

Variants of Zeroth-order gradient estimator with improved bounds

Previously, we assumed
 $f \in \mathcal{C}^3$ (3-times cont diffble)
& showed

$$\mathbb{E} \|\hat{\nabla} f(x) - \nabla f(x)\| \leq C_1 d^2$$

Let's fix the unified estimate

Recall

$$\begin{aligned} \nabla f(x) &= \left[\frac{f(x+\delta u) - f(x-\delta u)}{2\delta} \right] v \\ &+ \left[\frac{\xi^+ - \xi^-}{2\delta} \right] v \end{aligned}$$

Assume
 $\mathbb{E}[\xi^+ - \xi^- | v] = 0$
 $\mathbb{E}[v v^T] = I$

Variant 1: f is convex + L -smooth

$$\frac{\delta \nabla f(x)^T u}{2\delta} \stackrel{\text{convex}}{\leq} \frac{f(x+\delta u) - f(x)}{2\delta} \stackrel{L\text{-smooth}}{\leq} \frac{\delta \nabla f(x)^T u + \frac{L}{2} \delta^2 \|u\|^2}{2\delta}$$

A similar inequality holds for $f(x-\delta u)$

$$\frac{\nabla f(x)^T u - \frac{L}{2} \delta \|u\|^2}{2} \leq \frac{f(x+\delta u) - f(x-\delta u)}{2\delta} \leq \frac{\nabla f(x)^T u + \frac{L}{2} \delta \|u\|^2}{2}$$

$$\text{Let } \phi(x, \delta, u) = \frac{1}{\delta} \left[\frac{f(x+\delta u) - f(x-\delta u)}{2\delta} - \nabla f(x)^T u \right]$$

$$\text{Then, } |\phi(x, \delta, u)| \leq \frac{L \|u\|^2}{2}$$

$$\mathbb{E} \hat{\nabla} f(x) = \mathbb{E} \left[v \left(\frac{f(x+\delta u) - f(x-\delta u)}{2\delta} \right) \right]$$

$$= \mathbb{E} \left[v v^T \nabla f(x) + \delta \phi(x, \delta, u) v \right]$$

Using $\mathbb{E}(v v^T) = I$,

$$\mathbb{E} \|\hat{\nabla} f(x) - \nabla f(x)\| \leq \delta \mathbb{E} \|\phi(\cdot) v\|$$

$$\leq \frac{\delta L}{2} \mathbb{E} \|v\|^2$$

Assume $\mathbb{E} \|v\|^2 \leq C_4$

Then,

$$\mathbb{E} \|\hat{\nabla} f(x) - \nabla f(x)\| \leq \text{const} \times \delta$$

For the chain,

$$\mathbb{E} \|\hat{\nabla} f(x) - \mathbb{E}(\hat{\nabla} f(x) | x)\|^2 \leq \frac{\text{const}}{\delta^2},$$

the proof is as in the case $f \in \mathbb{C}^3$.

Gaussian Smoothing

"Neykov-Spokoyny, 2017"

Goes back to "Kalkorik-Kulchitsky, 1972",

See also Kushner-Clark, 1978

Aka "Gaussian smoothed functional".

$$\hat{\nabla} f(x) = \Delta \left(\frac{f(x + \delta \Delta) + \xi^+}{\delta} - (f(x) + \xi) \right)$$

$\Delta \rightarrow$ vector of $N(0, 1)$

$$\Delta \sim N(0, I_d)$$

$$\mathbb{E}(\xi^+) = \mathbb{E}(\xi) = 0$$

Then,

$$\|E \hat{\nabla} f(x) - \nabla f(x)\| \leq C_1 \delta$$

Pf^o

"Smoothed functional"

$$f_{\delta}(x) = \frac{1}{(2\pi)^{d/2}} \int_{-\infty}^{\infty} f(x + \delta u) \exp\left(-\frac{\|u\|^2}{2}\right) du$$

Next lecture

Lecture - 19

Gaussian smoothing: $x \in \mathbb{R}^d$

$$f_\delta(x) = \frac{1}{(2\pi)^{d/2}} \int f(x + \delta u) e^{-\frac{1}{2}\|u\|^2} du$$

why?

$$= \frac{1}{(2\pi)^{d/2} \delta^d} \int f(y) e^{-\frac{1}{2\delta^2}\|y-x\|^2} dy$$

