset$

Recurrence & transience:



$$T_i = \min \{n > 0 \mid X_n = i\}, i \in S$$

$$\tilde{u}_i = P(\tilde{T}_i < \infty \mid X_0 = i) \rightarrow \text{Prob of returning to state } i$$

$$\tilde{m}_i = E(\tilde{T}_i \mid X_0 = i) \rightarrow \text{expected \# steps taken before returning}$$

Def: A state i is $\begin{cases} \text{recurrent if } \tilde{u}_i = 1 \\ \text{transient if } \tilde{u}_i < 1 \end{cases}$

Q: If $\tilde{u}_i < 1$, then $\tilde{m}_i = \infty$.
state is transient mean # steps for return



Recurrent i : $P_i(\tilde{T}_i < \infty) = 1$

Transient i : $P_i(\tilde{T}_i < \infty) < 1$

Def:

A recurrent state i is

positive recurrent
if $\tilde{m}_i < \infty$

null-recurrent
if $\tilde{m}_i = \infty$

\uparrow
expected return time

Example: If i is an absorbing state, then

$$P(X_1 = i | X_0 = i) = 1$$

$$\tilde{u}_i = 1, \quad \tilde{m}_i = 1$$

Thus, i is positive recurrent.

Recurrence & transience are (communicating) class properties

Facts:

① i is recurrent, $i \leftrightarrow j \Rightarrow j$ is recurrent

② i transient, $i \leftrightarrow j \Rightarrow j$ is transient.

Next, positive/null recurrence are class properties

More
Facts

① $i \leftrightarrow j$, i is positive recurrent
 $\Rightarrow j$ is positive recurrent

② $i \leftrightarrow j$, i is null recurrent
 $\Rightarrow j$ is null recurrent

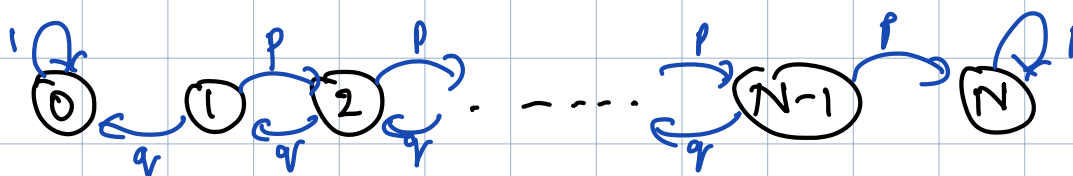
(I) A communicating class is called

- (i) "transient" if all its states are transient
- (ii) "positive recurrent" if all its states are positive recurrent
- (iii) "null recurrent" if all its states are null recurrent

(II) An irreducible DTMC is positive (null recurrent, transient) if all its states are positive (null recurrent, transient).

Example: Random walk

$$P_{0,0} = P_{N,N} = 1, \quad P_{i,i+1} = p, \quad P_{i,i-1} = q, \quad 1 \leq i \leq N-1$$



$$0 < p, q < 1, \quad p + q = 1$$

State 0 : recurrent

N : ———

$\{1, \dots, N-1\}$: transient

Markov chains taken to their limit

Fact:

Finite irreducible Markov chain

\Rightarrow recurrent & also positive recurrent

Stationary distributions

(aka steady-state / invariant distributions)

Def: For a ^{discrete-time} Markov chain with t.p.m. P , the vector $\pi = (\pi_i, i \in S)$ is called a **stationary distribution** if

(i) $\pi_i \geq 0 \forall i, \sum_i \pi_i = 1$ $\leftarrow \pi$ is a distribution

(ii) $\pi = \pi P$ $\leftarrow \pi$ is stationary

Remark: If the initial distribution is π , then what is the distribution of X_n :

$$\begin{aligned} & \pi P^n \\ &= \pi P \cdot P^{n-1} \\ &= \pi P^{n-1} \\ &\vdots \end{aligned}$$

$$\text{dist}^n \text{ of } X_n = \pi$$

Main result. Consider an irreducible Markov chain

(a) \exists a stationary distribution π if and only if some state is positive recurrent.

(i.e., if DTMC is irreducible + transient/null-recurrent, then NO stationary distribution)

(b) If there exists a stationary distribution π , then (i) every state is positive recurrent

(ii) $\pi_i = \frac{1}{m_i} \quad \forall i \in S$, where

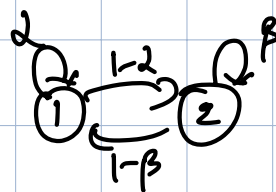
m can return time $m_i = E(T_i | X_0 = i)$, with $T_i = \min \{n \geq 1 \mid X_n = i\}$

(i.e., $\frac{1}{m_i} = \sum_j \frac{1}{m_j} P_{j,i}$, since $\pi_i = \sum_{j \in S} \pi_j P_{j,i} \Rightarrow \pi = \pi P$)

(iii) π is unique.

