

Saliency Detection in Images using Graph-based Rarity, Spatial

Compactness and Background Prior

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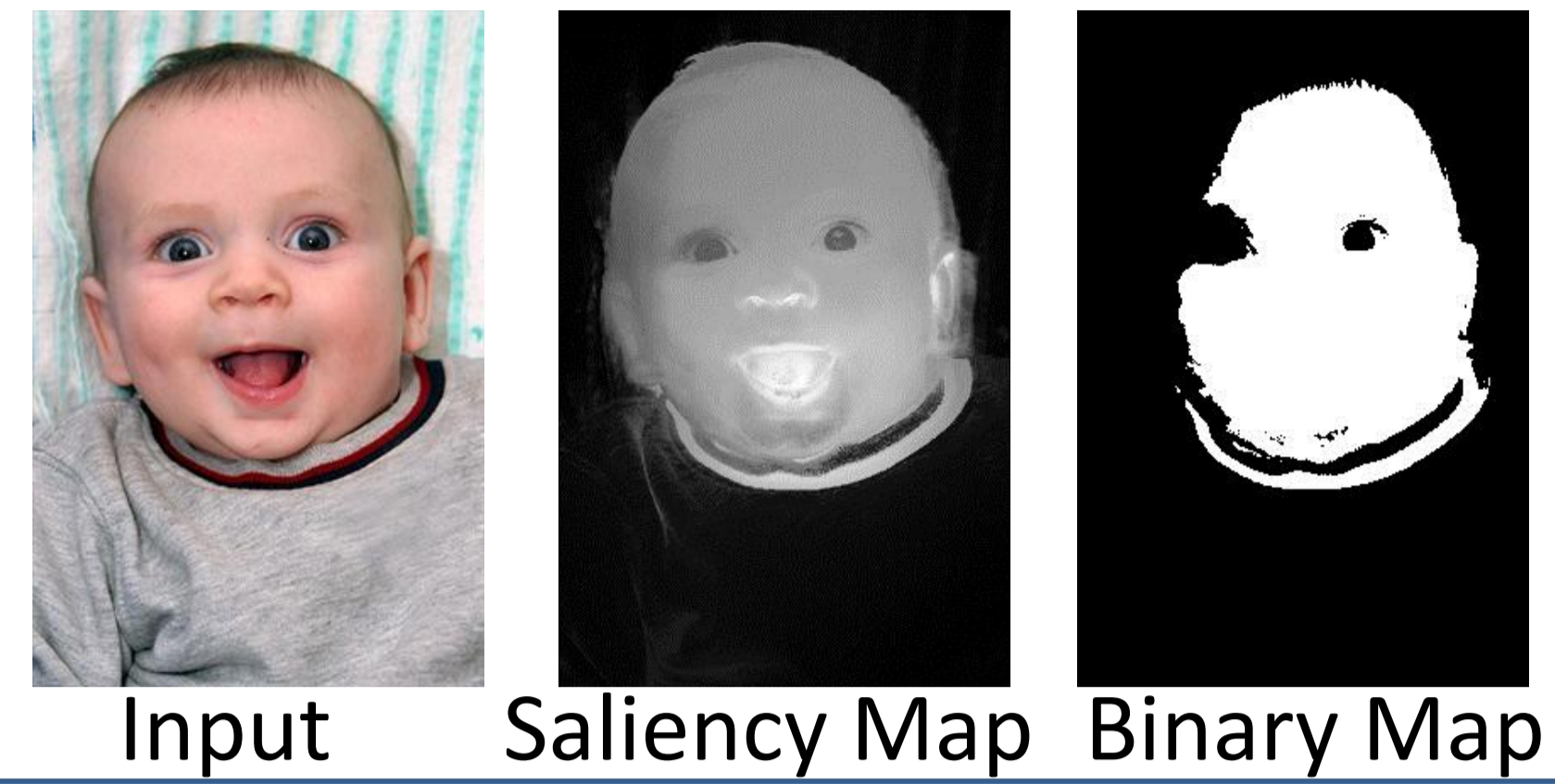
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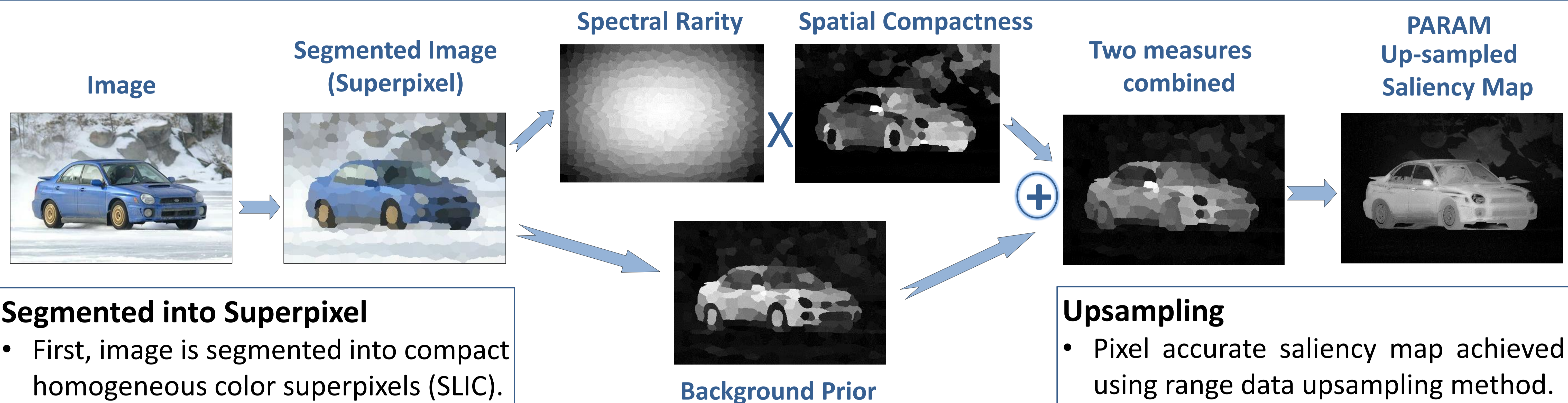


