

Multi-criteria Energy Minimization with Boundedness, Edge-density and Rarity, for Object Saliency in Natural Images

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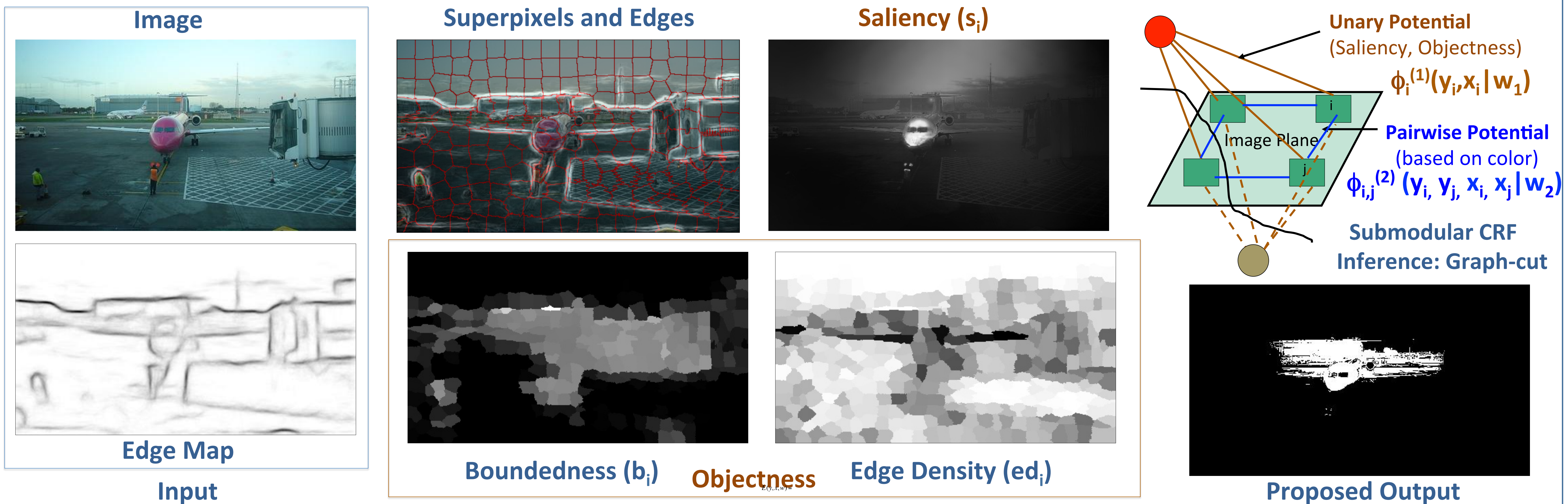
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Abstract

- Motivated by saliency and category independent object segmentation methods, we predict a single object proposal which captures all the salient objects in an image, within $O(\text{number of superpixels})^3$.
- The CRF parameters are learned using a margin-rescaled struct-SVM approach with (1- IoU) loss function.
- Fast but effective objectness criteria, viz. boundedness and edge-density. Submodular CRF is minimized using graph-cut. Results are shown on the challenging PASCAL VOC 2012 dataset.

Algorithm Overview



Energy Function over superpixels:

$$E(y, x, w) = \sum_{i \in V} \phi_i^{(1)} + \lambda \sum_{(i,j) \in E} \phi_{i,j}^{(2)}$$

Salient Object Likelihood:

$$\phi_i^{(1)}(y_i, x_i^{(1)} | w_1) = w_s ((1 - y_i) (1 - s_i) + y_i s_i) + w_b ((1 - y_i) (1 - b_i) + y_i b_i) + w_{ed} ((1 - y_i) ed_i + y_i (1 - ed_i))$$

Edge Cost:

$$\phi_{i,j}^{(2)}(y_i, y_j, x_i^{(2)}, x_j^{(2)}) = |y_i - y_j| \exp(-k_c |c_i - c_j|)$$

c_i denotes color of i th superpixel in lab space and k_c indicates the sensitivity of color similarity.