Example:

Two state DTMC:



$$\alpha + \beta < 2$$

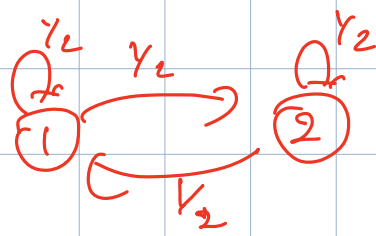
$$\pi = \pi P \quad (\Rightarrow)$$

$$\begin{cases} \pi_1 = \alpha \pi_1 + (1-\beta) \pi_2 \\ \pi_2 = (1-\alpha) \pi_1 + \beta \pi_2 \end{cases} \quad (\Rightarrow) \pi = \pi P$$

$$\pi_1 + \pi_2 = 1$$

If you solve, then

$$\pi_1 = \frac{1-\beta}{2-\alpha-\beta}, \quad \pi_2 = \frac{1-\alpha}{2-\alpha-\beta}$$



$$\frac{1}{n} \sum_{m=1}^n \mathbb{I}\{X_m = 1\} \xrightarrow{n \rightarrow \infty} \frac{1}{2}$$

like a
LLN

↓
is the
stationary distⁿ
value for state 1



$\pi_i \rightarrow$ Space avg.

HTS \rightarrow time-average

In the limit, time-avg = space-avg
"ergodic".

Last Big Fact:

"Convergence in Cesaro Sense".

$$\tilde{V}_n(j) = \sum_{m=1}^n \mathbb{I}(X_m = j) \quad \leftarrow \text{occupancy measure for state } j$$

$$\text{Time average} = \frac{1}{n} \tilde{V}_n(j)$$

As $n \rightarrow \infty$, where does the "time average" converge for a irreducible, positive recurrent DTMC?

$$\frac{1}{n} \tilde{V}_n(j) \rightarrow \pi_j \text{ as } n \rightarrow \infty \text{ a.s. (w.p.1)}$$

$$\text{or equivalently, } \frac{1}{n} \tilde{V}_n(j) \rightarrow \frac{1}{m_j} \text{ as } n \rightarrow \infty \text{ w.p.1.}$$

For a null recurrent state j ,

$$\frac{1}{n} \tilde{V}_n(j) \rightarrow 0 \text{ a.s. as } n \rightarrow \infty.$$

(the same for transient states)

Big Fact II: Consider a irreducible, recurrent DTMC.

Then, for any $j \in S$,

a law of large numbers result for Markov chains

$$\frac{\tilde{V}_n(j)}{n} \rightarrow \frac{\mathbb{I}\{T_j < \infty\}}{m_j} \text{ as } n \rightarrow \infty \text{ w.p.1}$$

(almost surely = a.s.)

\Updownarrow

for any state j $X_{n \geq j}$

A few remarks:

$$\textcircled{1} \quad E\left(\frac{\tilde{V}_n(j)}{n} \mid X_0 = i\right) = \frac{1}{n} \sum_{m=1}^n E(I(X_m = j) \mid X_0 = i) \\ = \frac{1}{n} \sum_{m=1}^n p^{(m)}(i, j)$$

$$E\left(\frac{I\{T_j < \infty\}}{m_j} \mid X_0 = i\right) = \frac{P(T_j < \infty \mid X_0 = i)}{m_j}$$

So,

$$\frac{1}{n} \sum_{m=1}^n p^{(m)}(i, j) \xrightarrow{n \rightarrow \infty} \frac{P(T_j < \infty \mid X_0 = i)}{m_j} \quad \text{--- (**)}$$

In (**), if j is null recurrent, then the limit is zero.

In (**), if j is positive recurrent, then the limit is positive.

$\textcircled{2}$ For a transient state j , $\sum_{m=1}^{\infty} p^{(m)}(i, j) < \infty$.

$$\frac{1}{n} \sum_{m=1}^{\infty} p^{(m)}(i, j) \xrightarrow{n \rightarrow \infty} 0$$

i.e., $E\left(\frac{\tilde{V}_n(j)}{n} \mid X_0 = i\right) \xrightarrow{n \rightarrow \infty} 0$
for transient j .