Abstract

- The proposed saliency detection method identifies regions in an image, containing prominent objects, which pop out from the background and helps to focus attention.
- We use rarity of feature based approach based on graph-based spectral rarity and spatial compactness of color, as well as boundary prior constraint using Gaussian mixture model.
- Combination of these two complimentary concepts gives better result in terms of both accuracy and speed.



PARAM (background Prior And RARity for saliency Modeling) Algorithm Overview



Segmented into Superpixel

- First, image is segmented into compact homogeneous color superpixels (SLIC).

Graph-based Spectral Rarity

- Eigen vectors of the Laplacian matrix of the superpixel graph form the descriptor (x_i) for each superpixel.
- Rarity of superpixel i is calculated as,

$$r_i = \sum_{j=1}^N ||x_j - x_i||^2 \cdot \exp(-k_r ||p_j - p_i||^2)$$

i.e., sum of Euclidean distances of the descriptors of spatially near superpixels.

Spatial Compactness

- A salient color c_i is spatially compact and close to the spatial mean position (μ_i) of the colors similar to c_i .
- Spatial variance of superpixel i is,

$$v_i = \sum_{j=1}^N ||p_j - \mu_i||^2 \cdot \exp(-k_c ||c_j - c_i||^2)$$

- Thus, spatial compactness of color is formulated as, $\exp(-k \cdot v_i)$.

