Roll. No:

Name:

Total Marks: 14, Total Time: 35mins

Instructions

- 1. The quiz is divided into two sections: short answer questions, and problems that require a detailed solution. For the first section, provide the final answer ONLY. For the second section, provide detailed answers showing all the necessary steps.
- 2. Use rough sheets for any calculations *if necessary*, and do not submit the rough sheets. Do not use a pencil for writing the answers.
- 3. Assume standard data whenever you feel that the given data is insufficient. However, do quote your assumptions explicitly.

I Short answer questions (Answer any four)

Note:

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If more than four questions are answered, then the first four answers will be considered for evaluation.
2 marks for the correct answer.

1. The convex hull of a set C, denoted Conv(C) is defined as

$$Conv(C) = \alpha_1 x_1 + \ldots + \alpha_k x_k \mid |x_i \in C, \alpha_i \ge 0, \forall i, \alpha_1 + \ldots + \alpha_k = 1.$$

For each of the following sets in \mathbb{R}^2 , provide a visual depiction of their convex hulls by sketching:

(a) $C = \{(0,1), (0,4), (-2,-1), (0,0), (3,-2), (-1,2)\}.$

- (b) Union of two unit circles, centered at (1, 1) and (-1, -1), respectively.
- 2 2. Let $\{X_n\}$ be a martingale sequence.

Consider the following two statements:

I: For all $n \ge 1$, $\mathbb{E}[X_n] = E[X_1]$. II: For all $n \ge 1$, Variance $(X_n) =$ Variance (X_1) . III: For all $n \ge 1$, Variance $(X_n) \ge$ Variance (X_1) . IV: For all $n \ge 1$, Variance $(X_n) \le$ Variance (X_1) . Which of the statements is/are true?

- 2 3. Exhibit a real-valued function f that is L-smooth but not L-Lipschitz.
- 2 4. Let $y^+ = f(x + \delta\Delta) + \xi^+$, $y^- = f(x \delta\Delta) + \xi^-$ and y = f(x), where $\Delta = (\Delta_1, \dots, \Delta_d)^{\mathsf{T}}$ is a *d*-vector of independent Rademacher random variables. Consider the following gradient estimators: For $i = 1, \dots, d$, the *i* co-ordinate of the gradient estimators $g_1^2 g_2^2, g_3^i$ are defined by

$$g_1^i = \left[\frac{y^+ - y^-}{2\delta\Delta_i}\right], \ g_2^i = \left[\frac{y^+ - y}{\delta\Delta_i}\right], \ g_3^i = \left[\frac{y^+}{\delta\Delta_i}\right].$$
(1)

Mini-quiz 1

Assume f is three times continuously differentiable and ξ^{\pm}, ξ are zero mean. Order these estimators using "bias" as the metric.

5. Show via an example that the second-order sufficient condition for optimality, i.e., the Hessian $\nabla^2 f(x^*) \succ 0$, is not necessary. In other words, exhibit a function with a minimum, where the aforementioned condition is not satisfied.

II. Problems that require a detailed solution (Answer any one)

Note: If more than one question is answered, then the first answer will be considered for evaluation.

- 1. Suppose that $f : \mathbb{R}^d \to \mathbb{R}$ is a convex function with a *L*-Lipschitz gradient and a minimizer x^* with function value $f^* = f(x^*)$.
- (a) Show that for any $x \in \mathbb{R}^d$, we have

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$$f(x) - f^* \ge \frac{1}{2L} \|\nabla f(x)\|^2.$$

(b) Prove the following property: For any $x, y \in \mathbb{R}^d$, we have

$$\left(\nabla f(x) - \nabla f(y)\right)^{\mathsf{T}} (x - y) \ge \frac{1}{L} \left\|\nabla f(x) - \nabla f(y)\right\|^{2}.$$

4 2. (a) Consider the function $f : \mathbb{R}^2 \to \mathbb{R}$ defined by

$$f(x_1, x_2) = \frac{x_1^2}{2} + x_1 x_2 + 2x_2^2 - 4x_1 - 4x_2 - x_2^3.$$

Find points where the first-order necessary condition for optima is satisfied. For each of these points, characterize whether they are minimizers or maximizers or neither.

(b) Consider the function $f : \mathbb{R}^2 \to \mathbb{R}$ defined by

$$f(x) = x^{\mathsf{T}} \begin{bmatrix} 2 & 5\\ -1 & 1 \end{bmatrix} x + \begin{bmatrix} 3\\ 4 \end{bmatrix}^{\mathsf{T}} x + 7.$$

Does this function have a minimizer? Justify your answer.