CRF parameter Learning:

- Convex in w , given \mathcal{L}
- Iteratively optimized, by finding y_n using graph-cut, and thus \mathcal{L}
- M is the number of training instances.
- $w = [w_1 \ w_2] = [w_s \ w_b \ w_{ed} \ \lambda]^T$

$$\min_w \frac{1}{2} \|w\|^2 + \frac{1}{M} \sum_{n=1}^M \xi_n$$

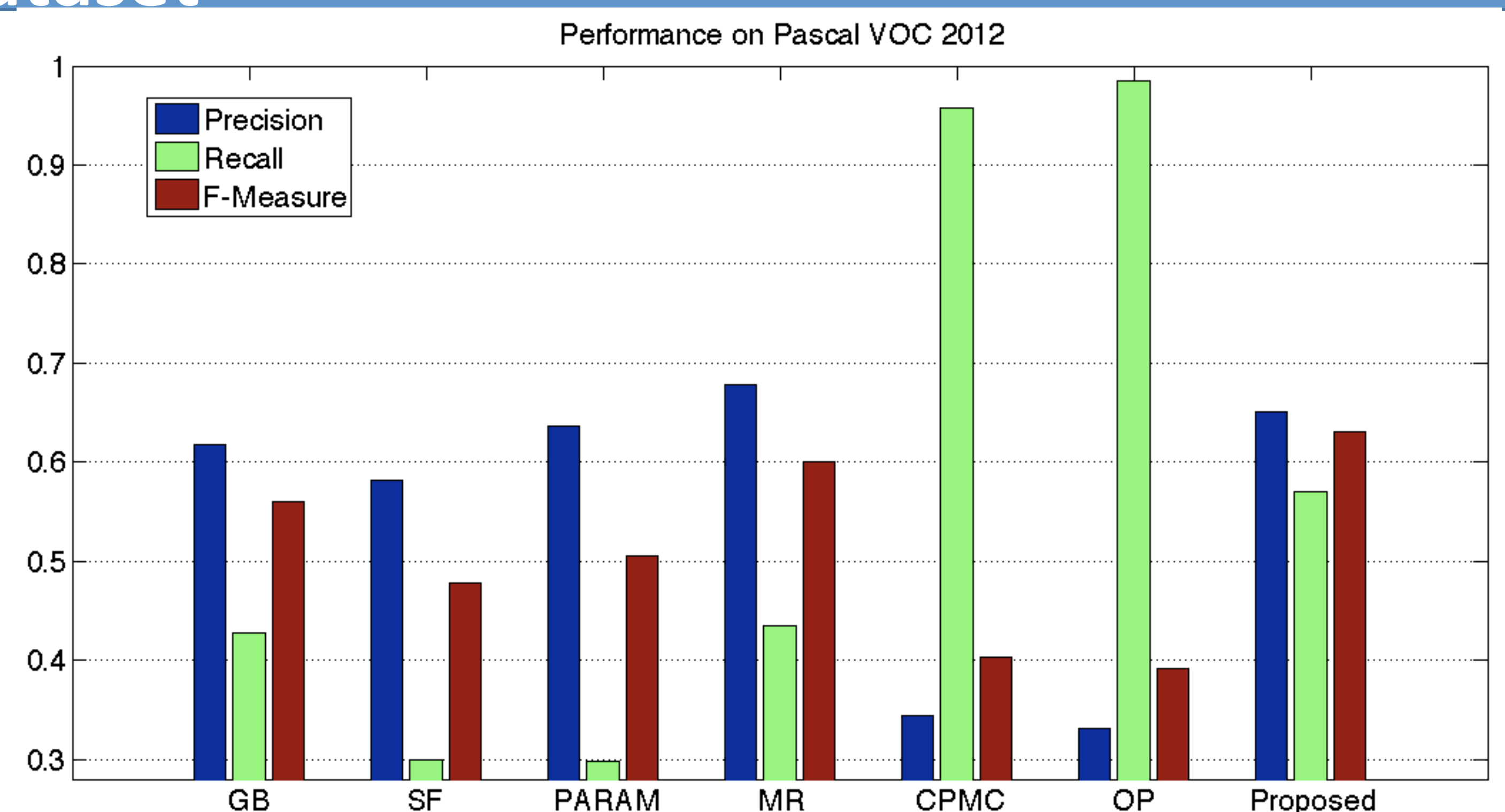
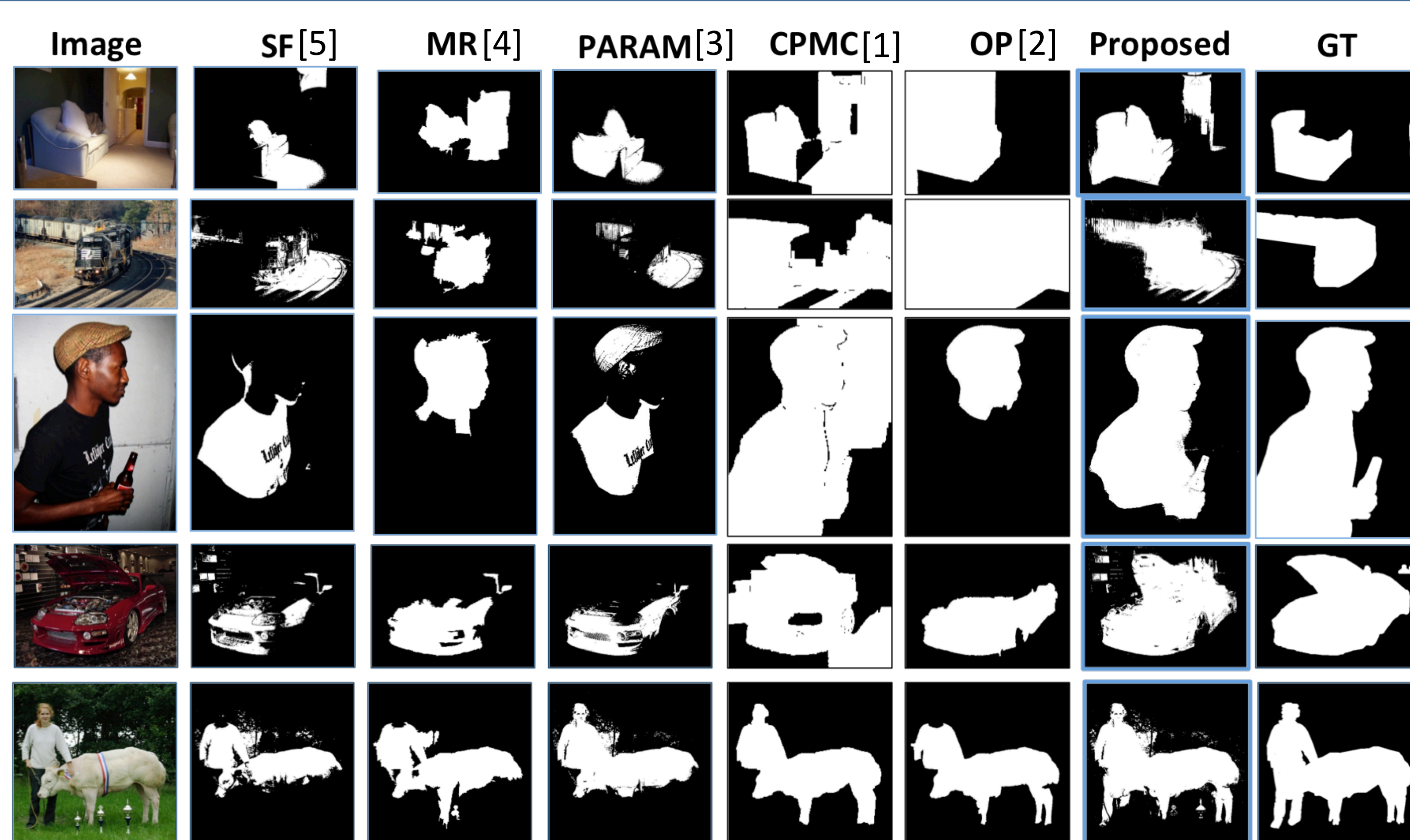
$$\text{subject to, } w^T v = 1$$

$$w^T \phi_n - w^T \hat{\phi}_n \leq \mathcal{L}(y_n, \hat{y}_n) + \xi_n$$

$$\xi_n \geq 0, w_2 > 0$$

$$\mathcal{L} = (1 - \text{IoU})$$

Results and Evaluations on PASCAL VOC 2012 Dataset



| Method | CPMC [1] * | OP [2] * | Proposed |
|-----------|------------|----------|---------------|
| IoU Score | 0.3319 | 0.3266 | 0.4097 |

* Considering top 10 proposal masks

Conclusion

- An efficient method based on saliency in conjunction with objectness cues to predict a category-independent object segmentation, using a CRF based formulation.
- Can be a preprocessing step for many high-level vision task.

References

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