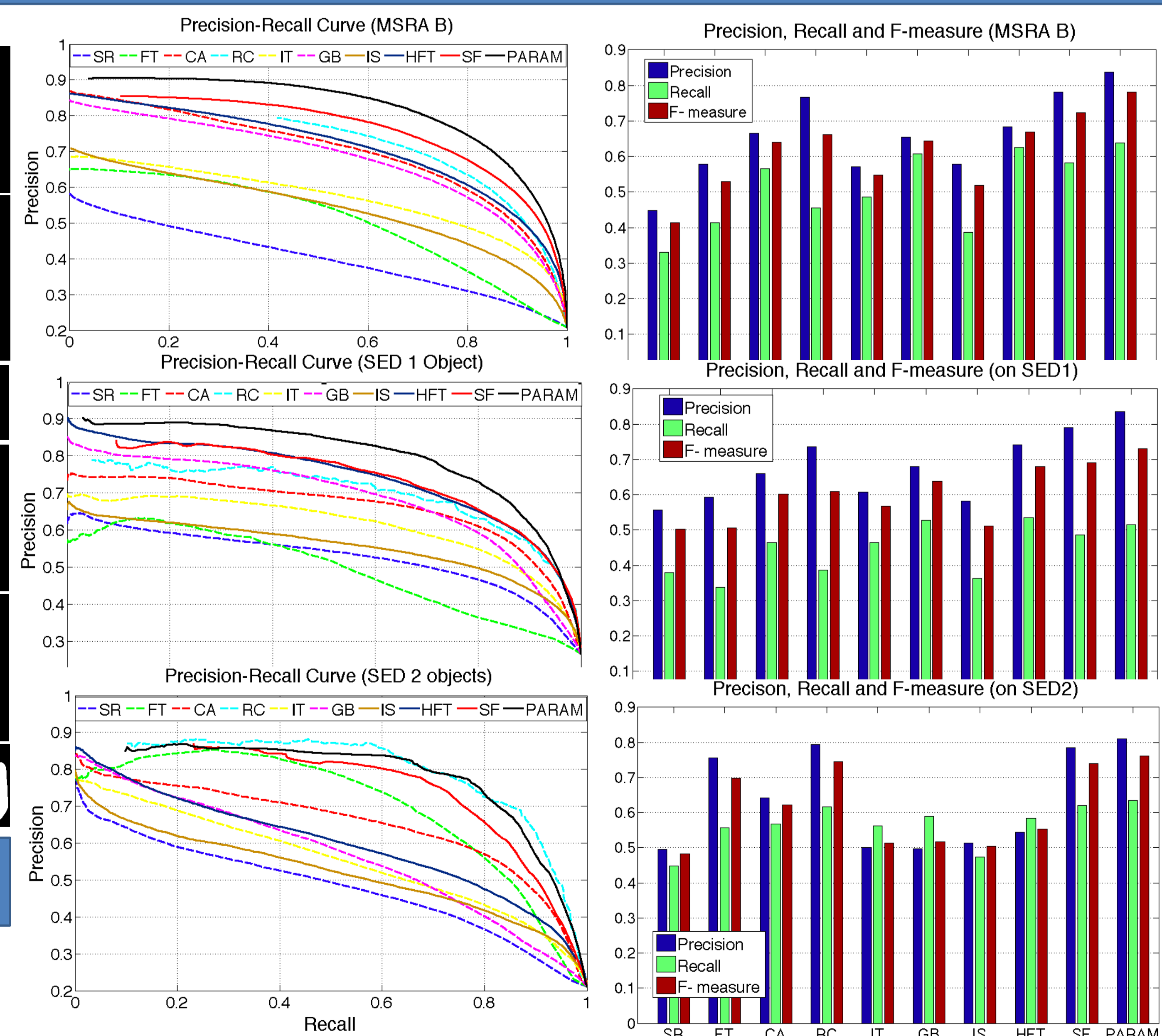
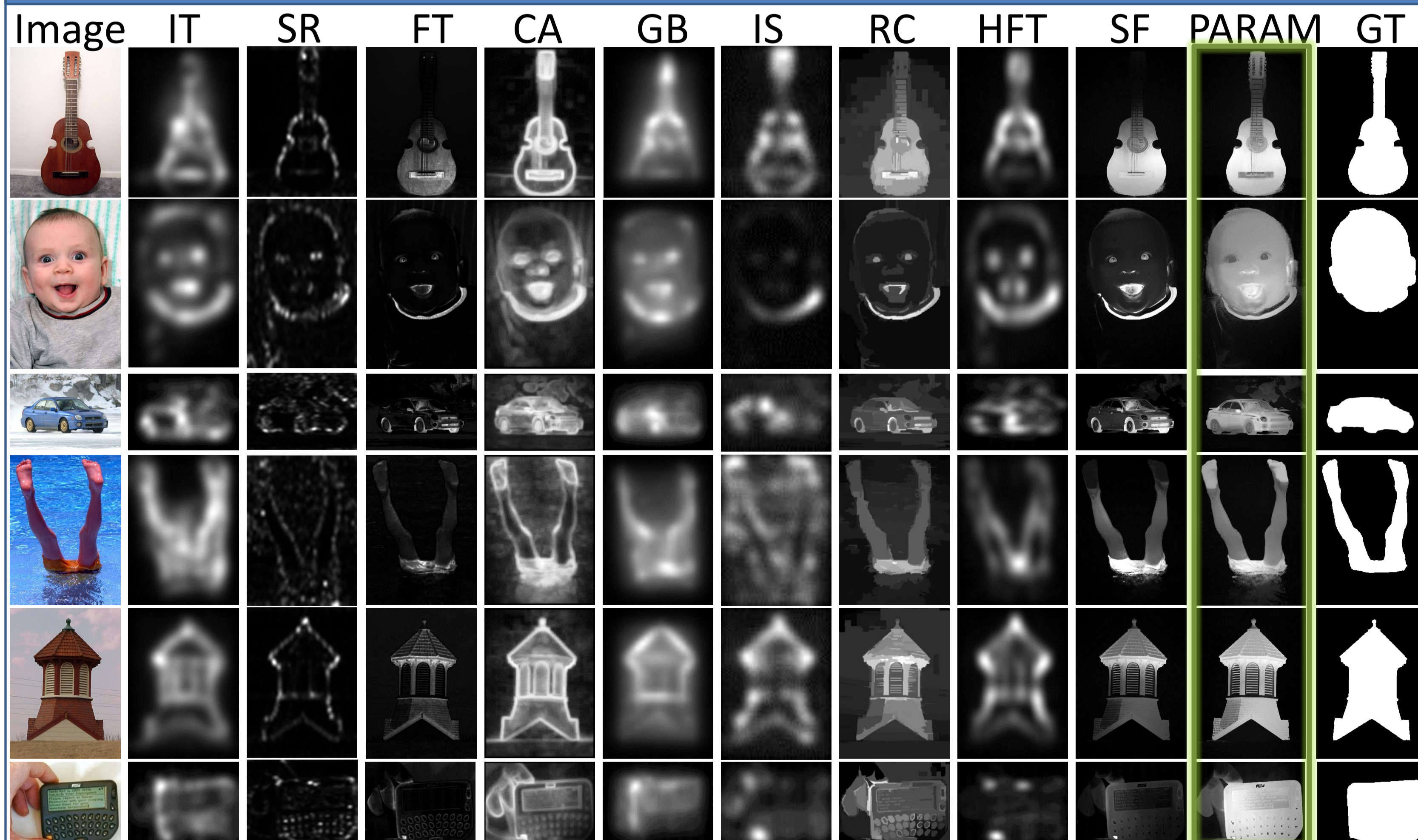
Background Prior

- Boundary superpixels are modeled by GMM (K modes) in Lab color space.
- Saliency given by background prior,

$$B_i = \sum_{j=1}^K \pi_j \cdot D_M(c_i, \mu_{Gj})$$

- Non-salient superpixels are similar to the large modes depicting background, with low Mahalanobis distance (D_M).

Results and Evaluations



Conclusion

- Autonomously finds salient regions, thus the prominent objects.
- Fast - can be used as preprocessing step to reduce search space.

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