$y = x + \delta u$ Jacobian matrix = $\begin{bmatrix} \delta & & 0 \\ & \ddots & \\ 0 & & \delta \end{bmatrix}$

$|Jacobian| = \delta^d$

$\frac{dy}{\delta^d} = du$

$$\nabla f_\delta(x) = \frac{1}{(2\pi)^{d/2} \delta^{d+2}} \int f(y) e^{-\frac{1}{2\delta^2}\|y-x\|^2} (y-x) dy$$

$$= \frac{1}{(2\pi)^{d/2} \delta} \int f(x + \delta u) e^{-\frac{1}{2}\|u\|^2} u du$$

$$\nabla f_\delta(x) = \frac{1}{(2\pi)^{d/2}} \int \frac{f(x + \delta u) - f(x)}{\delta} e^{-\frac{1}{2}\|u\|^2} u du$$

used

$$\int u e^{-\frac{1}{2}\|u\|^2} du = 0$$

Also, $\nabla f_\delta(x) = \frac{1}{(2\pi)^{d/2}} \int \frac{f(x+du) - f(x-du)}{2\delta} e^{-\frac{1}{2}\|u\|^2} du$

Now,

$$\|\nabla f_\delta(x) - \nabla f(x)\|$$

$$\leq \frac{1}{(2\pi)^{d/2}} \delta \int |f(x+du) - f(x) - \delta \langle \nabla f(x), u \rangle| \|u\| e^{-\frac{1}{2}\|u\|^2} du$$

used

$$\frac{1}{(2\pi)^{d/2}} \int \langle \nabla f(x), u \rangle e^{-\frac{1}{2}\|u\|^2} u du = \nabla f(x)$$

Since $\frac{1}{(2\pi)^{d/2}} \int u u^T e^{-\frac{1}{2}\|u\|^2} du = I$

$$\leq \frac{1}{(2\pi)^{d/2}} \times \frac{\delta L}{2} \int \|u\|^3 e^{-\frac{1}{2}\|u\|^2} du$$

why

$$|f(y) - f(x) - \langle \nabla f(x), y-x \rangle| \leq \frac{1}{2} L \|x-y\|^2$$

$$\leq \frac{\delta L}{2} (d+3)^{3/2}$$

↑

$$\text{using } \frac{1}{(2\pi)^{d/2}} \int \|u\|^3 e^{-\frac{1}{2}\|u\|^2} du = (d+3)^{3/2}$$

$$\nabla f_\delta(x) = \frac{1}{(2\pi)^{d/2}} \delta^{d+2} \int f(y) e^{-\frac{1}{2\delta^2}\|y-x\|^2} (y-x) dy$$

$$= \frac{1}{(2\pi)^{d/2}} \delta \int f(x+\delta u) e^{-\frac{1}{2}\|u\|^2} u du$$

$$\nabla f_\delta(x) = \frac{1}{\delta c} \int f(x+\delta u) e^{-\frac{1}{2}\|u\|^2} u du$$

$$u = -v, \quad du = -dv$$

$$\nabla f_\delta(x) = \frac{1}{\delta c} \int f(x-\delta v) e^{-\frac{1}{2}\|v\|^2} v dv$$

$$\nabla f_{\delta}(x) = \frac{1}{(2\pi)^{d/2}} \int \frac{f(x+\delta u) - \boxed{f(x)}}{\delta} e^{-\frac{1}{2}\|u\|^2} u \, du$$

Now? $\rightarrow$

$$\frac{1}{(2\pi)^{d/2}} \int \frac{f(x) - f(x-\delta u)}{\delta} e^{-\frac{1}{2}\|u\|^2} u \, du$$

$x + \delta u = v$, $x = v - \delta u$

$$\nabla f_{\delta}(x) = \frac{1}{(2\pi)^{d/2}} \int \frac{f(v) - f(v-\delta u)}{\delta} e^{-\frac{1}{2}\|u\|^2} u \, du$$

A Calculation:

$$\frac{1}{(2\pi)^{d/2}} \int_{-\infty}^{\infty} \nabla f(x)^T u \exp\left(-\frac{\|u\|^2}{2}\right) u \, du$$

$$= \sum_{i=1}^d \nabla_i f(x) \frac{1}{(2\pi)^{d/2}} \int_{-\infty}^{\infty} u_i \exp\left(-\frac{\|u\|^2}{2}\right) u \, du$$

$$= \sum_{i=1}^d \nabla_i f(x) \frac{1}{(2\pi)^{d/2}}$$

$$\times \int_{-\infty}^{\infty} (u_1 u_i, u_2 u_i, \dots, u_{i-1} u_i, u_{i+1} u_i, \dots, u_d u_i) \\ \times \exp\left(-\frac{\|u\|^2}{2}\right) du$$

$$= \sum_{i=1}^d \nabla_i f(x) \frac{1}{(2\pi)^{d/2}} \int u_i^2 \exp\left(-\frac{\|u\|^2}{2}\right) du$$

(used $\int_{i \neq j} u_i u_j \exp\left(-\frac{\|u\|^2}{2}\right) du = 0$)

$$= \sum_{i=1}^d \nabla_i f(x) \frac{1}{(2\pi)^{d/2}} \left(\prod_{j \neq i} \int \exp\left(-\frac{u_j^2}{2}\right) du_j \right) \\ \times \int u_i^2 \exp\left(-\frac{u_i^2}{2}\right) du_i$$

$$= \nabla f(x)$$

Main point?

$$\nabla f_{\delta}(x) = \frac{1}{(2\pi)^{d/2}} \int \frac{f(x+\delta u) - \cancel{f(x)}}{\delta} e^{-\frac{1}{2}\|u\|^2} u \, du$$

$$= \mathbb{E} \left(\left(\frac{f(x+\delta u) - f(x)}{\delta} \right) u \right)$$

An estimate of $\nabla f_{\delta}(x)$ is $u_1 \sim \mathcal{N}(0, I_d)$

$$\hat{g} = \frac{(f(x+\delta u_1) - f(x))}{\delta} u_1$$

$$\mathbb{E} \hat{g} = \nabla f_{\delta}(x)$$

$$\|\nabla f_{\delta} - \nabla f\| \leq (\text{const}) \times \delta$$

Lecture-13

Improved variance bound:

Setting:

$$\underset{\substack{\uparrow \\ \text{objective}}}{f(x)} = \underset{\substack{\uparrow \\ \text{noise}}}{E_{\xi}} \left[\underset{\substack{\uparrow \\ \text{sample performance}}}{F(x, \xi)} \right]$$

Assume: F is L -smooth, i.e.,

For any ξ ,

$$\begin{aligned} & \| \nabla F(x_1, \xi) - \nabla F(x_2, \xi) \| \\ & \leq L \| x_1 - x_2 \| \quad \text{a.s.} \end{aligned}$$

Suppose we can fix " ξ " (noise) across two function evaluations:

$$\hat{\nabla} f(x) = \frac{F(x + \delta U, \xi) - F(x - \delta U, \xi)}{2\delta}$$

ξ same across evals.

similar to unified estimate

Claim: If F is L -smooth then f is L -smooth.

The converse is not true.

Try $\lambda \|\nabla E F(x, \xi) - \nabla E F(x, \xi)\| \rightarrow$ proceed

Bias/Variance guarantees:

See Sec 3.3.4 of the book

Assume f is convex & F is L -smooth.

Then, $\| \mathbb{E} \hat{\nabla} f(x) - \nabla f(x) \| \leq C_1 \delta$ and

$$\mathbb{E} \| \hat{\nabla} f(x) - \mathbb{E} \hat{\nabla} f(x) \|^2 \leq C_2 + C_3 \delta^2$$

Proof. As in the proof of Proposition 3.2, for any convex function h with an L -Lipschitz gradient, for any $\delta > 0$, we have

$$\frac{\langle \nabla h(\theta), \delta u \rangle}{2\delta} \leq \frac{h(\theta + \delta u) - h(\theta)}{2\delta} \leq \frac{\langle \nabla h(\theta), \delta u \rangle + (L/2) \|\delta u\|^2}{2\delta}.$$

Using similar inequalities for $h(\theta - \delta u)$, we obtain

$$\langle \nabla h(\theta), u \rangle - \frac{L\delta \|u\|^2}{2} \leq \frac{h(\theta + \delta u) - h(\theta - \delta u)}{2\delta} \leq \langle \nabla h(\theta), u \rangle + \frac{L\delta \|u\|^2}{2}.$$

Letting $\phi(\theta, \delta, u) := \frac{1}{\delta} \left(\frac{h(\theta + \delta u) - h(\theta - \delta u)}{2\delta} - \langle \nabla h(\theta), u \rangle \right)$, we get

$$|\phi(\theta, \delta, u)| \leq \frac{L}{2} \|u\|^2.$$

Using $\mathbb{E} [VU^\top] = I$, we obtain

$$\mathbb{E} \left[V \left(\frac{h(\theta + \delta U) - h(\theta - \delta U)}{2\delta} \right) \right] = \mathbb{E} [VU^\top \nabla h(\theta) + \delta \phi(\theta, \delta, U)V]$$

$$= \nabla h(\theta) + \delta \hat{\phi}(\theta, \delta),$$

where $\hat{\phi}(\theta, \delta)$ satisfies $\|\hat{\phi}(\theta, \delta)\| \leq \frac{L}{2} \mathbb{E}[\|V\| \|U\|^2]$.

Applying the above expression to $F(\cdot, \psi)$ and using (3.23), we have

$$\mathbb{E} [\hat{\nabla} f(\theta)] = \nabla F(\theta, \psi) + \delta \hat{\phi}(\theta, \delta) \text{ a.s.,}$$

where $\hat{\phi}(\theta, \delta)$ satisfies $\|\hat{\phi}(\theta, \delta)\| \leq \frac{L}{2} \mathbb{E}[\|V\| \|U\|^2]$.

A3.4 together with dominated convergence theorem leads to $E[\nabla F(\theta, \psi)] = \nabla f(\theta)$. Using this fact, we obtain

$$\begin{aligned} & \left\| \mathbb{E} [\hat{\nabla} f(\theta)] - \nabla f(\theta) \right\| \\ &= \left\| \mathbb{E} \left[V \left(\frac{f(\theta + \delta U) - f(\theta - \delta U)}{2\delta} \right) - V U^\top \nabla f(\theta) \right] \right\| \\ &\leq \delta \|\mathbb{E}[V \phi(\theta, \delta, U)]\| \\ &\leq \frac{\delta L}{2} \mathbb{E}[\|V\| \|U\|^2], \end{aligned}$$

and the claim for the bias follows by setting $C_1 = \frac{L}{2} \mathbb{E}[\|V\| \|U\|^2]$.

We now bound $\mathbb{E} [\|\hat{\nabla} f(\theta)\|^2]$ as follows:

$$\begin{aligned} \mathbb{E} \|\hat{\nabla} f(\theta)\|^2 &\stackrel{\text{Wu?}}{=} \mathbb{E} \left\| V \left(\delta \phi(\theta, \delta, U) + U^\top \nabla f(\theta) \right) \right\|^2 \\ &\leq \mathbb{E} \left[\left(\|V U^\top \nabla f(\theta)\| + \frac{\delta L}{2} \|V\| \|U\|^2 \right)^2 \right] \\ &\leq 2\mathbb{E} [\|V U^\top \nabla f(\theta)\|^2] + \frac{\delta^2 L^2}{2} \mathbb{E} [\|V\|^2 \|U\|^4], \end{aligned}$$

and the claim for the variance follows by setting

$$C_2 = 2B_1^2 + \frac{L^2}{2} \mathbb{E} [\|V\|^2 \|U\|^4] \text{ with } B_1 = \sup_{\theta} \|\nabla f(\theta)\|.$$

□

$$\begin{aligned}
\mathbb{E} \left\| \hat{\nabla} f(\theta) \right\|^2 &\stackrel{\text{Wug:}}{=} \mathbb{E} \left\| V \left(\delta \phi(\theta, \delta, U) + U^\top \nabla f(\theta) \right) \right\|^2 \quad \text{--- (XX)} \\
&\leq \mathbb{E} \left[\left(\|V U^\top \nabla f(\theta)\| + \frac{\delta L}{2} \|V\| \|U\|^2 \right)^2 \right] \\
&\leq 2\mathbb{E} \left[\|V U^\top \nabla f(\theta)\|^2 \right] + \frac{\delta^2 L^2}{2} \mathbb{E} \left[\|V\|^2 \|U\|^4 \right],
\end{aligned}$$

$$\mathbb{E} \left[\hat{\nabla} f(\theta) \right] = \nabla F(\theta, \psi) + \delta \hat{\phi}(\theta, \delta)$$

$$\mathbb{E} \left[V \left(\frac{h(\theta + \delta U) - h(\theta - \delta U)}{2\delta} \right) \right] = \mathbb{E} \left[V U^\top \nabla h(\theta) + \delta \phi(\theta, \delta, U) V \right] \quad \text{--- (Xf)}$$

A similar claim with improved variance holds without assuming convexity.